



# MASTERING MACHINE CODE ON YOUR **ZX 81**

TONI BAKER



# Mastering Machine Code on Your ZX81

Toni Baker

with illustrations by Cathy Lowe



Reston Publishing Company, Inc.  
A Prentice-Hall Company  
Reston, Virginia

# Contents

<b>CHAPTER 1</b>	<b>AN INTRODUCTION 9</b>
	A brief summary of the book.
<b>CHAPTER 2</b>	<b>INTRODUCTION TO HEXADECIMAL AND MACHINE CODE 11</b>
	Computers count in sixteens, not tens. This system is called hexadecimal, and is quite useful to get to know.
<b>CHAPTER 3</b>	<b>SIMPLE ARITHMETIC 17</b>
	"Simple" means <i>very</i> simple! Plusses and minuses only. Shares and timeses are left till later!
<b>CHAPTER 4</b>	<b>PEEKING AND POKING AND MORE ABOUT LOADING 29</b>
	An explanation of how to use memory in RAM. A "SCROLL Backwards" program is included to demonstrate this.
<b>CHAPTER 5</b>	<b>MORE PLACES TO STORE MACHINE CODE 39</b>
	A very explicit guide to the use of REM statements, variables area, and protected regions of RAM.
<b>CHAPTER 6</b>	<b>STACKING AND JUMPING 47</b>
	How to use the stack to store data. Jumping and conditional jumping, and the use of subroutines explained.
<b>CHAPTER 7</b>	<b>PRINTING THINGS TO THE SCREEN 55</b>
	In BASIC the PRINT statement is perhaps the most widely used instruction of all. Here's how to use it in machine code.

- CHAPTER 8 A DICTIONARY OF MACHINE CODE 63**  
All the instructions. A complete explanation of every single machine language instruction used by the ZX.
- CHAPTER 9 A PROGRAM TO HELP YOU DEBUG 75**  
A machine code editing program, itself written largely in machine code. The speed it offers is likely to make your fluency in machine code develop very strongly.
- CHAPTER 10 SCANNING THE KEYBOARD 87**  
Using the keyboard in programs has obvious advantages. Here we cover the function INKEYs for the NEW ROM and explain how to recreate it on the OLD. An elegant little program called GRAFFITI is developed which shows how the character set is generated.
- CHAPTER 11 DRAUGHTS PART ONE 99**  
The first part of this program, which allows a player to input a move, and checks for cheats!
- CHAPTER 12 A TOUCH OF CULTURE 109**  
Music and pictures. Music from the keyboard, and pictures from the screen. Watch out for the program LIFE.
- CHAPTER 13 DRAUGHTS PART TWO 119**  
The output of the computer's move. This section does not decide upon a move to make; it merely outputs a move assuming the decision has been made already.
- CHAPTER 14 GRAPHICS GAMES 125**  
A section intended only for the ZX81 because the games included here rely on the SLOW mechanism. (And in machine code the word "SLOW" should absolutely *not* be taken literally.)
- CHAPTER 15 DRAUGHTS PART THREE 133**  
The making of the big decision. . . Which move to choose.
- CHAPTER 16 HOW TO DISASSEMBLE THE ROM 143**  
The ROM holds many secrets, but it, and any other machine code program, may be disassembled fairly simply. A hex-listing program is given, and an outline as to how a full disassembler-program may be written is also given.

- CHAPTER 17 THE ARITHMETIC SUBROUTINES 155**  
Have you ever wondered how floating point numbers work in machine code? How you can add and subtract them? Multiply and divide them? Even take sines and cosines!? This chapter will tell you how.

**APPENDICES 165**  
Useful information you might need when writing programs.

## Foreword

I was staggered when Toni first brought the manuscript for this book to us at the National ZX80 and ZX81 Users' Club. We'd talked about it, and Toni had given me a broad idea of the contents of the book, but until I had the chance to read it, I did not realize just what a comprehensive and easy-to-understand work it would be.

The book has been written for those who know BASIC, but haven't much idea about machine code, and want to get down and master this most useful addition to one's programming skills. We've waited for over a year for a book like this, and now it is here.

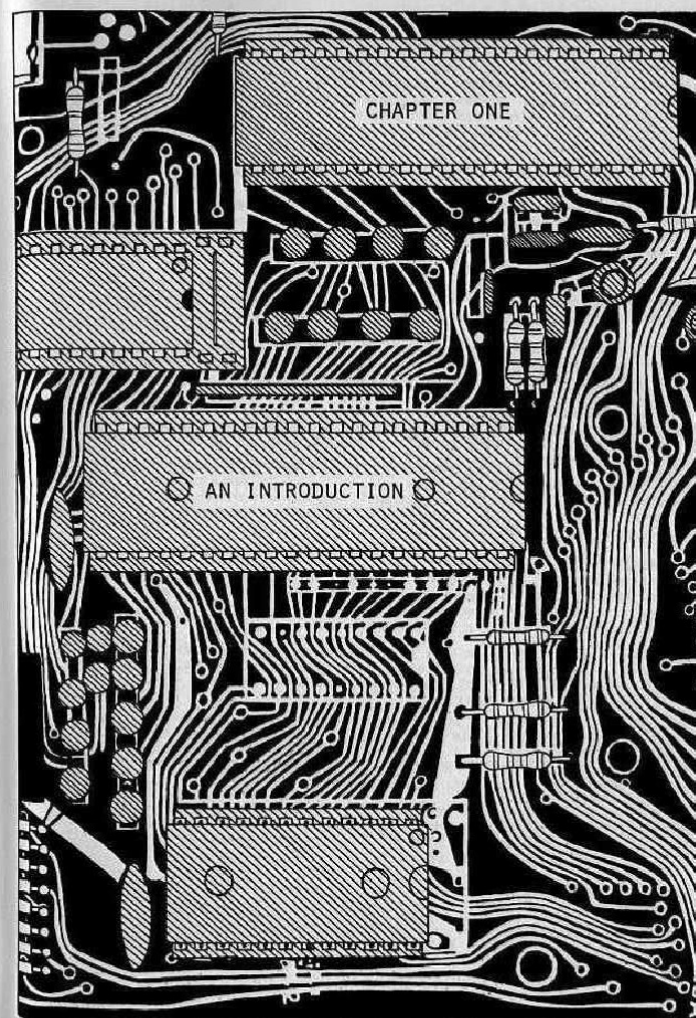
If you've decided that GUESS MY NUMBER and SIMON are OK for a while, but now it's time to start exploring the full potential of your computer, and time to begin developing all your potential programming skills, then this book may well prove just what you've been waiting for.

When Toni first came to us with the idea for the book, I stressed that it must be designed to lead someone who knew absolutely nothing about machine code through from the true basics to the point where they would have a real knowledge of how to use it. I'm pleased to say that she has done just that, and if you work through the book with your ZX81 or ZX80 turned on, entering the programs and routines as instructed, you'll certainly end up *Mastering Machine Code on Your ZX81 or ZX80*.

Tim Hartnell  
National ZX80 and  
ZX81 Users' Club,  
London,  
August 1981

## Mastering Machine Code on Your ZX81

CHAPTER ONE  
AN INTRODUCTION



## AN INTRODUCTION

This book is designed for those people who have a reasonable understanding of BASIC, but whose knowledge of machine code is zero. Starting at first principles with BASIC programs, we gradually introduce the concept of a machine code subroutine, and develop this theory throughout the book. Before long you'll find your understanding of machine language increasing, and you'll soon begin writing your own routines and programs.

Machine language is no more than a second computer language - very much like BASIC is in fact. We start by learning the simplest of instructions, and become familiar with them by using them in BASIC programs. An example would be a SCROLL program given in chapter four, which moves the screen downward instead of upward. This effect is rather interesting, and certainly surprising.

Printing strings is the next thing covered, and this involves making use of the PRINT subroutine in the ROM. The routine is demonstrated by printing a draughts board which later on in the book we shall make use of.

We explain the machine code equivalent of the INKEY\$ function, and use the technique of scanning the keyboard to write a typewriter-type program which uses greatly enlarged versions of the keyboard characters.

The same keyboard scanning technique is used to generate musical notes in rather surprising manner. Two whole octaves can be produced from your machine, enabling you to play a wide variety of tunes at the touch of the keyboard.

The computer is made to generate many intricate and fascinating displays in the program LIFE. It challenges the skill of an unwary human operator in graphics games such as SPIRALS. A draughts program is included, with several interesting features. This is actually a teaching game because you are encouraged to add your own features to it as you progress.

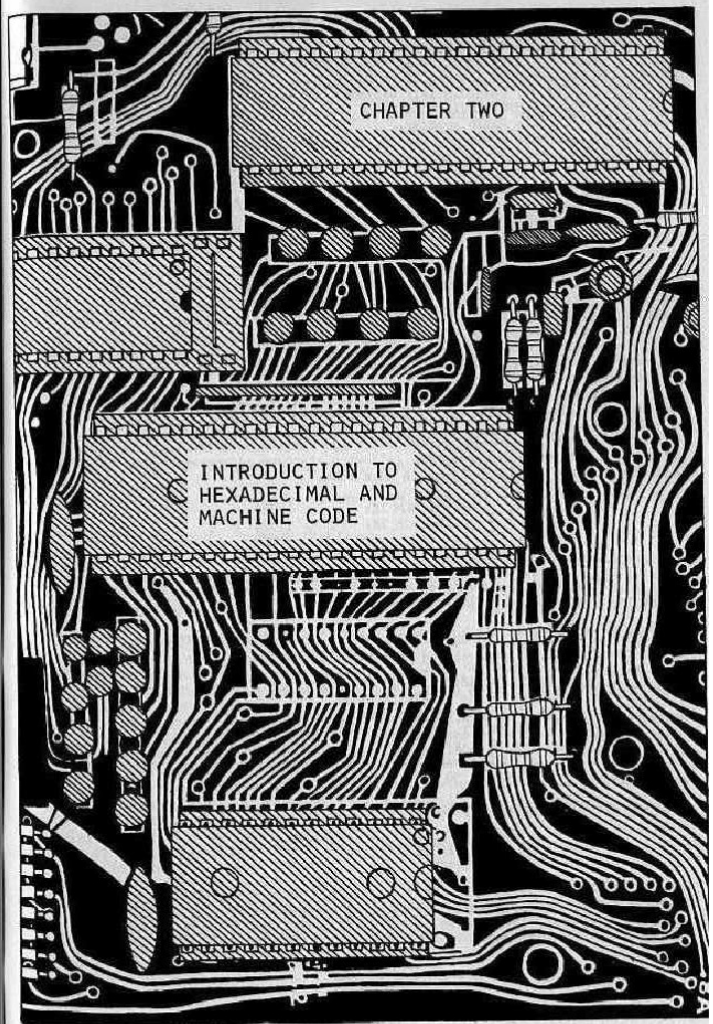
Careful study of the listings of these programs will teach you a great deal about machine code, but of course the biggest steps in learning will come from experiment. By writing your own programs, or by adapting mine - by all means do - they are intended for this purpose, and some in fact are deliberately improvable for this reason.

To make the best use of this book you are advised to work through from start to finish, and where asked to alter or improve programs you should make an attempt to do so. It's not difficult, since the book progresses very slowly, but will require some thought.

The last two chapters in the book are rather ambitious. An algorithm by which the ROM may be disassembled is given, but only guidelines are given as to how you may write a program for it. All of the arithmetic subroutines are explained in detail, even NEW ROM floating point functions like SIN and COS, and how the numbers are stored.

The heavily tabulated appendices at the back are designed to be used as a source of reference throughout the book. Any piece of information you need to know can generally be found in these appendices, or in chapter eight, which is a kind of "catalogue" of machine code.

The first chapter begins on the next page, and starts with an introduction to the use of "hexadecimal"....



OK, so your ZX80/81 is all fired up and ready, and that ominous inverse-K is sitting there glaring at you from its little corner and waiting for you to type something in. What do you do?

Well the first thing is to set up the machine so that it can accept programs in machine code instead of in BASIC. This is not difficult, but unfortunately for us, when Sinclair designed his machine he forgot to include a button saying GO-INFO-MACHINE-CODE-MORE, so the routine for doing this is going to have to be a BASIC program.

If you have a NEW ROM machine type one of the following sequences, depending on how much memory you have:

1K	4K	16K
POKE 16386,173	POKE 16386,32	POKE 16386,48
POKE 16389,67	POKE 16389,78	POKE 16389,117
NEW	NEW	NEW

The effect of this is quite straightforward. The addresses 16386 and 16389 together hold a system variable called RAMTOP. It contains the address of the first byte which the computer cannot use - at least not for BASIC. Under ordinary circumstances this address is the one immediately after the last byte in memory, so that the whole of the memory is available for BASIC programming. What we have done is to alter that address, so that some of the memory is unavailable for BASIC, and becomes a safe place in which to store machine code.

If you have an OLD ROM machine, don't worry - you can still store machine code in spare areas of the memory, but you MUST NOT type NEW, or you will lose it all.

The best addresses in which to store machine code are best found by trial and error. We shall adopt the following standard addresses, which should work perfectly for all of the routines in this book:

OLD ROM 1K:	17225
NEW ROM 1K:	17325
4K:	20000
16K:	30000

Throughout the remainder of this book I shall use the address 30000. Please read this as one of the alternatives above if you have less than 16K.

OK! - Now we're ready to start. Type in the following BASIC program:

```

When you have      10 LET X=30000
typed this program 20 LET A$=""
in name it         30 IF A$="" THEN INPUT A$
"HEXLD" and don't  40 IF A$="S" THEN STOP
forget to SAVE     50 POKE X,16*CODE(A$)+CODE(A$(2))-476
it.               60 LET X=X+1
                  70 LET A$=A$(3 TO )
                  80 GO TO 30

```

(For the OLD ROM you must replace lines 50 and 70 as follows:)

```

50 POKE X,16*CODE(A$)+CODE(TLS(A$))+36
70 LET A$=TLS(TLS(A$))

```

Can you see how the program works? Or at least what it does? In brief - it will accept a machine code program, & will store it at addresses 30000 onwards. (Or 20000, or whatever.) The program will stop when you input an "S". Note that although it will enter machine code, it will NOT attempt to run it.

Now for the big question you've all been dying to ask - what exactly IS machine code? Well machine code, or machine language as it's otherwise known, is another computer language - much like BASIC is - only at a much lower level, which means that very complicated instructions, such as FOR/NEXT loops, are simply not available. However this also makes it quite an easy language to learn. Like BASIC it consists of a set of instructions, each of which tells the computer to do a different, and quite specific, task. One such instruction is RET, which is more or less equivalent to BASIC's RETURN.

Unlike BASIC, however, the computer isn't programmed to understand all of the various instructions as we do. If you were to RUN the above program and enter "RET" then this simply would not make sense to the poor old ZX81 (or '80). To make life easier for it, every instruction has a numerical code, which it DOES understand directly. For example the code for RET is 201. Every code lies somewhere in the range 0-255, and it is usually more convenient to write these codes in a system called HEXADECIMAL.

#### COUNTING IN HEXADECIMAL

Our friend Mr. Sinclair briefly covers this obscure system of counting in the ZX81 instruction manual by describing an imaginary race of sixteen fingered "Martians" who would regard counting in tens as being equally absurd. In these modern days of science we know enough about Mars to realise that it is extremely unlikely to host sixteen fingered people, but the principle of counting in sixteens is still very very sound.

Briefly, for those who have not read the ZX81 manual, hexadecimal, or hex for short, is a means of counting which uses sixteen symbols instead of ten. The first ten symbols are the same as the ones we're used to. These are:

0, 1, 2, 3, 4, 5, 6, 7, 8, 9.

There are six new symbols which represent the numbers 10 to 15. These are:

A, B, C, D, E, F.

The fun really starts when we want to represent numbers bigger than fifteen, for believe it or not, sixteen is written as 10<sub>16</sub> (Worse still, seventeen is written 11<sub>16</sub>. This continues up as far as twenty-five, written 19, and then when we come to twenty-six we have to start using the new symbols again; twenty-six becomes 1A<sub>16</sub>.

A complete table of all of the numbers from 0 to 255 is shown here. This is intended to help you to understand the hexadecimal system of counting. You should try to refer to it as little as possible, but don't worry if you find yourself using it all the time at first, you'll find you get used to it much quicker than you expect.

The symbols down the left hand side are the first hex digit, the symbols along the top are the second digit. The leading zeros may of course be omitted if there are any, but it is sometimes more convenient to leave hex codes as two digits rather than one.

If there is ever any confusion about whether a number is written in hex or not, you should make it clear by writing a small letter h (standing for hex) or a small letter d (for decimal) after the number, so that 19h means twenty-five, and 19d means nineteen. Usually you won't need to do this because numbers like CD can only possibly be hexadecimal, and numbers like 118, which are three digits long, can only be in decimal. (Computing does not use hex numbers which are three digits long, though it does use ones which are FOUR digits long).

Knowing at least the fundamentals of counting in hex is virtually paramount as far as machine code is concerned, so don't be afraid to keep coming back to this section, or to keep referring to the table - that's what it's there for.

	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
2	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47
3	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63
4	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79
5	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95
6	96	97	98	99	100	101	102	103	104	105	106	107	108	109	110	111
7	112	113	114	115	116	117	118	119	120	121	122	123	124	125	126	127
8	128	129	130	131	132	133	134	135	136	137	138	139	140	141	142	143
9	144	145	146	147	148	149	150	151	152	153	154	155	156	157	158	159
A	160	161	162	163	164	165	166	167	168	169	170	171	172	173	174	175
B	176	177	178	179	180	181	182	183	184	185	186	187	188	189	190	191
C	192	193	194	195	196	197	198	199	200	201	202	203	204	205	206	207
D	208	209	210	211	212	213	214	215	216	217	218	219	220	221	222	223
E	224	225	226	227	228	229	230	231	232	233	234	235	236	237	238	239
F	240	241	242	243	244	245	246	247	248	249	250	251	252	253	254	255

There are fundamental differences between machine code programming and BASIC programming. One of the most fundamental differences is that of **LINE NUMBERS**.

As you know, every BASIC instruction in a program must be preceded by a line number, so that the computer knows in which order to execute them. If no line number is given the computer will interpret the instruction as a **COMMAND** and will execute it immediately.

In machine code, there are no line numbers. Also, the ZX80/81 will not allow you to use machine code instructions as commands, they **MUST** form part of a program. The instructions are executed in the order that they are stored. For example, if the computer had just finished executing the instruction which was stored in location 30000, it would then go on to execute the instruction held in location 30001. It will continue in this way until it received an instruction telling it to do otherwise.

Unlike BASIC, it will **NOT** automatically stop when it reaches the end of the program. It will plough right on through the addresses, and every time it finds a number which is not zero it will simply treat that number as a code for some instruction and try to execute it. Usually this will result in what is called a **CRASH**.

#### ABOUT CRASHING

Crashing is the name we give to what happens when your (up until now at least moderately well-behaved) Sinclair machine unwittingly tries to execute something it shouldn't, or if there is a drastic mistake in your machine-coding which will

confuse the poor machine and give it a rather nasty headache. The effect of a crash is very unmistakable - The screen will either go blank or will go into its "LET'S-PRODUCE-SOME-MODERN-ART" mode. If this happens you will get pretty (or otherwise) patterns on your TV not unlike those produced during SAVE.

When this happens you will undoubtedly try to break out, by using the **BREAK** key, and will discover to your horror that the **BREAK** key doesn't work! In fact **NONE** of the keys will work after a crash, except possibly to produce slight variations in the TV picture. This is the prime reason why we dislike crashes, for **THE ONLY WAY TO THEN GET BACK TO NORMAL IS TO DISCONNECT THE POWER SUPPLY!** When you reconnect you will of course have lost all of your program and will have to **reLOAD** it.

If a BASIC program contains a mistake it will usually **NOT WORK**.

If a machine-code program contains a mistake it will usually **CRASH!**

#### HOW TO PREVENT CRASHES

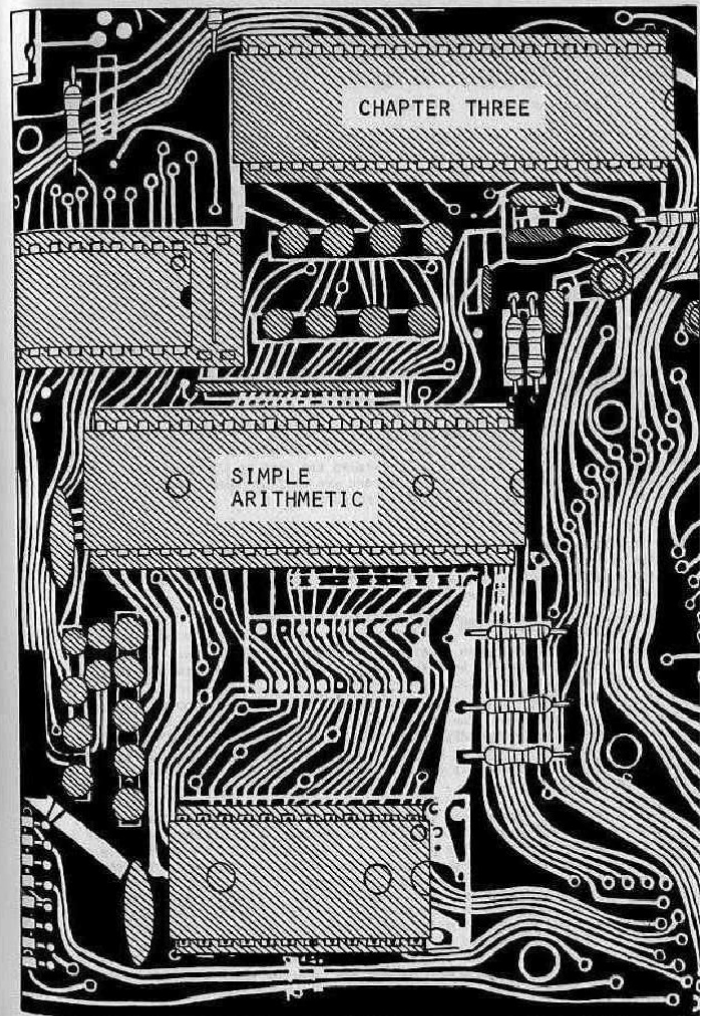
We have already stated that a machine code program will not automatically stop at the end of a program - it must be told to do so by a specific instruction. For The ZX80/81, that instruction is **RET**. (Return - is return to BASIC).

There is an instruction similar to **STOP** in BASIC, that instruction is **HALT**. **DO NOT USE THIS INSTRUCTION!** On other computers you can use **HALT** to end a program, but not on the ZX's. **HALT** produces a condition similar to a crash, for it means "Do nothing whatsoever until somebody breaks out." The problem is of course that you **CAN'T** break out because you'll find that the keyboard no longer works. To summarise: To end a machine code program **ALWAYS** use **RET**. **NEVER** use **HALT**.

A program must have at least one return instruction in it somewhere, otherwise it will never return to BASIC, unless you actually disconnect the power supply, and this is not usually a desirable thing to do.

This chapter has dealt with how to reserve space for machine code programs, and has given you a program with which to load it. It has not told you how to make use of this program, nor has it explained how to run machine code programs once they have been loaded. The fundamentals of counting in hex have been introduced, and the notion of a crash has been mentioned.

Once you have understood this chapter, you may turn to chapter three for your first lesson in machine language programming.



## "HEXLD" REVISITED

You remember the program I asked you to save in chapter two? Well now it's time to break it out, wipe the dust from it, and after you've reserved yourself some machine code space as described at the start of the previous chapter, you can LOAD it.

Now press RUN, and newline.

The program is waiting for a string input. What it in fact wants is some kind of **HEXADECIMAL** input. This means that every time you want to input a machine language instruction you have to know its numerical code, and you have to know it in hex.

The code for RET is, as we have already stated, 201. What is this in hexadecimal? Divide it by sixteen and you get twelve remainder nine. Now the hex symbol for twelve is C, the hex symbol for nine is 9. If you look 201 up in the table in chapter two you'll find that it is written C9. Is this a coincidence?

Input C9. You have now told the computer that the first instruction of your machine language program is RET.

The computer is now waiting for another input. Break out of the program by inputting "S".

Your program is now complete. It consists of the single instruction RET. This is usually written

C9

RET

to remind you that the hex-code for RET is C9. The machine language instructions are sometimes called **OPCODES** to distinguish them from their corresponding **HEX-CODES**. C9 is a hex-code, RET is an Opcode. Hex-codes are used by the machine - it will not understand opcodes. Conversely, opcodes are used by humans, because we would find it extremely difficult to work in hex-codes.

If you now look at the screen you'll see that the computer has gone back to command mode. It is waiting for an instruction. Suppose we now wish to run the machine code program that we've just typed in. We can do this either as part of a BASIC program, or, as we are going to do, as a direct command. If your routine was loaded to address 30000 then the command is

PRINT USR 30000

If your routine began at some other address simply use this figure instead of the 30000 in the above command. Note that OLD ROM users will need brackets around the number following the word USR.

You will have found that the computer has printed 30000 in the top left hand corner of the screen. Can you see why this is so? It started off with the number 30000 - this is the address you gave it when you typed PRINT USR 30000. The program told it to RET, or return to BASIC, having done nothing at all to this number, so that's exactly what it did - it returned to BASIC and it returned the number 30000 with it.

Before we can advance to learning any more instructions, we are going to have to break for a while and explore the concept of **REGISTERS**. A Register is like a variable, in that it has a name - usually a letter of the alphabet - and it can store numbers in much the same way that BASIC variables can. The big difference is that registers can only store numbers in the range 0 to 255. (Or in hex, 00 to FF).

There are seven registers which are most commonly used for machine code routines. Their names are A, B, C, D, E, H, L. To give a larger degree of flexibility it is also possible to use the registers in pairs. When this is done you can alternatively store numbers either in the range -32768 to 32767 or in the range 0 to 65535, using the register-pairs, as they are known, BC, DE, and HL.

To make this clear, if register H contains the value 2, and register L contains the value 23, the register-pair HL is said to contain the value 2\*256+23, which is 535. If H were to contain a value of 128 or more, then HL could instead be thought of as containing a negative value, equal to (H-256)\*256 L.

## THE INSTRUCTION LD

Consider the BASIC instruction LET A=42. In machine language we assign variables (registers) using the instruction LD. We could, for example write LD A, 42. Note there is no equals symbol as there is in BASIC, instead a comma (,) is used to separate the A from the number. The effect of this instruction is exactly what you'd expect it to be - the previous value of A is overwritten, and a new value, in this case 42, is assigned in its place.

Each different LD instruction has a different code. For example the code for LD A, is 3E. The number 42 is 2A in hex, so the full instruction in hex is 3E2A. Note that this is TWO BYTES in length (every two hex digits is one byte). Compare this with the number of bytes in the BASIC instruction LET A=42.

The remaining codes are as follows:

LD A,	3E	LD BC,	01
LD B,	06	LD DE,	11
LD C,	08	LD HL,	21
LD D,	16		
LD E,	1E		
LD H,	26		
LD L,	2E		

Using the program "HEXLD" enter the following program, by inputting the symbols in the left hand column. Once the whole program has been entered, break out by inputting "S".

```
2600 LD H,00h
2E2A LD L,2Ah
C9 RET
```

Now that the program is loaded you can run it by typing as a direct command PRINT USR 30000. What happens?

Now try entering this program:

```
0600 LD B,00
0E2A LD C,2A
C9 RET
```

If you possess an OLD ROM then the first program should return a value of forty-two, and the second program should return a value of 30000. However the NEW ROM will work the other way round, and return 30000 for the first program, and forty-two for the second. The reason is the fact that USR works differently for the two ROMs. For the OLD ROM, USR something means load HL with that something and then run the machine code. On the NEW ROM it means load BC with that something before running the machine code. When

BASIC returns the number you are left with is the value of HL (OLD ROM) or BC (NEW ROM). The first program leaves BC unchanged (on the NEW ROM it will have been assigned 30000) but will load HL with 42. The OLD ROM will return HL (42) and the NEW ROM will return BC (30000). The second program is the reverse. It will leave HL unchanged. (On the OLD ROM HL will have been assigned 30000) BC will then be loaded with 42. Which ROM will return which number? Which ROM do you have? Try it and see.

HL, by the way, stands for High/Low. Because any number in HL is stored in two parts the part that is stored in H is called the HIGH part, and the part that is stored in L is called the LOW part. BC and DE also have high and low parts, with the first letter for the high part, and the second letter for the low part.

What is 42 in hexadecimal to FOUR digits? Answer: 002A. What do you think the following program will do? Try it and find out.

OLD ROM	NEW ROM
21002A	01002A
C9	C9

You may be surprised to discover that when you type PRINT USR 30000 to run it you get the answer 10752 - NOT 42! Now run this program:

OLD ROM	NEW ROM
212A00	012A00
C9	C9

NOW you will get 42. Notice the way the 2A and the 00 have been swapped around. Although this is rather strange it is in fact USUAL for the ZX80/81 to think of its numbers as having the low part FIRST, and the high part SECOND. In fact with the exception of line numbers, and in FOR/NEXT loops the ZX80/81 will always store its numbers "the wrong way around." In the instruction LD HL, the first byte is always 2lh. The second byte is the new value of L, and the last byte is the new value of H. Note that this is always three bytes long.

To summarise: The LD instructions which operate on register pairs, rather than on single registers, use values stored "the wrong way round."

#### LDing From One Variable To Another

If we were restricted in BASIC to only using LET instructions of the form LET A= a number we would be a bit stuck. We need to be a bit more flexible than that. For instance something like LET A=B would be useful. Well we can certainly manage that in machine code. The codes are:

LD	A	B	C	D	E	H	L
A	7F	78	79	7A	7B	7C	7D
B	47	40	41	42	43	44	45
C	4F	48	49	4A	4B	4C	4D
D	57	50	51	52	53	54	55
E	5F	58	59	5A	5B	5C	5D
H	67	60	61	62	63	64	65
L	6F	68	69	6A	6B	6C	6D

In the above table you read the left-hand-column registers first, and the top-row registers second, so that the code for LD D,A is 57, and the code for LD A,D is 7A. Notice how each of these is a mere ONE BYTE in length. Compare this with the equivalent BASIC instruction LET A=D, which takes a total of ten bytes in all (eight on the old ROM) if you include the line number, the line length, and the end of line character.

And now for some simple arithmetic. Those of you who have been thinking ahead may have been wondering how we can add and subtract registers like we can in BASIC. After all, the single-byte representation of LD A,B, for example, doesn't leave a lot of room for manoeuvre.

In fact, we use a different instruction altogether to add registers together. The instruction is ADD. You can think of an ADD instruction as being a LET statement with an expression involving "plus" on the right hand side of the equals. A useful example would be

```
ADD HL,DE
LET HL=HL+DE
```

which has the effect

The instruction ADD HL,DE will take the contents of the register-pair DE, and will add this number to the contents of register-pair HL. The result of this calculation will then be stored in register-pair HL. As you can see, if we were working in BASIC and we were dealing in variables instead of register-pairs then we would have performed the operation LET HL=HL+DE.

Well almost, but not quite. There is in fact one small difference - the difference is what happens when you get what is called an overflow. You see register pairs can store all of the (hexadecimal) numbers between 0000 and FFFF. Those from 0000 to 7FFF are the integers 0 to 32767 in decimal, those from 8000 to FFFF can either represent numbers from 32768 to 65535, or numbers in the range -32768 to -1. You can use either form, but when the USR function returns a decimal number to BASIC the OLD ROM will use -32768 to 32767 and the NEW ROM will return a number between 0 and 65535. An OVERFLOW is what happens when you go beyond these ranges. In BASIC any overflow will simply stop the program and give you an error message. What do you suppose will happen in machine code?

OLD ROM first then: the BASIC for the OLD ROM deals with numbers from -32768 to 32767. What is the number 32767 in hexadecimal? Dividing by 256 to split it into two bytes gives 127 remainder 255, so the first byte is 127 (7F) and the second byte is 255 (FF). Now enter this program:

OLD ROM ONLY:	110100	LD DE,1
	21FF7F	LD HL,32767
	19	ADD HL,DE
	C9	RET

The program will simply attempt to add one to the number 32767. Run it (using the direct command PRINT USR(30000)) and the result may astonish you. By the way, did you notice how the 00 and 01, and also the 7F and FF, had been swapped around in the above listing? You must always remember to do this in machine code. Did you notice also that the code for adding the registers (ADD HL,DE) was only one byte long? In fact the byte 19h. All of the ADD codes are one byte in length.

If you want to add one to BC for instance then you must do something like this

210100	LD HL,1
09	ADD HL,BC
44	LD E,H
4D	LD C,L

Notice how B and C have to be loaded separately since there is no such instruction as LD BC,HL. If you have a NEW ROM and you want to see what happens on an overflow load and run this program:

```
NEW ROM ONLY:      210100      LD HL,1
                   01FFFF      LD BC,65535
                   09          ADD HL,BC
                   44          LD B,H
                   4D          LD C,I
                   C9          RET
```

Another thing you should notice is that only register-pairs may be added to register pairs, and that only single-registers may be added to single-registers. You may NOT add a single-register to a register pair, or vice versa. ADD A,HL is WRONG.

```
ADD HL,BC      09      ADD A,A      87
ADD HL,DE      19      ADD A,B      80
ADD HL,HL      29      ADD A,C      81
                   ADD A,D      82
                   ADD A,E      83
                   ADD A,H      84
                   ADD A,L      85
```

If overflowing register-PAIRS had you thinking, then think about overflowing SINGLE registers, for they can only hold numbers from 0 to 255. What happens when they overflow? Well yes, they simply start again at zero, but the question is can we do anything about this? In fact we can. Whenever we add two numbers, sometimes there is an overflow, or CARRY, and sometimes there isn't. The computer sets aside a NEW register, called F (which we cannot use directly) to store various bits of information. One of these bits of information is called the CARRY BIT.

An ADD instruction will always reassign the CARRY BIT. If there is no carry, it will be set to zero. If there is a carry, it will be set to one. We can use the value of the CARRY BIT by using the machine code instruction ADC, which means "ADD with CARRY".

It works like this. Suppose the machine comes across the instruction ADC A,B. It will take the contents of register B, and it will add the contents of register A, as in the previous instruction ADD A,B, and then it will add the CARRY BIT to this new number. Having done this it will store the result in register A, overflowing if necessary. The carry bit will always be reassigned to either zero or one, depending on whether or not there is an overflow.

```
So      ADD A,B      effectively means      LET A=A+B
                                     followed by      LET CARRY=INT((A+B)/256)

whereas  ADC A,B      effectively means      LET A=A+B+CARRY
                                     followed by      LET CARRY=INT((A+B+CARRY)/256)
```

Study the programs that follow. If the value of the A register is irrelevant, then are these programs equivalent (ie do they both do the same thing?) or not? Can you understand why?

```
The first program is
118533      LD DE,13189
21C77B      LD HL,31687
19          ADD HL,DE
44          LD B,H
4D          LD C,L) NEW ROM only
C9          RET
```

22

and the second program is

```
1633      LD D,51
1E85      LD E,133
1E85      LD H,123
267B      LD L,199
2E67      LD A,L
7B          ADD A,E
83          LD L,A
8F          LD A,H
7C          ADC A,D
8A          LD H,A
67          LD B,H
44          LD C,L) NEW ROM only
4D          RET
C9
```

In actual fact they are exactly the same. You can learn two things from this: firstly that the instruction LD does not in any way affect or alter the value of CARRY, for if it did the two LD instructions between ADD A,E and ADC A,D would really mess things up; secondly that the instruction ADD HL,DE is much shorter, and much neater, than going all round the houses by adding each byte separately. And never forget to swap the order of the bytes round in LD instructions on pairs - compare the first two lines of program one with the first four lines of program two.

Now run both of the above programs just to verify that they are the same. What would happen if the ADC A,D in program two were replaced by ADD A,D?

Now that you understand the difference between ADD and ADC we shall go on to cover some other ways of adding. First though, the codes for ADC:

```
ADC HL,BC      ED4A      ADC A,A      8F
ADC HL,DE      ED5A      ADC A,B      88
ADC HL,HL      ED6A      ADC A,C      89
                   ADC A,D      8A
                   ADC A,E      8B
                   ADC A,H      8C
                   ADC A,L      8D
```

Notice how the codes for ADC HL, are all TWO bytes long, rather than one. The first byte is ED, and the second byte depends on what you are adding. Do not think of ED as meaning ADC HL, though, since it may have many other possible meanings as well, depending on what follows it.

#### ADDING CONSTANTS

We can also use the ADD and ADC instructions to add numerical constants directly to the A register. An example would be ADD A,3 which would, as you'd expect, add three to the current value of A. It would also assign CARRY to one or zero, depending on whether or not this addition caused A to overflow beyond 255.

The code for ADD A, is C6, and the code for ADC A, is CE. Note that we cannot add constants to any register other than A.

Suppose we wished to add 57 to HL. One way would be as follows:

```
113900      LD DE,57d
19          ADD HL,DE
```

but this method has the disadvantage that it requires the use of DE, which may be needed for other things. Another way of achieving the same thing, but this time only bringing the A register into use, is thus:

```
7D          LD A,L
C639      ADD A,57d
6F          LD L,A
7C          LD A,H
CE00      ADC A,0
67          LD H,A
```

23

Notice how the instruction **ADD A,0** was used to add any carry digit there may have been from adding 57 to 1.

#### AND FINALLY....

There is one more way that we can add constants to a register, and that is by using the instruction **INC**.

**INC A** means add one to the value of A. Unlike **ADD**, **INC** may be used on ANY register, so statements like **INC D** (add one to the value of D) or **INC DE** (add one to the value of register-pair DE) are allowed.

If A contained the value 255, then **INC A** will set A to zero, but WITHOUT setting **CARRY** equal to one. In fact **INC** will not alter the value of **CARRY** at all. If it was one before an **INC** instruction, it will be one after such an instruction. If it was zero before an **INC**, it will be zero after an **INC**.

In short:

INC B		is equivalent to	LET B=B+1	
INC BC	03		INC A	3C
INC DE	13		INC B	04
INC HL	23		INC C	0C
			INC D	14
			INC E	1C
			INC H	24
			INC L	2C

Remember, the difference between **ADD A,1** and **INC A** is that **ADD A,1** will assign a new value to **CARRY**, whereas **INC A** will leave it unaltered. **INC**, by the way, is short for **INCREMENT**.

The value of **CARRY** can be altered directly without any of the other registers being affected. There is an instruction **SCF**, which stands for **SET CARRY FLAG**, and its job is to assign to **CARRY** a value of one. The code for this instruction is 37h. Alternatively, it is possible to reset **CARRY** to zero, although there is no specific instruction to do this. One way would be to say **ADD A,0** for example. Adding zero will of course leave the value of A unchanged, but an **ADD** instruction will always reassign **CARRY**.

**CARRY** is called a **FLAG** rather than a register, because it can only store the numbers one and zero. It is not possible to assign a value of two to **CARRY**, nor any other number in fact, only one and zero.

There is one other way to directly change the value of the carry flag, that is by using the instruction **CCF**, which stands for **COMPLEMENT CARRY FLAG**. It will change the value of **CARRY** from one to zero, or from zero to one. In **BASIC** terms these three instructions may be listed thus.

37	<b>SCF</b>	<b>LET CARRY=1</b>
C600	<b>ADD A,0</b>	<b>LET CARRY=0</b>
3F	<b>CCF</b>	<b>LET CARRY=1-CARRY</b>

#### SUBTRACTION

In machine language, there are codes for subtraction, which are used in exactly the same way as the addition codes. The instruction is **SUB**, for **SUBTRACT**, and in exactly the same way as **ADD**, there is also an instruction **SEC**, for **SUBTRACT WITH CARRY**.

It works like this. **SUB A,B** will take the value of register B, and will subtract it from the value of register A. The result of this calculation is stored in register A. The carry flag is reassigned to zero if there is no overflow, or to one if the result overflows to below zero (in which case the value of A will have 256 added to it.)

**SUB A,B** may also be written as simply **SUB B**, because it is only the A register which may have things subtracted from it. Do not get confused by this convention - the two terms mean exactly the same thing.

The codes for **SUB** are:

<b>SUB A,A</b>	97
<b>SUB A,B</b>	90
<b>SUB A,C</b>	31
<b>SUB A,D</b>	92
<b>SUB A,E</b>	33
<b>SUB A,H</b>	94
<b>SUB A,L</b>	95

It is also possible to subtract numerical constants from the A register. For example the instruction **SUB A,100** will subtract 100 from the number stored in register A. The result is stored in register A, and the carry flag is re-assigned to zero if there is no overflow, or to one if there is an overflow. The code for subtracting constants is D6, so that **SUB A,100** is D664 (since 100 is written as 64 in hexadecimal)

<b>SUB A,</b>	<b>D6</b>
---------------	-----------

You should note the fact that although there are instructions such as **ADD HL,BC**, there are NO instructions to subtract register-pairs.

**SUBTRACT WITH CARRY (SEC)** on the other hand, WILL work for register pairs, but as with **ADD** and **ADC**, only the value of HL may be altered. For single registers it is only the value of A that may be changed.

**SEC A,C** will subtract the value of C from the value of A, and will then subtract the value of **CARRY** from this result. The final answer will be stored in register A. **CARRY** will be reassigned as before.

The codes for **SEC** are:

<b>SEC HL,BC</b>	ED42	<b>SEC A,A</b>	9F
<b>SEC HL,DE</b>	ED52	<b>SEC A,B</b>	98
<b>SEC HL,HL</b>	ED62	<b>SEC A,C</b>	99
		<b>SEC A,D</b>	9A
		<b>SEC A,E</b>	9B
		<b>SEC A,H</b>	9C
		<b>SEC A,L</b>	9D

To **SUBTRACT WITH CARRY** a numerical constant from the A register the code is DE followed by the number itself in hex. What is the code for **SEC A,200**? What precisely does this instruction do?

**DEC** is short for **DECREMENT**. It is, as you may have gathered from its wierd sounding name, the opposite of **INC** (Increment). Its purpose is to decrease the value of any register by one without changing the value of the carry flag. So **DEC DE** has the effect of **LET DE=DE-1**, remembering of course that if you decrement zero you get 255.

Compare these two routines:

C600	<b>ADD A,0</b>
D602	<b>SUB A,2</b>
ED52	<b>SEC HL,DE</b>

and

C600	<b>ADD A,0</b>
3D	<b>DEC A</b>
3D	<b>DEC A</b>
ED52	<b>SEC HL,DE</b>

Are they the same? And if not, why not? One of these two routines will subtract two from A, and will subtract DE from HL - The other routine is wrong. Which is which?

In fact it is the first example which is wrong. The instruction `SEC HL,DE` will subtract both `DE` and the carry flag, so the carry flag must first be reset to zero. This is what `ADD A,0` is for. But having done that, the first example will alter the carry flag AGAIN with the instruction `SUB A,2`. The chances are that it will be reset to zero, but if `A` happens to equal one or zero then the `SUB` will not only change `A` to 255 or 254, it will also set the carry flag to ONE. So that the effect of `SEC HL,DE` would then be to assign `HL` a value of `HL-DE-1`, NOT `HL-DE`. In the second example, the instruction `DEC A` is used twice. `DEC` will not change the carry-flag, so it will still be zero when the instruction `SEC HL,DE` is reached, and the subtraction will then go ahead correctly.

Got it? `INC` and `DEC` do not alter the value of the carry flag - the other arithmetic instructions do. The other instructions we've covered are `RET` and `LD`. Neither of these will alter `CARRY` at all.

<code>DEC BC</code>	<code>0B</code>	<code>DEC A</code>	<code>3D</code>
<code>DEC DE</code>	<code>1B</code>	<code>DEC B</code>	<code>05</code>
<code>DEC HL</code>	<code>2B</code>	<code>DEC C</code>	<code>0D</code>
		<code>DEC D</code>	<code>15</code>
		<code>DEC E</code>	<code>1D</code>
		<code>DEC H</code>	<code>25</code>
		<code>DEC L</code>	<code>2D</code>

In this chapter we have dealt with how to load machine language programs, and how to run them. The use of the instructions `RET` and `LD` were explained, and the arithmetic instructions `ADD`, `ADC`, `SUB` and `SEC` were introduced along with `INC` and `DEC`. The purpose of the carry flag has been covered, and the instructions `SCF` (Set Carry Flag) and `CCF` (Complement Carry Flag) have been mentioned.

You are not expected to remember any of the hex-codes which the computer uses - not even the experts do that! All of the codes are printed in an appendix in the back of the book. All you have to know are the words we use for them - the `OPCODES` - and what they do.

Before you proceed to chapter four, see if you can tackle some of the following exercises. If you find some of them difficult don't worry about it, just take them slowly, and think clearly.

Enter the following machine language program using `HEXLD`: You will have to look up the various hex-codes yourself!

```
LD BC,0
LD HL,0
ADD HL,BC
(LD B,H)
(LD C,L)-NEW ROM only
RET
```

Now use the direct command `PRINT USR 30000` to run it. What did you get? If you got zero well done. If, on the other hand, you got `-31004` or `34532` then you did something fundamentally wrong. The instructions `LD BC`, and `LD HL`, both need THREE bytes altogether to make them work, not two. What

instructions did you really give the computer to make it come up with `-31004` or `34532`? And how exactly did it arrive at that answer? Now try again until you get zero.

Delete `HEXLD` by typing `NEW` (or on the old ROM by deleting each line individually). The machine code program will STILL BE THERE. Type in the following BASIC program:

```
10 INPUT A
20 INPUT B
30 POKE 30001,A-INT(A/256)*256
40 POKE 30002,INT(A/256)
50 POKE 30004,B-INT(B/256)*256
60 POKE 30005,INT(B/256)
70 PRINT A,B
80 PRINT USR 30000
90 PRINT
100 GO TO 10
```

This BASIC program will replace the second, third, fifth, and sixth bytes of the machine code routine by the values you input in lines 10 and 20. Run the program and input some values to see what happens. Try going outside the range `-32768` to `32767`.

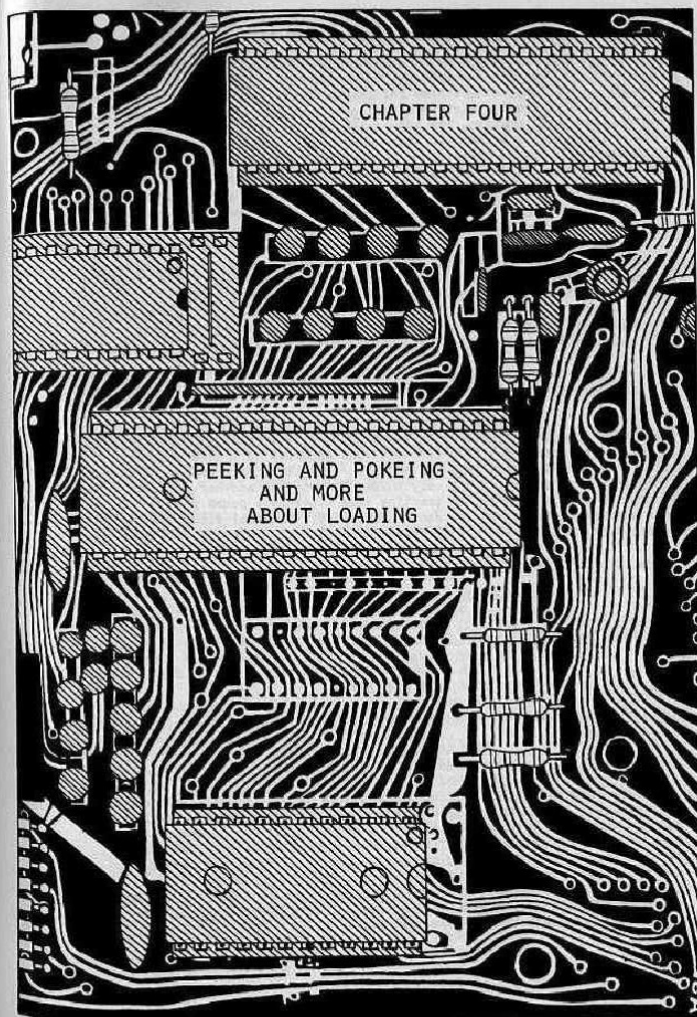
Now see if you can write a similar program, including a COMPLETELY NEW machine code routine, which will print a TABLE of values of `A` and `B` on the screen, and the result of subtracting `A` from `B` in each case. Let `A` and `B` both take on all of the values from 1 to 10 inclusive.

Write a machine code routine which will produce a one if `BC` is greater than or equal to `DE`, and a zero otherwise. How could you test this? (HINT: see previous exercises on this page) Do so.

Write a short machine code routine which will set the carry flag equal to one, but without altering any of the registers. Do it WITHOUT using the instructions `SCF`, `CCF`, or `ADD A,0`.

CHAPTER FOUR

PEEKING AND POKEING  
AND MORE  
ABOUT LOADING



# PEEKING AND POKING AND MORE ABOUT LD-ING

For those of you who thought maybe seven registers might not be enough, it's just as well we can PEEK and POK, and thus make use of all the addresses in the RAM. (The RAM, which stands for Random Access Memory by the way, is the portion of memory which we are allowed to alter - the addresses numbered from 16384 upwards. The add-on 16K pack is RAM for instance.) If there's any number we have to store somewhere, either permanently or temporarily, then it makes sense to just POK that number somewhere - (almost anywhere will do) then when we need it again all we have to do is to PEEK at that address and voila - there it is!

## A LESSON IN PEEKING

If you've ever seen any machine language printed anywhere, you may have wondered why obscure brackets kept turning up here and there. What, for example, is the difference between LD HL,16396, and LD HL,(16396)? It's not just for variety, or to make it look pretty, they do actually mean something: brackets around a number or register-pair will refer to the contents of the ADDRESS in the brackets. So

```
LD HL,16396      means LET HL=16396
and LD HL,(16396) means LET HL=PEEK 16396+256*PEEK 16397
```

The second example may have confused you. The only address in brackets is 16396, so how does 16397 come into it? What happened is a kind of side-effect. H and L can each hold ONE BYTE, so the pair HL stores TWO BYTES altogether. The address 16396 only holds ONE byte, so another one has to come in from somewhere. In practice this other byte comes from the next possible address, in the above case, 16397. The real effect of the instruction LD HL,(16396) is LET L=PEEK 16396, followed by LET H=PEEK 16397.

There is also a reverse instruction, which is

```
LD (16396),HL
```

This is effectively POKING. The result of the instruction is

```
POKE 16396,HL=INT(HL/256)*256
POKE 16397,INT(HL/256)
```

or if you think of H and L separately:

```
POKE 16396,L
POKE 16397,H
```

In BASIC, this particular pair of instructions is used quite frequently. I'll give you an example. Suppose you've just written a BASIC program, and you want to know how long it is. You can find out the number of bytes your program occupies by using the expression PEEK 16404+256\*PEEK 16405 to find the address of the END of your program (including the screen and all of your variables) and then subtract 16509 (the START of your program) from this number. There is a similar expression for the OLD ROM, which is PEEK(16394)+256\*PEEK(16395)-16424. A very simple machine code program to calculate this value would be:

## OLD ROM

```
112840
2A0A40
C600
ED52
C9
```

```
LD DE,16424
LD HL,(16394)
ADD A,0
SBC HL,DE
RET
```

## NEW ROM

```
117D40
2A1A40
C600
ED52
44
4D
C9
```

```
LD DE,16509
LD HL,(16404)
ADD A,0
SBC HL,DE
LD B,H
LD C,L
RET
```

The instruction ADD A,0 is used to set the carry flag to zero, so that the immediately following instruction will always produce the correct answer. Remember that there is no such instruction as SUB HL,DE, so if we ever need to subtract HL from DE we are forced to use SBC instead. This won't subtract properly unless CARRY equals zero.

Notice how the hex-code for LD HL,(16404) is built up. The first byte is 2A. Now, although you're not expected to remember this, the last time we used a LD HL, instruction the code was 21 (hex). The difference is the TRACKERS! LD INSTRUCTIONS WHICH USE BRACKETS HAVE A COMPLETELY DIFFERENT HEX-CODE. The next two bytes are 1A and 40:- this is the number 16404 in hexadecimal - if you divide 16404 by 256 you get sixty-four (40h) remainder twenty (14h). In the HEX-CODE these two bytes have been switched around to give 1440 rather than 4014. You must always remember to do this in machine code.

If you store this machine code program above RAMTOP (This is something that only NEW ROM users can do easily) as I've described then you can type in or LOAD any BASIC program and find its length in bytes simply by the by now familiar direct command PRINT USR 50000

16404 will ALWAYS contain the address of the end of all the variables in your program - this is its job. It is one of the SYSTEM VARIABLES which are used to help the ROM know what it is doing. If you alter this value by POKING or LDing then the poor machine will get very confused, although, as we shall see later, this is sometimes an advantage.

Make sure you understand exactly how the above program works, and why every line is needed. The most important instruction is still the first one we learned - RET. If any of the others are missing then you will get the wrong answer, but at least you'll get AN answer. Without RET the program will CRASH.

Not all of the variables (registers) can be LDed from addresses. The instructions you are allowed to use, together with their codes, and a breakdown of exactly what they do, are listed here.

```
LD A,(pq)
LD BC,(pq)
LD DE,(pq)
LD HL,(pq)
```

```
3A
ED4B
ED5B
2A
```

```
LET A=PEEK pq
LET C=PEEK pq
LET B=PEEK(pq+1)
LET E=PEEK pq
LET D=PEEK(pq+1)
LET L=PEEK pq
LET H=PEEK(pq+1)
```

## AND POKING:

```
LD (pq),A
LD (pq),BC
LD (pq),DE
LD (pq),HL
```

```
32
ED43
ED53
22
```

```
POKE pq,A
POKE pq,C
POKE pq+1,B
POKE pq,E
POKE pq+1,D
POKE pq,L
POKE pq+1,H
```

You will notice that only the variable A may be assigned a PEEK value, or POKE anywhere, by itself - all of the other registers may be used in pairs. Usually this is quite a useful feature, but there are times when you'll want to assign a single register (a usual choice is L) without disturbing the value of A. There isn't really any way around this I'm afraid, but what you can do is to assign both halves of a register pair as described above, and then reset one of the registers to zero afterwards.

Suppose you needed to know how far down the screen the PRINT position was. If you look in your instruction manual you'll find that PEEKing 16442 will tell you exactly that. (On the OLD ROM you'll need 16421 instead.) The problem is to LD this into HL, because the number we're after is ONE BYTE long - it ISN'T stored in either 16441 or 16443 - and one way of doing it is this:

OLD ROM		NEW ROM	
212540	LD HL,(16421)	ED4B3A40	LD BC,(16442)
2600	LD H,C	0600	LD B,0
C9	RET	C9	RET

As you can see, the first instruction will successfully load the contents of 16421/16442 into the L or C register as required, but it will also load H or B with 16422/16443, so H or B must be reset to zero before we return to BASIC, otherwise the figure printed by the routine will be virtually meaningless.

The other way of getting PEEK 16442 into BC is to go via the A register, since this register can be LDed directly all by itself. But as you will see this offers no advantages, since we still have to reset B to zero anyway.

OLD ROM		NEW ROM	
3A2540	LD A,(16421)	3A3A40	LD A,(16442)
2600	LD H,0	0600	LD B,0
6F	LD L,A	4F	LD C,A
C9	RET	C9	RET

If you still aren't convinced that the second instruction is necessary try omitting it to see what happens. You'll find you get the number 29952 added to the real answer. Can you see why? You started off with the number 30000 and only altered the LOW part. The HIGH part was unchanged. (The HIGH part is INT(30000/256).) It happens to be 117. The factor of 29952 comes in because 117\*256 is 29952.

Both of the above programs, as they are written, will have the same effect - they will tell you the line number of the PRINT position, that is, they will tell you how far down the screen the next character to be printed will be.

Try feeding in ONE of the above two programs, and then type in this BASIC program:

```
10 FOR I=0 TO 20
30 PRINT USR 30000
50 NEXT I
```

Remember, only NEW ROM users may type NEW without wiping out the machine code. Run it and see what happens. Now insert more lines.

```
20 FOR J=0 TO 3
30 PRINT TAB(8*J);USR 30000;
40 NEXT J
```

and again, RUN it and see what happens. OLD ROM users should replace the new line 30 by PRINT USR 30000, (ie with a comma at the end of the statement).

## POKEing IN MACHINE CODE

POKEing is just as easy. To put line 50 of your BASIC program at the top of the screen at the next automatic listing you can POKE 16419,50. (On the OLD ROM it is POKE 16403,50.) You must make sure the cursor is 50 or more first though. In machine code:

OLD ROM		NEW ROM	
3E32	LD A,50	3E32	LD A,50
321340	LD (16403),A	322340	LD (16419),A
C9	RET	C9	RET

Note that it doesn't actually matter what number returns to BASIC - (in actual fact it will be 30000) - the important thing is that the system variable called S-TOP (Screen Top) is POKEd with 50. That is what this program does.

Now look at the HEX-CODE of LD (16419),A. The first byte is 32h. This is the code for LD (pq),A, where pq represents some arbitrary address. The remainder of the code is 2340, which is the number 16419 in hexadecimal (with of course the first and last bytes switched around) So even though we humans would write our OPCODE with the (16419) first, and the ,A second, the machine language code always puts the instruction itself FIRST - despite the fact that the instruction itself actually incorporates the A at the end of the OPCODE. You must not put the 32h last, for the instruction 234032 would mean something totally different. In fact it would probably end up crashing, because it would take it to mean

23	INC HL
40	LD B,B
32	LD (???) ,A

With the (???) address made up of your next two bytes of machine code.

There are some other PEEK and POKE instructions which use register names throughout. These are:

LD A,(BC)	0A	LET A=PEEK BC
LD A,(DE)	1A	LET A=PEEK DE
LD A,(HL)	7E	LET A=PEEK HL
LD B,(HL)	46	LET B=PEEK HL
LD C,(HL)	4E	LET C=PEEK HL
LD D,(HL)	56	LET D=PEEK HL
LD E,(HL)	5E	LET E=PEEK HL
LD H,(HL)	66	LET H=PEEK HL
LD L,(HL)	6E	LET L=PEEK HL
LD (BC),A	02	POKE BC,A
LD (DE),A	12	POKE DE,A
LD (HL),A	77	POKE HL,A
LD (HL),B	70	POKE HL,B
LD (HL),C	71	POKE HL,C
LD (HL),D	72	POKE HL,D
LD (HL),E	73	POKE HL,E
LD (HL),H	74	POKE HL,H
LD (HL),L	75	POKE HL,L

If you study the codes of the instructions that have (HL) in them you'll see that they form a regular pattern. In fact it looks very much like there ought to be an instruction LD (HL), (HL) with code 76 just to fill up a small hole in the regular pattern. In actual fact there is no such instruction, and code 76 corresponds to an instruction called HALT.

To demonstrate what I mean, here is a small table of all of the LD codes, which use registers A to L, and address (HL):

LD	B	C	D	E	H	L	(HL)	A
B	40	41	42	43	44	45	46	47
C	48	49	4A	4B	4C	4D	4E	4F
D	50	51	52	53	54	55	56	57
E	58	59	5A	5B	5C	5D	5E	5F
H	60	61	62	63	64	65	66	67
L	68	69	6A	6B	6C	6D	6E	6F
(HL)	70	71	72	73	74	75	—	77
A	78	79	7A	7B	7C	7D	7E	7F

Do you see what I mean about a regular pattern with LD (HL), (HL) missing? Of course, it's not an instruction you'll ever want to use, since it does absolutely nothing, but it's worth pointing out that you must never even ATTEMPT to use it because, as I've said, 76 is the code for HALT.

Why is any variable in brackets a register pair rather than a single register? Why is any variable NOT in brackets a single register rather than a register pair? If HL contained a value of 16434, what is the difference between LD B, (HL) and LD BC, (16434)? What is the precise effect of each? See if you can write a program in machine language which will assign to HL a value of PEEK 16442 ONLY, using one of the LD, (HL) instructions.

We have now covered all of the basic LD instructions which operate on the registers A, B, C, D, E, H, L. We shall now take a look at some of the other ways of loading these variables.

#### HOW TO LOAD BLOCKS

Loading BLOCKS means loading huge chunks of memory all in one go. For example, if you had a machine code routine stored beginning at location 30000 and you wanted to move it completely to location 20000, then if you were really really patient you could write a new machine code routine along the lines of

```

11204E      LD DE,20000
213075      LD HL,30000
7E          LD A,(HL)
12          LD (DE),A
23          INC HL
13          INC DE
7E          LD A,(HL)
12          LD (DE),A
23          INC HL
....
and so on.

```

You could shorten things a bit if you knew about the instruction LDI, which means LOAD WITH INCREMENT. This is a very special instruction which does four things all in one go. First of all it will transfer the contents of the ADDRESS stored in HL into the ADDRESS stored in DE, then it will increment both HL and DE, and it will decrement BC. It will not alter the value of register A. To summarise:

```

LDI          EDI          POKE DE,PEEK HL
              LD HL,HL+1
              LD DE,DE+1
              LD BC,BC-1

```

The above program could therefore have been completely rewritten as

```

11204E      LD DE,20000
213075      LD HL,30000
EDAO        LDI
EDAO        LDI
EDAO        LDI
....        ....
and so on.

```

There is no list of variables after the opcode LDI, because the instruction will ALWAYS load from (HL) to (DE). You must not write LDI (DE), (HL) because this does not make sense. Further, it is impossible to load in this manner in any other combination. Loading from (HL) to (BC) for example simply cannot be done in a single instruction.

There is also an instruction LDD, or LOAD WITH DECREMENT, which has the same effect as LDI except that DE and HL are decremented and not incremented. Neither of these instructions, as with all LD instructions, will in any way alter the value of CARRY. The code for LDD is EDAB.

#### REPEATING THINGS

Even with LDI and LDD at our disposal, it would still be a very tedious affair to move something from, say, 30000 to 20000 if that something were around fifty bytes long. If it were a hundred we'd probably give up in despair. Fortunately for us both LDI and LDD have a REPEAT facility. If, instead of writing LDI we wrote LDIR, with the extra R standing for REPEAT, then the instruction LDI would be carried out over and over again, and would not stop until the value of BC was zero. So if the routine we wanted to move was in fact 100 bytes long then we could move it using the routine

```

016400      LD BC,100
11204E      LD DE,20000
213075      LD HL,30000
EDBO        LDIR

```

When the machine reaches the instruction LDIR, BC will contain a value of 100. After LDI had been carried out once, the first byte would have been transferred, DE would be increased to 20001, HL would be increased to 30001, and BC would be decreased to 99. After a second attempt, the second byte would have been transferred, and BC would contain a value 98. After LDI had been carried out one hundred times, the whole routine would have been successfully transferred, and BC would contain a value zero and so the program would continue with the next instruction. If this routine were the entire program then the next instruction should of course be RET.

The four instructions LDI, LDD, LDIR, LDDR each do slightly different things. Make sure you understand the differences between them. They also each have a different code, all beginning with ED. The codes are

```

LDI          EDAC
LDD          EDAB
LDIR         EDBC
LDDR         EDBB

```

I shall now give you a program which will enable you to SCROLL the screen BACKWARDS, so that the screen moves downwards, not upwards, and the print position is moved to the top of the screen. It will work on the OLD ROM provided 1) all twenty-two lines of the screen are full, i.e. contain thirty-two characters plus a newline character, 2) you do not attempt to PRINT anything again (however you can alter the screen by POKING the display file). It will work on the NEW ROM provided 1) RAMTOP is at least 19712 (effectively this means if you have 4K or more plugged in) 2) every time you use the statement SCROLL you fill the bottom line (for example by using the statement PRINT "thirty-two spaces", your next PRINT should be a PRINT AT.

A complete explanation of the program will also be given.

```
01B602      LD BC,726
2A0C40      LD HL,(16396)
09          ADD HL,BC
34          LD B,H
3D          LD E,L
01B502      LD BC,693
2A0C40      LD HL,(16396)
09          ADD HL,BC
EDB8       LDIR
C9          RET
```

The screen may now be scrolled BACKWARDS by using the NEW ROM statement PRINT AT USR 30000,0; On the OLD ROM the corresponding statement is LET L USR(30000) but remember that on the OLD ROM once the screen is full you can only "PRINT" by POKING into the display file. The machine code routine will leave a value of zero in BC. (See the description of the last instruction, LDIR) so having executed the machine code it will then PRINT AT 0,0; i.e. it will move the NEW ROM print position to the top of the screen. This is precisely the opposite of SCROLL.

The first instruction is LD BC,726. This is the number of characters in the screen. There are twenty-two lines and each line contains thirty-three characters (thirty-two plus one new-line character) hence the total number is  $22 \times 33 = 726$ . The address 16396 (together with 16397) contains the address of the START of the display file. (The first character in the display file is a new-line, so the screen itself actually starts one character further on.) This address is LDed into HL. Remember that LD HL,(16396) will load TWO bytes into HL, not one. The ADD instruction will then calculate the address of the LAST byte of the screen.

In order for LDIR to work, we need this address in DE, not in HL, and so since LD IE,HL is not a valid instruction it needs TWO instructions, LD I,H and LD E,L to accomplish this. We can now use HL for something else.

We need the address of what WILL BE the last character of the screen after we've finished scrolling (or antiscrolling if you want to call it that). Since it is the bottom line that will be lost, then this will be the last character of what is currently the TWENTY-FIRST line. So we need the start address plus  $21 \times 33$ , or 693.

The next three instructions in the program: LD BC,693; LD HL,(16396); and ADD HL,BC will achieve this, and the result will be left in HL. This is precisely what we need for LDIR to work. LDIR will transfer from the address contained in HL to the address contained in DE, i.e. it will move the last character of the twenty-first line to the last character of the twenty-second line, before HL and DE are both decremented, or decreased by one.

How many times do we need to make such a transfer? We have to move twenty-one lines altogether, so we have to make sure that we do not use LDIR until BC contains a value of 21\*33, or 693. As it happens, it already does, since we assigned it to 693 earlier on in the program. We may now quite happily use the instruction LDIR to BLOCK LOAD the first twenty-one lines of screen down to their new position occupying the LAST twenty-one lines of screen. Note that the old screen will be completely overwritten by the new screen with the exception of the first (top) line, which will be left unchanged. This is why the BASIC statement PRINT AT 0,0;"thirty-two spaces" is needed after every antiscroll.

The following NEW ROM BASIC program is designed to demonstrate the ANTISCROLL feature at work. It isn't a terrifically exciting game, or a pattern making artistic genius, or anything, but it will show you exactly what the machine code we've just been working on will do. You can of course insert the routine into any program - there are some graphics games which would be immensely enhanced by the ability to SCROLL in either direction. This program sets up a striped pattern across the screen, with each stripe composed of a random character chosen from the whole ZIS1 set. The pattern on the screen will then wait for you to tell it what to do. Pressing the "up" key will move the pattern upwards, and pressing the "down" key will move the pattern downwards. These are of course the standard cursor control keys I'm referring to, except that you don't need to use SHIFT.

The listing is written for both FAST and SLOW modes. In FAST, line 110 should read PAUSE 40000, but in SLOW it should be changed to IF INKEY#="" THEN GOTO 110. Otherwise enter the program as listed.

#### UP AND DOWN

```
10 DIM A$(22,32)
20 FOR I=0 TO 22
30 LET B%=CHR$(63+RND*128*(RND*.5))
40 FOR J=1 TO 5
50 LET B%=B%+B%
60 NEXT J
70 LET A$(I)=B%
80 PRINT A$(I)
90 NEXT I
100 LET A=1
110 PAUSE 40000
120 LET B=A+1
130 IF B=23 THEN LET B=1
140 LET C=A-1
150 IF C=0 THEN LET C=22
160 LET B%=INKEY$
170 IF B%="6" THEN PRINT AT USR 30000,0;A$(C)
180 IF B%="7" THEN SCROLL
190 IF B%="7" THEN PRINT A$(B)
200 IF B%="6" THEN LET A=C
210 IF B%="7" THEN LET A=B
220 GOTO 110
```

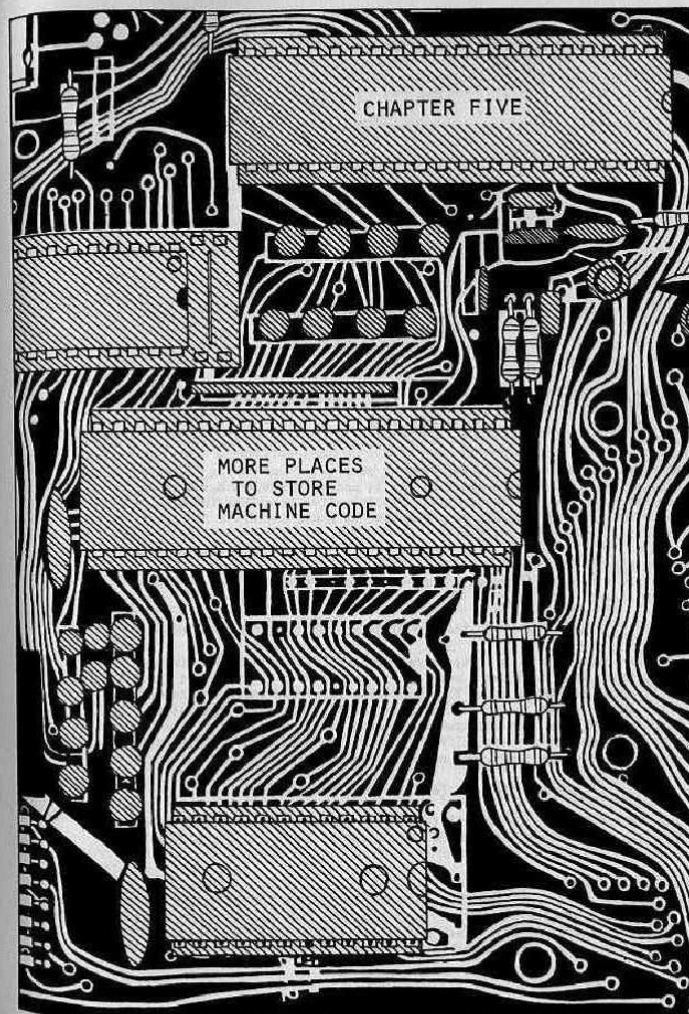
This chapter has tried to develop a deeper understanding of the LD instruction, and has explained how LD can be used to access the memory addresses of the computer. The specialised load instructions LDI (Load with Increment), LDD (Load with Decrement), LDIR (Load with Increment and Repeat), or BLOCK LOAD with Increment, LDIR (Load with Decrement and Repeat, or BLOCK LOAD with Decrement) have been covered.

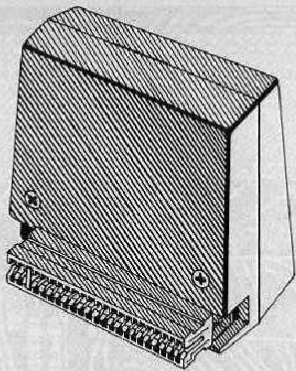
#### EXERCISES

Based on the Antiscroll program in this chapter, write a machine language program to SCROLL forwards, as the keyboard SCROLL does. (This exercise is especially useful if you do not have SCROLL on your keyboard.) Then see if you can write a machine language program which scrolls forward, but which will ONLY SCROLL THE BOTTOM HALF OF THE SCREEN, so that the top ten lines are unaltered, the eleventh line is lost, and the twelfth to twenty first lines are all moved up one line.

Write a BASIC program making use of the routine. You will need the BASIC statement PRINT AT 21,0;"thirty-two spaces" every time the machine code routine is used. Try leaving this out just to see what happens.

If you can't cope with the challenge of writing such a SCROLL program, then I'll give you a hint or two. You will need to use LDIR instead of LDD, otherwise all you'll get is a pretty pattern, and you'll need to start block loading at the BEGINNING of the screen, NOT the end. The instruction LD HL,(16396) will always give you the address at which the screen begins. Don't forget that a full line contains thirty-three characters, not thirty-two, since there is always a new-line character there as well.





## SOME NEW PLACES TO STORE MACHINE CODE

Storing machine code above RAMP0P will protect it from being erased by NEW, or overwritten by a program, but it has the disadvantage that you can never save it. There are several alternative locations in which we can store machine language programs, and we shall explore a few of the possibilities in this chapter.

### Using REM.

To store a machine language routine that is fifty bytes long, make the first line of your program

```
1 REM 12345678901234567890123456789012345678901234567890
```

is a REM statement with fifty characters after it. If your routine was sixty bytes long then you'd need sixty characters after the word REM. If it were only three bytes long you would only need three characters after the word REM. It doesn't actually matter what these characters actually are, but counting upwards in ones, as I have done, will ensure that you don't lose count halfway through. You will need to LOAD "HEXLD" before you add this new line one, and then change line 10 to

```
10 LET X=16514 (or 16427 on the OLD ROM)
```

OLD ROM users should ensure that line one does not appear on the automatic LISTing. You can use the command POKE 16403,10 to remove it. If this has no effect try moving the cursor to line 10 and try again.

NOW you can enter a machine code program exactly as before, except that to execute it you must say USR 16514 instead of USR 30000. On the OLD ROM you must say USR(16427). BUT you MUST NOT type NEW. Delete HEXLD by entering the line numbers one at a time, and do not delete line one! On the OLD ROM you must not even attempt to list line one or you may cause a crash.

Now there are two very important differences between using 16514 and using 30000. Firstly, SAVE will store the machine code as well as the BASIC program - this is something you cannot do in upper memory. Secondly, the command NEW will erase it. It is thus an integral part of the program, and can only be used with that one BASIC program and no other (unless you delete it line by line and then type in a new program line by line). If you have written a machine code routine specifically to accompany some BASIC program then this method is an obvious choice, but it does have one big disadvantage - on the OLD ROM the command LIST will usually cause a system crash.

There is another very very good place to store machine code, that is immediately after the program area. This has several advantages: 1) The BASIC surrounding program can be safely listed - even on the OLD ROM. 2) The MACHINE CODE can be SAVED. 3) Using RUN, as opposed to GOTC 1, will not wipe it out. To load a machine code routine that is, say, 20 bytes long, type the following BEFORE you type in any BASIC:

```
OLD ROM: 1 REM 45678901234567890
NEW ROM: 1 REM 678901234567890
```

Then as a direct command type:

```
OLD ROM: POKE 16424,-1
NEW ROM: POKE 16509,-1
```

You have now reserved a space of twenty bytes in which to store whatever machine code you like. The starting address is a little more complicated though - it is on the OLD ROM  $PEEK(16392)+256*PEEK(16393)-20$ , and on the NEW ROM  $PEEK 16396+256*PEEK 16397-20$ . The PEEK expression is the end of the machine code, and the minus twenty is there to find the start. This is an excellent way of storing machine language routines. You begin loading it from address  $PEEK 16396+256*PEEK 16397$ -length-of-routine, and you can execute it with the expression USR (PEEK 16396+256\*PEEK 16397-length-of-routine). First though, there is one disadvantage to get round. As I've explained things so far there is no way you can actually load an editing program like HEXLD: If you LOAD before you apply the above technique then HEXLD will disappear along with the REM statement as soon as you POKE 16509. If you try to LOAD after you've reserved a space then the very act of LOADING will overwrite this space.

Here then is a step by step method of reserving a space for machine code in a place that is 1)editable, 2)SAVEable, and 3)unLISTable.

### STEP ONE. LOAD an editing program such as HEXLD.

STEP TWO. Add a new line at the END of the program: 9999 REM followed by a number of arbitrary characters. On the OLD ROM you'll need three characters less than the number of bytes in the machine code routine, on the new ROM you'll need five bytes less than the machine code. The best way of doing this is to fill the REM statement with digits, and simply start counting from 4 (OLD ROM) or 6 (NEW ROM). Like this - for a fifteen byte routine:

```
OLD ROM: 9999 REM 456789012345
NEW ROM: 9999 REM 6789012345
```

Of course it doesn't actually matter if you have too many characters, but it is a waste of space if you reserve area and then don't use it.

**STEP THREE.** Add the following lines anywhere in the program. I've put them at 9000, but it doesn't matter. If you use 8000 then just remember to read 8000 every time you see 9000 written on this page.

```

OLD ROM      9000 LET X=PEEK(16392)+256*PEEK(16393)
NEW ROM      9000 LET X=PEEK 16396+256*PEEK 16397

OLD ROM      9010 POKE X-(four more than the number of
NEW ROM      9010 POKE X-(six more than the number of
              characters in the REM statement),-1
              characters in the REM statement),-1

BOTH         9020 STOP

```

If you counted up to fifteen in line 9999 (as above) then 9010 should be POKE X-15,-1. If you counted up to twenty then line 9010 should instead be POKE X-21,-1, and so on. Remember though to start counting at four or six though, as above.

**STEP FOUR.** Run the program from line 9000, and then delete lines 9000, 9010, and 9020.

**STEP FIVE.** Replace all references to the machine-code-starting-address on your editing program by the expression PEEK 16396+256\*PEEK 16397 minus the number you counted up to in the REM statement. OLD ROM users should instead use PEEK(16392)+256\*PEEK(16393) minus the number you counted up to in the REM statement.

You are now complete. The only thing you must not do is type REM, since this will erase the machine code. Other than that you are in complete command.

#### REM STATEMENTS

For the purposes of storing machine code, OLD and NEW ROM REM statements are completely different. Let's examine them one at a time. First of all for the Old ROM:

There are several important points about OLD ROM REM statements. Most people already know that a "blank" REM statement - that is a statement consisting of the word REM and nothing else - has the effect of ensuring that the next line is not executed. It is therefore the same as GOTO the-line-after-next, and can be used in BASIC programs deliberately with this meaning.

The biggest limitation of an OLD ROM REM statement is the fact that you may not store the byte 76 (hex) in the line, except in extremely limited cases, which I shall explain. The reason is that a character 76 is interpreted by the ROM as an end of line marker. The two bytes immediately after such a character will be interpreted as representing the line number of the next BASIC program line, and the following byte will be the first character in that line. Thus if the following data were POKED into a REM statement in line one the following would happen:

```

DATA:      39 76 01 01 F8 E4 D5

RESULT:    1 REM T
           257 LET C THEN
           2 next line of program...

```

If you tried to RUN this program you would get a syntax error in "line 257". Typing RUN 2 would be useless, because the program searches for line numbers from top to bottom, and as soon as it hit the "line number" 257 it would think to itself "ah - there obviously isn't a line 2 in the program - I'll have to RUN it from here instead." The same applies to all GO TO's in the program which have destinations between 2 and 257. You must only allow 76's in your data IF the next two bytes form a "line number" less than the next line number in the program, and IF you never try to execute this "new line".

On the other hand - this treatment does offer one or two advantages. For instance, if you made your REM statement too long and you want to shorten it, if your machine code data ends at address A just type

```

POKE A+2,2
POKE A+1,0
POKE A,118

```

then simply delete "line 2" by typing in it's line number. It doesn't matter if there is already a line numbered 2 in the program - typing the line number alone will only delete the first "line 2" in the program - all your excess REM characters in other words.

Conversely, if you find you don't have enough characters after the word REM just type in a line 2 consisting of a second REM statement full of arbitrary characters. In this way as soon as the "real" end of line marker is overwritten line 2 will become part of line 1, with enough characters for whatever you need.

Also, the NEW ROM does not fit any of these descriptions. NEW ROM REMs are quite, quite different.

The first, and most important difference, is that you can put character 76's into the REM data and the machine won't notice. BUT if you do so be prepared to be confused by the LISTING - even the ROM gets confused over it - but you don't need to worry because even with supposed new-line markers in mid-line the program will RUN quite smoothly, and will not interpret the remainder of the line as a different line.

On the other hand, it's a little more difficult to extend the length of a REM statement. If you want to overrun into line two you'll have to do some very clever POKING first, but I'll explain how to get round that in a minute. The obvious way of making a line longer is simply to use EDIT and add more characters. Unfortunately for us this is usually not a very wise thing to do.

If the data in the line does not contain a byte 7E then by all means go ahead and use EDIT - you are quite safe, and nothing will go wrong.

If the data in the line does contain a byte 7E then DO NOT use EDIT. In the listing, a byte 7E is invisible, and the five bytes of data that follow immediately after it will also be invisible, but they are still there! If on the other hand you use EDIT, all six of these invisible bytes will simply vanish without a trace.

7E is used by Sinclair to mean "This is a (floating point) number". Whenever you use a decimal number in a program listing the ROM will automatically follow this number with a byte 7E, followed by five more bytes which contain the number itself in floating-point-binary-form. Both the byte 7E and the five bytes that follow will be invisible from the listing. This is what causes all the problems in editing REM statements. Now although I agree that this is a very efficient means of storing floating point numbers in a program, it is also true that Sinclair Research could have used ANY byte

for this purpose - they didn't specifically have to use 7E. It is of course the purest of coincidences that 7E happens to be one of the most commonly used machine language instructions of all.

The only practical means of adding more characters to a REM statement containing machine code on the NEW ROM is to let the data overrun into line two, but there are problems even there, thanks to our kind friends at Sinclair Research. You see the start of every line of program is preceded by two invisible bytes which store the length of the line, so that even if you overwrite the end-of-line-marker, the ROM will still try to interpret the second line from the same point. To get round this you have to actually POKE these invisible bytes with different values. The following is a small routine which will enable you to increase the length of a REM statement at line one.

Step one is to insert a new line 2 to your BASIC program consisting of the word REM followed by a number of arbitrary characters. Then, at ANY point in the program insert the following five lines - (They will shortly be deleted anyway):

```
LET A=16515+PEEK 16511+256*PEEK 16512
LET A=A+PEEK A+256*PEEK (A+1)-16511
POKE 16511,A-256*INT (A/256)
POKE 16512,INT (A/256)
STOP
```

Simply run this routine and line 2 will automatically be a part of line 1. You can delete this routine now - its job has been done. LIST line one - you'll see that line two still looks quite separate, but try moving the cursor down - you'll find it skips over line two altogether. Try deleting line 2 by typing in its line number - it won't work because now the computer doesn't know that line 2 is there! Whatever the listing may look like, the ROM will now ignore line 2 altogether, taking it to be part of line one. You may now quite happily overwrite the end-of-line-marker at the end of line one with no ill effects.

Conversely, the following routine will shorten a REM statement by a minimum of six bytes.

```
LET A=the address of the last byte which you wish to preserve
in the REM statement of line 1.
LET B=A-16511
LET C=PEEK 16511+256*PEEK 16512-B-4
POKE 16511,B-256*INT (B/256)
POKE 16512,INT (B/256)
POKE A+1,118
POKE A+2,0
POKE A+3,2
POKE A+4,C-256*INT (C/256)
POKE A+5,INT (C/256)
STOP
```

Again you simply RUN the routine once, and then delete it. Now LIST the program and you'll find a new line 2 has appeared. Delete this by typing its line number and your REM statement will now be as short as you need it.

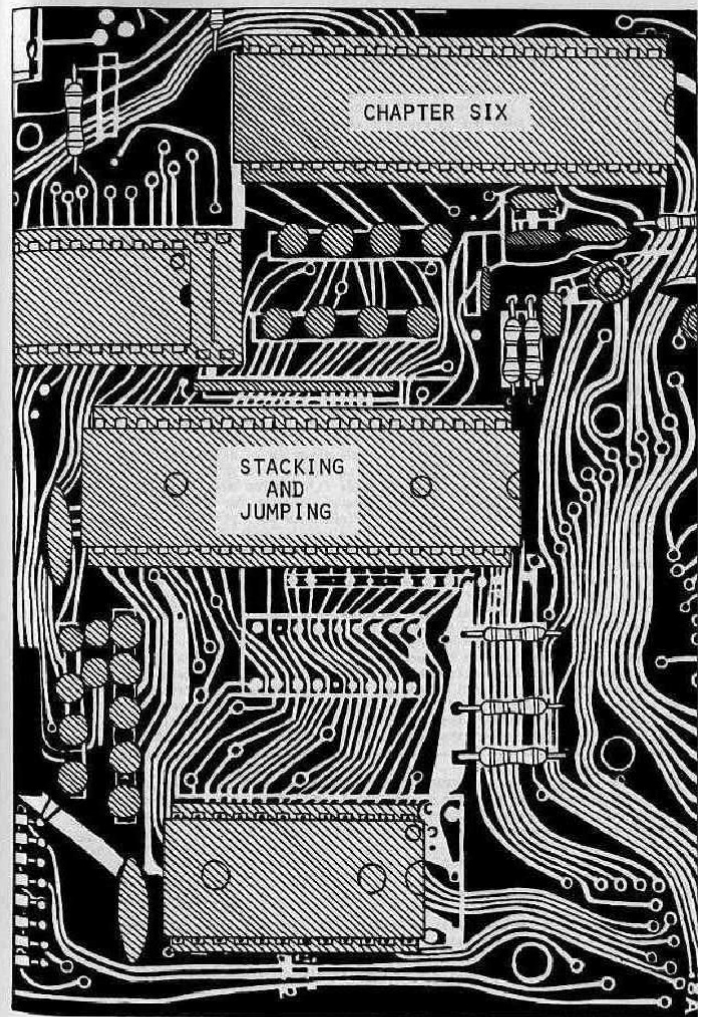
## USING THE VARIABLES AREA

Another place where machine code may be stored is in the variables area. To do this you must first of all reserve the space. To store a machine code routine of n bytes (n is the length) OLD ROM users should type DIM O(n/2), and NEW ROM users should type DIM O\$(n). You may now write your machine code.

On the OLD ROM the starting address will be PEEK(16392)+256\*PEEK(16393)+2, provided the array O is the first item in the variables area. This will be the case if the DIM was the first DIM, FOR, INPUT, or LET statement executed since the last time you used RUN or CLEAR. If you DIMensioned O as a direct command you should remember to type CLEAR first. You can say in your program something along the lines of LET A=PEEK(16392)+256\*PEEK(16393)+2 right at the very start, and this value will not change throughout the program.

On the NEW ROM the starting address is PEEK 16400+256\*PEEK 16401+6, provided the character array O\$ is the first item in the variables area. This will be true if the DIM was the first DIM, FOR, INPUT, or LET statement executed since the last time you used RUN or CLEAR. You can dimension O\$ as a direct command, but you must remember to type CLEAR first. There is however one big difference between the OLD and NEW ROMs here. On the NEW ROM the value PEEK 16400+256\*PEEK 16401+6 will change during the running of your program if you have less than 32K plugged in. If you have more than 32K then you don't need to worry, but otherwise you must recalculate the expression every time you wish to access the machine code.

One last important point is that having stored machine-code in the variables area, any future use of either RUN or CLEAR will completely wipe it all out, never to be seen again. For this reason I do not advise using it for machine code storage. It WILL SAVE and RE-LOAD, again provided you never type RUN or CLEAR.



## THE STACK

There is an area of RAM that is set aside for storing various pieces of information to help the machine know what it's doing. It works like this:

The word "stack" is something that the computer people have got straight out of a dictionary. It means exactly what it sounds like! Imagine a stack of cardboard boxes. Each box is really a memory location, so each has an address, but if you want to know what's in any particular cardboard box then the only one you can easily look at is the top one. If you tried to pull one of the boxes from somewhere in the middle then all the boxes above it would fall down. Conversely, to add a new box to the stack, the only place you can easily put it is at the top.

The memory locations in the stack are just like that. You can put things on top of it, but ONLY at the top, and you can take things FROM THE TOP. There are two special words that go with the stack - one word which means "stacking a new number onto the top", and a second word that means "removing a number from the top". The first word is PUSH, and the second word is POP, so if you PUSH the number five onto the stack, and then you PUSH the number one-thousand, and then you PUSH say 16426, the first number you can POP is 16426, because this number is at the top since it was put there last. The next number to be POPped will be 1000, and then five.

The stack is stored very very high in the address, so that there is less chance of programs "colliding" with the stack as either one or the other is built up. In the old ROM the bottom of the stack is at the very top of memory - 17407 for 1K, 20479 for 4K, and 32767 for 16K. In the new ROM the whole stack moves around - the bottom of the stack is at an address stored in one of the system variables - `SPR-SP` - to be found at 16386 and 16387. The stack is actually very peculiar, because it's UPSIDE DOWN. The BOTTOM of the stack is at the TOP of available memory, and the TOP of the stack is BELOW it! It turns out to be more efficient this way. It's not actually a deliberate plot to confuse the whole human race so that the world may be taken over by ZX computers, even if it does at times seem like it. So remember - the stack, or the MACHINE STACK as it's sometimes called, is like a stack of cardboard boxes piled up on a shop floor, except that in a daring feat of defiance of Newton's laws this stack instead decides to reside on the ceiling and build up downwards. The top - the only part you can easily get at - is lower down than the bottom!

The stack is so important to the computer that a special REGISTER is set aside just to store the position of the TOP of the stack. (The part with the lowest address - the part we can get to.) That register is called SP, which stands for STACK POINTER. It is actually a register-PAIR, because it can store two separate bytes, but unlike the other register-pairs BC, DE, and HL, we CANNOT treat the two halves independently - they just won't separate.

Here's how the instructions PUSH and POP work. Suppose HL contained a value 12345. This means that it contains a value of `INT(12345/256)`, or 48, and L contains a value of `12345-256*INT(12345/256)`, or 57. Now the instruction `PUSH HL` would store the number 12345 at the top of the stack. It would do it by first of all stacking the HIGH part, and then stacking the LOW part. It would also alter the value of SP accordingly since two more bytes have been added to the stack, and the position of the top will therefore have moved (down) by two addresses.

It is unfortunately not possible to PUSH single registers onto the stack, you may only PUSH register-pairs, so BC may be PUSHed but B on its own may not. It is worth noting that the instruction `PUSH BC` will not in any way alter the value of BC, it will simply copy it without changing it. This of course goes for all PUSH instructions.

PUSH can be thought of in BASIC as a sequence of three statements:

```
PUSH HL      POKE SP-1,H
              POKE SP-2,L
              LET SP=SP-2
```

POP of course works the other way round. POP HL will first of all remove L from the stack, and will then remove H. SP will be changed, since the top of the stack will have moved.

```
POP HL       LET L=PEEK(SP)
              LET H=PEEK(SP+1)
              LET SP=SP+2
```

Verify by using the BASIC equivalents given, that `PUSH HL` followed by `POP DE` is the same thing as `LD D,H` followed by `LD E,L`.

## PUSH

Here are the codes for the instruction PUSH. One of them will require a small degree of explanation.

```
PUSH AF      F5
PUSH BC      C5
PUSH DE      D5
PUSH HL      E5
```

The register-pair AF, which cannot normally be used in this way, is made up of smaller single registers A and F, in the same way that BC is composed of B and C. A is the register which we've been using throughout the book so far, but F is something completely different. The F stands for FLAGS, and is so called because it stores the value of all the FLAGS used. (A FLAG is a memory that can only store zero or one). One of these FLAGS we've already seen - the CARRY flag. The F register has the capability to store eight flags altogether, but in fact only six of them are used. We shall see what these are, and how to use them, later on.

## POP

The codes for the POP instruction are very similar to the codes for PUSH. They are:

```
POP AF       F1
POP BC       C1
POP DE       D1
POP HL       E1
```

One of the major uses of `PUSH AF` and `POP AF` is simply to put the value of A onto the stack. The fact that F has been stacked with it is irrelevant. `PUSH AF` will conveniently store the value of A until it's needed again, at which point its value may be recovered by the use of `POP AF`. This can be useful if you have to use the A register to perform calculations of some kind that couldn't be performed by any other register, but when the value of A will still be needed later on in the program.

For example, to add twenty-five to the value of B without altering the value of any other registers:

```
F5          PUSH AF
78          LD A,B
C619        ADD A,25d
47          LD B,A
F1          POP AF
```

Why will only B and no other register be altered? (Not even the CARRY flag!) See if you can work out precisely what the above routine is doing, before you read on.

#### ALTERING SP

We can actually use SP in much the same way that we use DE and BC. We can add and subtract it, and we can load it. The hex codes are

```
LD SP,HL      F9
LD SP,nn      31
LD SP,(pq)    ED7B
LD (pq),SP    ED73
ADD HL,SP     39
ADC HL,SP     ED7A
SUB HL,SP     ED72
INC SP        33
DEC SP        3B
```

This is very powerful, and very useful. Suppose you wanted to exchange the values of D and E without altering anything else. The following routine will do just that

```
D5      PUSH DE
D5      PUSH DE
33      INC SP
D1      POP DE
33      INC SP
```

The final instruction INC SP was necessary in order to restore the Stack Pointer to its original value. If this is not done you may cause a pretty nasty crash.

SP is not the only very specialised register in use. There is another two byte register called PC, or PROGRAM COUNTER. Its job is to remember whereabouts we are in the program. Every time it has to execute an instruction it will take a look at what PC says. If it says 30004 then it will execute the instruction at location 30004, and then it will increment the value of PC by the number of bytes in that instruction, so that NEXT time round it will be looking at the next instruction in sequence. For example, if 30004 contained the instruction LD A,B then this would be carried out and PC would be increased to 30005. If the instruction at 30005 was LD A,2 then once this was carried out PC would be increased by TWO, since LD A,2 is a TWO-BYTE instruction. PC would then be reading 30007 where the next instruction begins.

If you alter the value of PC then the effect is like a BASIC GO TO. The only difference is that machine code does not use line numbers, so you have to GO TO the right ADDRESS rather than the right line number. The machine language instruction that does this job is JP, which of course is short for JUMP. JP 30000 means GO TO address 30000 and continue executing this machine code program from there. Of course all this instruction REALLY does is to load the number 30000 into register PC (but without incrementing it at the end of the instruction), so that it thinks 30000 is the next address in the program. It is far more useful for us human beings to think of it as kind of GO TO though, because that's what we're used to.

Be careful with JP though. If you create an infinite loop in machine code then TROUBLE! You're stuck with it, and what's more you can never break out unless you actually switch the machine off at the mains. Some other computers will let you break out of machine code, but the ZX81 will not, neither will the ZX80. An example of an infinite loop would be

```
77      30000      LD (HL),A
23      30001      INC HL
033075  30002      JP 30000
```

I've written the actual addresses in the middle column. Usually this isn't done, and important lines are marked with LABELS, or words which tell us which lines do what. These LABELS do not appear in the hex, and we only in fact write them for our own convenience. If for instance we decided to call the first line START then our pretty bad program could be written

```
77      START      LD (HL),A
23      INC HL
033075  JP START
```

There is another instruction similar to JP, called JR or JUMP RELATIVE. It means jump forward a given number of bytes. In many ways it is better than JP because it is only two bytes long instead of three, and because a whole routine may be RELOCATED without changing JP destinations all over the place. JR 0 has no effect whatsoever, and the next instruction will be executed in sequence, however JR 1 will cause the next instruction (assuming it to be a single byte instruction) to be skipped. To skip over a two byte instruction, or two single-byte instructions, you will need to use JR 2.

It is also possible to jump backwards using JR, since there is a convention that any hex number greater than 7F will be treated as a negative number, obtained by subtracting 256 from the number it would normally represent. To make life easier I have included a second table of hexadecimal numbers, only this time using the negative sign convention.

	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0	-128	-127	-126	-125	-124	-123	-122	-121	-120	-119	-118	-117	-116	-115	-114	-113
9	-112	-111	-110	-109	-108	-107	-106	-105	-104	-103	-102	-101	-100	-99	-98	-97
A	-96	-95	-94	-93	-92	-91	-90	-89	-88	-87	-86	-85	-84	-83	-82	-81
B	-80	-79	-78	-77	-76	-75	-74	-73	-72	-71	-70	-69	-68	-67	-66	-65
C	-64	-63	-62	-61	-60	-59	-58	-57	-56	-55	-54	-53	-52	-51	-50	-49
D	-48	-47	-46	-45	-44	-43	-42	-41	-40	-39	-38	-37	-36	-35	-34	-33
E	-32	-31	-30	-29	-28	-27	-26	-25	-24	-23	-22	-21	-20	-19	-18	-17
F	-16	-15	-14	-13	-12	-11	-10	-9	-8	-7	-6	-5	-4	-3	-2	-1

Here the number -5 is represented in hex by FB, and so it is therefore possible to use the instruction JR -5, but note that because of this convention we are unable to say JR 129 for instance, because 129 in hex is 81, which would here be taken to mean -127, and would be a jump backwards. The range we are limited to is therefore from -128 to 127.

JR 0, as we have said, does absolutely nothing. It will continue with the next instruction. It is important to remember that all relative jumps are counted from the NEXT instruction. JR 0 means execute the NEXT PLUS ZERO instruction, JR 1 means execute the NEXT PLUS ONE instruction. Consequently if we were to say JR -2 then you must count backwards for two bytes, starting at zero with the NEXT instruction. You will find that two bytes leads you to exactly the instruction we have just executed - the instruction JR -2. JR -2 is therefore an infinite loop, and is not a recommended instruction to use in a program.

The rather silly (infinite loop) program a couple of pages back can now be rewritten in one less byte using JR instead of JP.

```

77      START      LD (HL),A
23      INC HL
16FC    JR -4      or JR START

```

You have probably by now realised that JP and JR are more or less useless on their own, in the same way that the BASIC statement GOTO would be useless if it weren't for IF/THEN statements and GOTO N. We need some kind of a CONDITIONAL jump, so that we can say IF some condition is true THEN jump to a new address pq, otherwise we are virtually certain to produce an infinite loop. Although machine language doesn't have quite the same kind of flexibility as an IF/THEN statement, there are four conditions we can check for using JR, and eight conditions we can check for using JP. These are:

JR e	18	JUMP RELATIVE by e bytes.
JR Z e	28	IF the last result calculated was zero then JUMP RELATIVE by e bytes.
JR NZ e	20	IF the last result calculated was non-zero then JUMP RELATIVE by e bytes.
JR C e	38	IF CARRY=1 THEN JUMP RELATIVE by e bytes.
JR NC e	30	IF CARRY=0 THEN JUMP RELATIVE by e bytes.

and for JP:

JP pq	C3	JUMP to address pq.
JP Z pq	CA	IF the last result calculated was zero THEN JUMP to pq.
JP NZ pq	C2	IF the last result calculated was non-zero THEN JUMP to pq.
JP C pq	DA	IF CARRY=1 THEN JUMP to pq.
JP NC pq	D2	IF CARRY=0 THEN JUMP to pq.
JP PE pq	EA	see below.
JP PO pq	E2	see below.
JP M pq	FA	IF the last result calculated was negative (Minus) THEN JUMP to pq.
JP P pq	F2	IF the last result calculated was positive (Plus) THEN JUMP to pq.

Now although this is a far cry from IF A# "HELLO" THEN PRINT "GOODBYE" as you're used to, you'll soon see that even this horrendous task may be evaluated in machine code. First though I think I ought to explain about the instructions JP PE and JP PO. The P actually stands for PARITY, and the E and O mean Even and Odd. What we are doing is testing one of the flags - a flag called P/V. It's not all that difficult to understand - it works like this.

P/V stands for Parity/Overflow. V stands for Overflow because 0 is too confusing - it could mean zero or it could mean Odd (as in JP PO), so in their wisdom, and expertise at spelling, the computing boods decided to call it V. The P/V flag is a rather overworked little beast because it does two jobs at once. The first job is to check the PARITY of the last result calculated. This means you simply count the number of 1's (or 0's) in the binary form of the last result. (The binary form is always written to eight digits even if this means adding several leading zeroes.) If the number of 1's is ODD then the Parity is ODD. If the number of 1's is EVEN then the parity is EVEN.

The second job this flag has to do is to check for an overflow. If we regard numbers from 00 to 7F as positive, and from 80 to FF as negative (as described in the section on JR) then an overflow happens if the "sign" is changed accidentally. For example 41 (positive) plus 41 (positive) equals 82 (which is negative). This is an overflow, but note this is NOT a CARRY. JP PE in this case means JUMP if there has been an overflow, and JP PO means JUMP if there has not been an overflow.

The various tests, if combined with other instructions properly, can really check for any situation conceivable. In fact there's only one other kind of instruction you need in order to make JP and JR as powerful as IF/THEN/GOTO - that instruction is CP, or COMPARE.

CP will compare the register A with any other register, or with any constant number. It will do this by working out what would happen if that register or number were to be subtracted from A. It will not alter the value of any of the registers, but it will alter all of the flags. The conditional JP and JR instructions work by checking the value of the flags. Apart from the carry flag, some of the other flags are the sign flag, which stores a one if the last calculation was negative, and a zero if the last calculation was positive; the zero flag, which stores a one if the result of the last calculation was zero, and a zero otherwise; and the parity flag, which stores a one for parity-even, and a zero for parity-odd. Although this may sound complicated you don't actually remember any of it, as long as you know how to use CP.

If A=B THEN GOTO pq is quite easy to represent in machine code. It is CP B followed by JR Z,e. CP B will compare B with A (CP always compares with A, so that CP A is meaningless) which is done by working out A-B. The result isn't stored in any of the registers, so A and B both remain unchanged. The next instruction JR Z,e, will only jump if the result A-B is zero - in other words if A equals B.

IF A<B THEN GOTO pq may be achieved in machine code in two ways. The first instruction is CP B which will compare B with A by performing A-B. Now if A is less than B then A-B will be negative, and so you could well use JP M pq, but you could also do it in another way which will allow you to use JR instead of JP, since if A is positive, and A-B is negative, then there will be a carry, and so you may use the instruction JR C,e. Of course this will not work if A was "negative" (ie in the range 80-FF) to start with unless subtracting B caused another overflow by going through 00. This could not happen unless B was in the range 80-FF as well.

#### CALLING...

Even in machine code we can have subroutines. COSUB the routine starting at address pq is CALL pq. RETURN is RET. This particular instruction should look very familiar, since it is the very same RET that we've been using to get back to BASIC at the end of a routine. This is because every SUB routine is really a SUBROUTINE, even though we consider it as a program in its own right. Unfortunately there's no such thing as a CALL RELATIVE instruction, as there is with JUMP, so CALL must always be a three byte instruction. In exactly the same way as with JP we can impose IF/THEN conditions, which work in precisely the same way and are written with the same letters to define the conditions. These are:

CALL pq	0D	RET	C9
CALL Z pq	0C	RET Z	C8
CALL NZ pq	C4	RET NZ	C0
CALL C pq	DC	RET C	D6

CALL NC	D4	RET NC	D0
CALL PE	D2	RET PE	E8
CALL PO	E4	RET PO	E0
CALL N	FC	RET N	F8
CALL P	F4	RET P	F0

As you may or may not have guessed, instructions like RET Z (return if zero) can also be used to end a machine code routine, ie IF RESULT 0 THEN RETURN to BASIC.

It is very important however that the value of SP is not altered during a subroutine, since the instructions CALL and RET both use the stack. CALL works by PUSHing what would have been the next address to be executed onto the stack, and RET works by POPping the first item on the stack. Thereafter both of these instructions act exactly like JP. Therefore it is possible to alter the RET address, should you need to, by POPping the first item on the stack (the previous RET address) and then PUSHing a new address. For example, to change the RET address to 20000 you could use the sequence

```

E1      POP HL
21204E  LD HL,20000
E5      PUSH HL

```

Another useful trick is to store the value of the stack pointer somewhere at the start of a subroutine, and then retrieve it at the end. On the new ROM a good place to store this value is the address 16507 because neither this nor 16508 are used at all by the ROM - it is the two "spare" bytes between the system variables and the program. On the old ROM you don't have this spare space, but you can overwrite some of the other systems variables, for example the frame counter at address 16414. The advantage of doing this is that you can PUSH and POP to your heart's content and still be sure of a safe RETURN.

```

At the start of a subroutine:
ED737B40      LD (16507),SP
and at the end of a subroutine:
ED737B40      LD SP,(16507)
C9            RET

```

#### EXERCISES

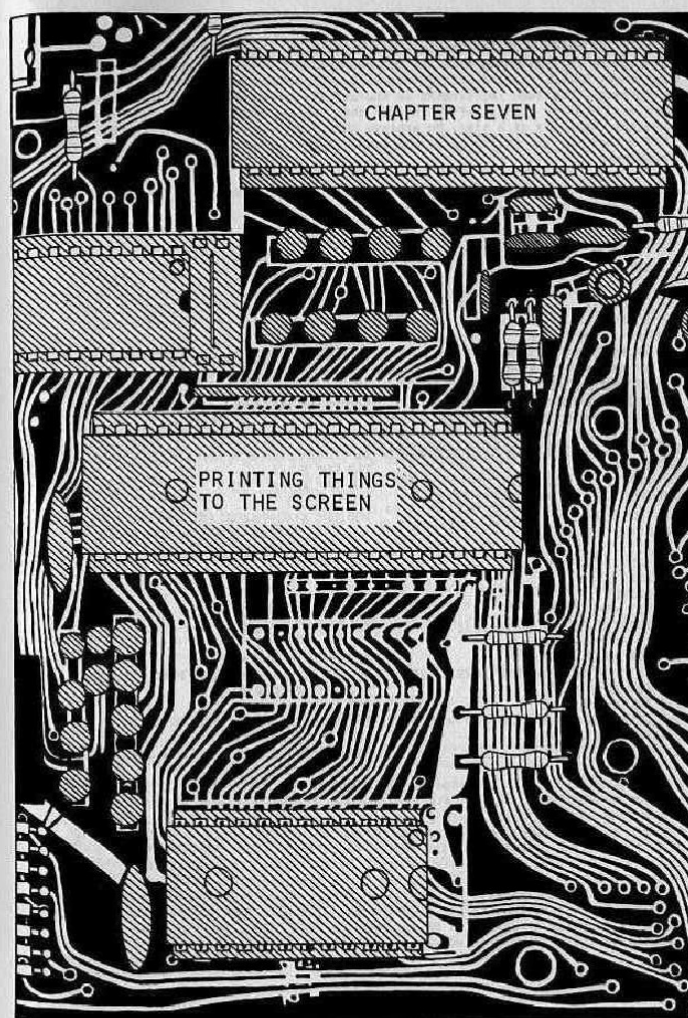
To make sure you have understood using the stack, and conditional jumps, write a program which will PUSH every number between one and fifty onto the stack (using PUSH AF) and then somehow manage to successfully return to BASIC. (HINT: CP 32 (Compare with 32 (hex) (50 decimal)) is quite a useful instruction here.

You'll need to know the various codes for CP. These are as follows:

CP A	BF	CP E	BB
CP B	B8	CP H	BC
CP C	B9	CP L	BD
CP D	BA	CP (HL)	BE

CP n    FEnn

In the next chapter we'll begin loading a program which is designed to play a game of draughts. Now don't worry if this sounds rather complicated - I did say we'd begin loading it. I'm afraid you won't get the whole program until you've nearly completed the whole book, so keep a cassette handy reserved just for this program, and you can reSAVE it at each new stage. You'll need at least AK for this.



In order to write a program as extensive as draughts, we'll need a fairly powerful BASIC program in order to help us load it. The following is a second version of HEXLID - called HEXLID2 - which has a couple of improvements over its predecessor. One such improvement is the ability to input strings of characters such as "To be or not to be" which will then be incorporated in the machine code one character at a time. To achieve this you must input "TO BE OR NOT TO BE;" - that is, the text must be surrounded by semicolons - this is very important.

HEXLID2 lists as follows. OLD ROM users should use the version on the left, and NEW ROM users the version on the right.

OLD ROM	NEW ROM
10 PRINT "WRITE TO ";	10 PRINT "WRITE TO ";
20 INPUT A\$	20 INPUT A\$
30 PRINT A\$	30 PRINT A\$
40 GOSUB 200	40 GOSUB 200
50 PRINT	50 PRINT
60 LET A\$=""	60 LET A\$=""
70 IF A\$="" THEN INPUT A\$	70 IF A\$="" THEN INPUT A\$
80 IF A\$="S" THEN STOP	80 IF A\$="S" THEN STOP
90 IF CODE(A\$)-215 THEN GOTO 300	90 IF CODE(A\$)-25 THEN GOTO 300
100 PRINT CHR\$(CODE(A\$));	100 PRINT A\$(2 TO 2); "two spaces";
CHR\$(CODE(TL\$(A\$)));	
"two spaces";	
110 POKE X,16*CODE(A\$)+CODE(TL\$(A\$))+36	110 POKE X,16*CODE A\$+CODE A\$(2)-476
120 LET X=X+1	120 LET X=X+1
130 INT A\$=VAL(TL\$(A\$))	130 LET A\$=A\$(3 TO )
140 GOTO 70	140 GOTO 70
200 LET X=0	200 LET X=4096*CODE A\$+256*CODE A\$(2)
210 FOR I=1 TO 4	+16*CODE A\$(3)+CODE A\$(4)
220 LET X=X+CODE(A\$)-28	-12332
230 LET A\$=TL\$(A\$)	210 RETURN
240 NEXT I	
250 RETURN	
300 LET A\$=TL\$(A\$)	300 LET A\$=A\$(2 TO )
310 PRINT " ";CHR\$(CODE(A\$));	310 PRINT " ";A\$(1); "two spaces";
"two spaces";	
320 POKE X,CODE(A\$)	320 POKE X,CODE A\$
330 IF CODE(A\$)-226 THEN POKE X,118	330 IF CODE A\$=216 THEN POKE X,118
340 LET A\$=TL\$(A\$)	340 LET A\$=A\$(2 TO )
350 LET X=X+1	350 LET X=X+1
360 IF NOT CODE(A\$)-215 THEN GOTO 310	360 IF CODE A\$=25 THEN GOTO 310
370 LET A\$=TL\$(A\$)	370 LET A\$=A\$(2 TO )
380 GOTO 70	380 GOTO 70

This program is basically the same as HEXLID except for two features. Firstly you are required to input the starting address (in hexadecimal) at which the machine code is to be loaded, and secondly it will allow you to input strings of data using their character codes, rather than hex - this is what the routine starting at line 300 is for. If you input "CDB080C9" it will be interpreted as CALL 0808 followed by RET - this is exactly the same as before - however if you instead input "LN graphic A graphic A TAN;" it will mean exactly the same thing. If you compare character codes with hexadecimal by looking it up in the manual you'll find the hex for LN is CD, hex for graphic A is 0A, and hex for TAN is C9. The semicolon is used to tell the program where the data starts and ends.

Let's look at some uses for this. Perhaps the most useful subroutine we could imagine would be one which prints a string of characters to the screen. There is already a subroutine in the ROM which will print a single character. Try this program. Load it to address 4E00. (If you only have 1K you'll have to find some other suitable address).

OLD ROM	NEW ROM		
CDE006		START	CALL PRPOS (OLD ROM only)
3E94	3E97		LD A,inverse asterisk
CD2007	CD0808		CALL PRINT
3A2540			LD A,(S.POSN) }
3D			DEC A }
08			RET Z }
18F1	18F9		JR START

You'll discover upon running it that the screen fills up with inverse asterisks, and that it fills up very, very fast. (Much faster than PRINT "inverse asterisk"/RUN). The ROM subroutine PRINT will place the character whose code is stored in the A register at the current PRINT position on the screen. In the new ROM, locating the print position is automatic, but in the old ROM you have to call up a completely different subroutine - PRPOS (Print Position) - first, in order that the second subroutine, PRINT, knows where to place the image on the screen. PRPOS wipes out the value of the A register, but PRINT does not. Note that OLD-ROM-PRINT, and NEW-ROM-PRINT, work by two completely different methods, even though we are using them in precisely the same way, except that for the OLD ROM we have to check for end-of-screen.

It is in fact possible to put this entire program into a 1K statement. NEW ROM users with only 1K might like to try clearing the machine with NEW and then typing line 1 REM Y inverse asterisk LN graphic A graphic A / RAND (You'll need to type THEN RAND and delete the word THEN to get the word RAND in position) This is precisely the above program, but entered direct from the keyboard instead of loaded via a separate program. Now the command RAND USR 16514 will almost instantly fill the screen! Shock - Horror - A full screen in 1K!!!

What we want though is a subroutine which can print any message, from "YES" to "OH WHAT A BEAUTIFUL MORNING". Suppose such a subroutine exists and it's called SPRINT (String Print). We want to be able to use an instruction something along the lines of CALL SPRINT WITH "OH WHAT A BEAUTIFUL MORNING". Here's how it will work:

CD????	CALL SPRINT
2D2A513134	DEFM HELLO
FF	DEFB FF

Here DEFM means Define Message. It's not actually a machine language instruction, but is used to specify data within a program. If you look at the hex equivalent you'll see that 2D is hexadecimal for the character code of H, 2A for E, 31 for L and 34 for O. DEFB is also data - it means define byte. We could have put DEFB 09 and it would have meant the byte 09. Here we are using it to specify the end of the data to be used by SPRINT. We must ensure, however, that the machine does not try to execute these bytes, since in machine language terms they don't make a great deal of sense. Let's take a look at how we could go about writing such a subroutine as SPRINT which at the same time ensures that we don't try to execute the data (is the word "HELLO" and the byte FF)

You may remember from the last chapter that CALL works by PUSHING the return address onto the stack and then jumping to the required address. RET works similarly - it POPs an address from the stack and then jumps to it. Therefore if the word "HELLO" immediately follows a CALL instruction then the address at the top of the stack will be the address of the first character of data - the "H" - we can obtain this with the single

instruction POP HL. If we then increment HL by one and PUSH it back onto the stack then the effect of the next RETURN will be to jump back to the NEXT address in line - the "E". We can test for the end of the data by looking for the byte FF (which is not a printable character). Follow this subroutine through.

OLD ROM	NEW ROM		
E1	E1	SPRINT	POP HL
7E	7E		LD A,(HL)
23	23		INC HL
E5	E5		PUSH HL
FEFF	FEFF		CP FF
C8	C8		RET Z
F5			PUSH AF
CD8006			CALL PRPOS
F1			POP AF
CD2007	CD0808		CALL PRINT
18EF	18F4		JR SPRINT

} OLD ROM ONLY

The first four lines are designed to look at the character stored at the current return address and then increment the return address. The next two lines will only return from the subroutine if the byte FF has been found. Note that CP FF will compare A with FF, not HL which was the last thing referred to. CP will always compare A with something - in this case the hex value FF. The RET instruction (actually a RET Z or return if zero, but it works in precisely the same way) will, if you examine the listing closely enough, return you to the byte AFTER the FF, not to the FF itself. Finally, if FF has not yet been found, the subroutine PRINT will be called and the single character now in the A register will be printed to the screen. The whole routine will then be repeated over and over again until the end of the message is found.

Enter the program HEXLD2 to enable you to load machine code. Add an additional line to it - line one - which should be a REM statement with fifty arbitrary characters after the word REM. OLD ROM users must ensure that this line is never listed, LIST 9999 followed by LIST 2 will ensure this. Now RUN the program. The message WRITE TO will greet you. Input "402B" for the OLD ROM, or "4082" for the NEW ROM. This is the address, in HEX, of the first character after the word REM. When prompted type in the following - (here / means newline) - E1/7E/23/E5/FEFF/C8/ (old ROM users only should type F5/CD8006/F1 ) CD2007 or CD0808/18EF or 18F4/CD2B40 or CD8240/;OH WHAT A BEAUTIFUL MORNING;/FF/C9. The last four lines were CALL SPRINT (Notice how the two bytes of the address have been switched around), DEPM OH WHAT A BEAUTIFUL MORNING, DEF9 FF, and RET.

Now do you see the purpose of the BASIC routine in HEXLD2 which begins at line 300. Imagine how tedious it would have been to have had to type in 342D003C2E263900... and so on instead of ;OH WHAT A BEAUTIFUL MORNING; it has exactly the same effect. Now type in as a direct command RANDOMISE USR (16444) (OLD ROM) or RAND USR 16526 (NEW ROM) and what happens?

We shall use this routine to print a draughts board for us. You'll need at least 4K to load this program, but once loaded it will quite happily fit and run in 1K. If you only have 1K altogether it might be an idea to try and borrow some memory from somewhere, and then give it back only once you've got the whole of draughts in - but be warned - the listing is spread very thinly throughout the whole of the book.

If you take a look at line 330 of HEXLD2 you'll see that every time you input a double-asterisk (\*\*) it will automatically be changed into a newline. This is a point of convenience. We can input a newline if we want, by just deleting the quote marks at the input prompt and instead typing CHR\$(118), but it is far simpler, and far more convenient, to only have to type shift-H. If of course you ever need two asterisks in a row you can always type a single asterisk twice.

The next machine code program forms the very first part of IRAUGHTS. It is the routine which enables us to print the playing board. For the OLD ROM we shall begin loading this program such that the first address used is 4C04. For the NEW ROM the first address will be 4C09. NEW ROM users should remember (or write down) the sequence of BASIC commands

POKE 16389,76  
NEW

which should be typed in BEFORE HEXLD2 is entered. Now enter the following machine code. WRITE TO 4C04 (OLD) or 4C09 (NEW).

	SPRINT	POP HL	
E1		LD A,(HL)	Increment the return
7E			address.
23		INC HL	
E5		PUSH HL	
FEFF		CP FF	Return if no more text.
C8		RET Z	
F5		PUSH AF	
CD8006		CALL PRPOS	} OLD ROM ONLY
F1		POP AF	
CD2007/CD0808		CALL PRINT	Print one character of
18EF/18F4		JR SPRINT	the text at a time.
CD044C/CD094C	CALL SPRINT		Print the draughts
			board.
001E1E1F202122232476	DEPM	12345678	Data for
1D0C0C0C0C0C0C0C0C1D76		1 W W W W 1	the SPRINT
1EEC0C0C0C0C0C0C0C01E76		2 W W W W 2	subroutine.
1F0C0C0C0C0C0C0C0C01F76		3 W W W W 3	
208C0C0C0C0C0C0C0C02076		4 - - - 4	
21080C0C0C0C0C0C0C02176		5 - - - 5	
22A700A700A700A7002276		6 A B B B 6	
2300A700A700A700A7002376		7 B B B B 7	
24A700A700A700A7002476		8 B B B B 8	
001D1E1F202122232476		12345678	
76			
76			
76			
00000000000000000000000000000000			
FF			End of data.
C9			Return to Basic.

The command RAND USR 19477 (The address of the CALL SPRINT instruction) will produce a complete draughts board picture on your screen almost instantly. Try it.

There is now one thing left to rectify - that is, we cannot as yet SAVE machine code that is stored high in memory. We shall now learn how to do so. Add the following lines:

# OLD ROM

```
500 PRINT "4000 TO ";
510 INPUT A$
520 PRINT A$
530 GOSUB 200
540 LET Y=(X-19454)/2
550 DIM O(Y)
560 FOR X=1 TO Y
570 LET A=PEEK(19455+2*X)
573 IF A>127 THEN LET A=A-256
576 LET O(X)=PEEK(19454+2*X)+256*A
580 NEXT X
590 SAVE
600 FOR X=1 TO Y
610 POKE 19454+2*X,O(X)
615 POKE 19455+2*X,O(X)/256
620 NEXT X
630 CLEAR
640 STOP
```

# NEW ROM

```
500 PRINT "4000 TO ";
510 INPUT A$
520 PRINT A$
530 GOSUB 200
540 LET Y=X-19456
550 DIM O$(Y)
560 FOR X=1 TO Y
570 LET C$(X)=CHR$(PEEK(19456+X))
580 NEXT X
590 SAVE "inverse space"
600 FOR X=1 TO Y
610 POKE 19456+X,CODE C$(X)
620 NEXT X
630 CLEAR
640 STOP
```

Now, to SAVE your machine code type RUN 500. At this stage enter 4040. It doesn't actually matter which address you give it, so long as this address is larger than the last address of machine code. (So far the last address happens to be 4036).

The program will then SAVE automatically (line 590). Incidentally if you're wondering why I've put SAVE "inverse space" in the NEW ROM version try instead using SAVE "space" and see what happens to the line. When you LOAD the program back, OLD ROM users will need to type GOTO 600 before doing anything else. NEW ROM users won't because the program will continue automatically. Here's how the program works: An array of sufficient size to hold all the bytes to be saved is dimensioned in line 550, after which the machine code is copied into this array and SAVED. The routine at 600 does the reverse - it copies the machine code from the array up to the required address.

## AND....

We leave draughts for the moment in order to introduce a few more machine language instructions which we'll need in order to continue with the program. The first of these is AND. Unfortunately for sanity the word AND doesn't mean quite the same thing as it does in BASIC. We're all used to seeing expressions like IF X=1 AND Y=1 THEN... In machine code however we use the word in a completely different context. For example AND B is a complete machine code instruction. So is AND (HL) or AND FO. In order to see how it works it is necessary to take a brief look at numbers in BINARY.

BINARY is yet another form of counting - like decimal or hex. Decimal makes use of the digits 0, 1, 2, 3, 4, 5, 6, 7, 8 and 9. Hex uses A, B, C, D, E and F as well. Binary on the hand uses only the digits 0 and 1. Converting from hex to binary is very simple - much simpler than changing from decimal to hex - simply convert each digit one at a time from this table:

HEXADECIMAL	HEXADECIMAL	BINARY	BINARY
0	0000	0	1000
1	0001	9	1001
2	0010	A	1010
3	0011	B	1011
4	0100	C	1100
5	0101	D	1101
6	0110	E	1110
	0111	F	1111

Therefore C9 (hex) is the same as 110011001 (binary). Can you see how the binary splits up into two halves, 1100 (C) and 1001 (9)? The same is true of all numbers. What is 1E (hex) in binary? What is 01100111 in hex? Now see if you can work out what 123 (decimal) is in binary. (Hint: convert to hex first)

AND assigns a new value to the A register. This new value is determined by a) the previous value of the A register, and b) the value written after the word AND in the instruction. Suppose A contains 5A, and B contains 1F, and the computer then comes across the instruction AND B. Here's how the new value is calculated:

```
A 01011010
B 00011111
new value 00011010
```

as you can see, the digits of the new value are zero if there is a zero in the corresponding position of either or both of the old values, and a one if both the old values contained a one in that position. To make this clear just look at the columns - you'll see that in all cases two zeroes lead to a zero, two ones lead to a one, and a mixture of zeroes and ones lead to a zero. The function is called AND since a one is only obtained if A AND B have a corresponding one. It may appear to you to be rather a useless function, but it is in fact one of the most widely used machine language instructions there is. Some examples of its use are:

AND A leaves A unchanged, but resets the carry flag.  
AND 7F if A contains a printable character, prevents it from being inverse - both of these examples we shall make use of.

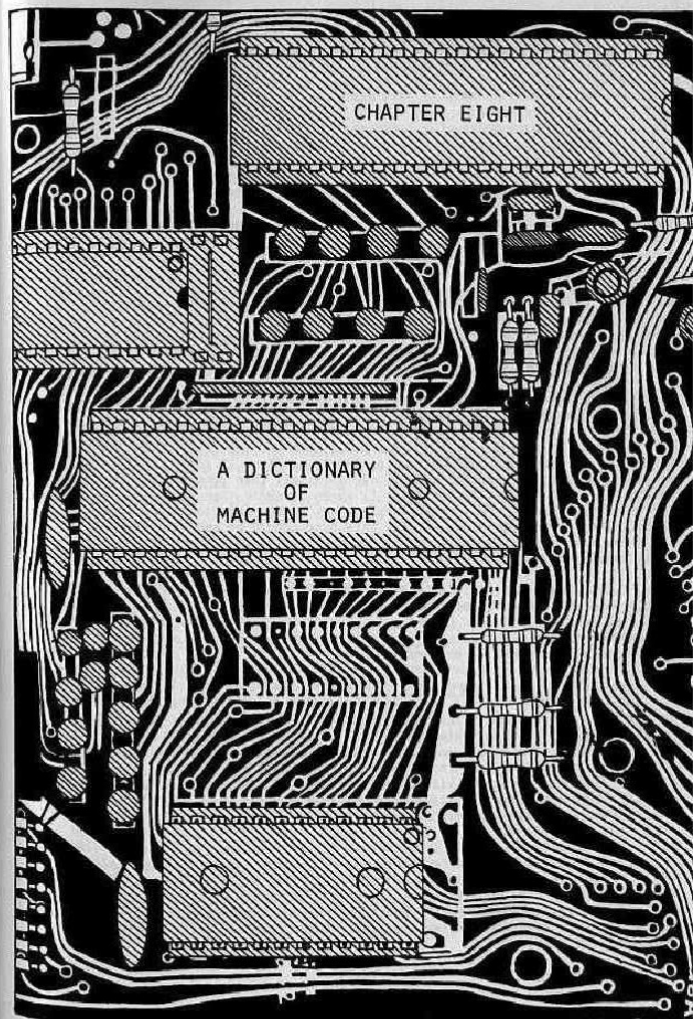
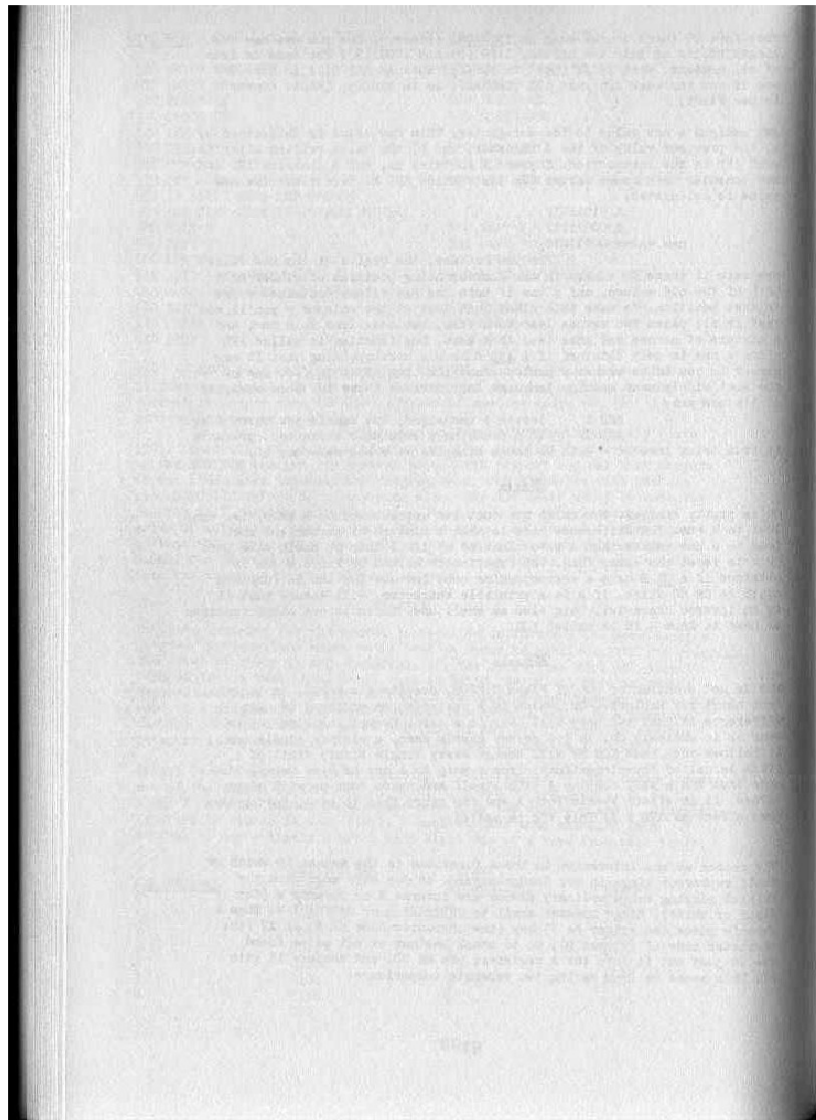
## OR....

OR is pretty similar. The rules are that two zeroes lead to a zero, two ones lead to a one. The difference here is that a mixture of zeroes and ones lead to a one rather than a zero. Instead of AND A then we could have used OR A to reset the carry flag. The function is called OR since a one is obtained if A OR B have a corresponding one. One use for the OR function could be OR 80 which, if A is a printable character, will ensure that it is an inverse character. This also we shall use. There is one other function we need to know - it is called XOR.

## XOR....

XOR is not a character out of Flash Gordon, despite its sound, it is in fact short for Exclusive-OR, which is a variation on ordinary OR. Its difference is that two ones will lead to a zero. Everything else is the same as in ordinary OR, ie two zeroes equals zero, a mixture equals one. It follows then that XOR FF will change every single binary digit of A (this is called "complementing") from a zero to a one or vice versa. Also note that XOR A will combine A with itself and hence come up with eight zeroes. It in effect resets both A and the carry flag to zero, having the same effect as SUB A,A. This too is useful.

The reason we are interested in these functions is the manner in which we shall represent kings in our draughts game. As you have seen from the initial playing board ordinary pieces are inverse B or inverse W (for Black or White). Kings however shall be ORDINARY B or ORDINARY W. Thus a human's piece can either be 27 hex (the character code of B) or A7 (the character code of inverse B), so to check whether or not we've found one we just put it into the A register, use OR 80, and compare it with A7. This saves us from making two separate comparisons.



### SPECIAL REGISTERS

The Z80 has two special registers which can be made use of. The first is called IX.

It is special because as well as just assigning it, as it can be used just like any other register pair with LD IX,0000 for instance, we can use it to find the contents of an address - using (IX) - just like we can with (HL). IX is different because we can add a constant to the address. Thus LD B,(IX+7B) works! If IX were 0000 then LD B,(IX+7B) will load B with the contents of memory location 007B. In no other way can we assign a single register from an address in one instruction.

There is a warning that goes with using IX though. If you are using SLOW then you must not alter the value of IX at all, otherwise you might cause a crash.

The other special register is called IY. It is used in exactly the same way as IX, except that the ROM itself gives us an added advantage. When you jump into a machine language routine, IY starts off as 4000 (hex), so that all of the system variables may be accessed directly. (The system variables start off at 4000.) For example, LD L,(IY+0C) will load L with the low part of the address at which the display file begins.

Changing the value of IY will not cause a crash. It will be reset to 4000 as soon as you return to BASIC. This is done automatically by the ROM.

To find the hex code of any instruction involving IX or IY pretend you are using HL instead and look up the code for that. Then precede it by DD for IX, or ED for IY. If the IX or IY is in brackets then it must have a displacement, even if that displacement is 00. (For instance, in LD B,(IY+04) the displacement is 04.) This byte should be added to the hex code, and should be the third byte of the code, even if this means splitting the original code in two.

Thus if the code of LD (HL),44 is 3644, then the code of LD (IX+20),44 is DD562044. Note how the displacement 20 has been inserted into the middle of the original code in order to make it the third byte. We have now reached the stage of using four byte instruction codes. This is the longest a Z80 instruction can possibly be.

### THE FLAGS REGISTER

Another special register is the FLAGS register, sometimes called the STATUS register. Usually it abbreviates itself to just F, and cohabitates with A in the hope that no-one will notice it. Its purpose is to store various bits of information about the results of calculations. Some instructions will alter all of the flags, some will alter only some of them, and some won't actually alter any flags at all. A complete list of what instruction does what is included in an appendix at the back of this book.

As for the register itself, it is, like any other register, eight bits in length, but each bit has a different purpose (although two of them aren't used). These bits are each used as an individual flag which can store a value of either zero or one. The flags are, from left to right; Sign, Zero, not-used, Half-carry, not-used, Parity/Overflow, Subtract, and Carry. The two unused flags are both more or less random, but the rest are quite specific. They work like this:

The SIGN flag stores the sign (positive or negative) of the last result. A positive number resets this flag to zero, and a negative number sets it to one. For the purposes of this flag, zero is counted as positive. The value of the S flag is therefore always equal to the leftmost bit of the result. It may be tested using instructions like JP P (Jump if positive) or JP M (Jump if negative (Minus)).

The ZERO flag checks whether or not the last result was actually zero. If so the flag is set to one, but otherwise it is reset. Watch out for this flag though - it can be very deceiving - many of the register-pair instructions simply do not change it as you'd expect: instructions like DEC or ADD for instance will only change the zero flag if applied to single registers. You are advised to check with the appendix if you are unsure.

The HALF-CARRY flag is set if there is a carry from bit 3 into bit 4, or, in the case of register-pairs, from bit 11 into bit 12. It is used internally by the Z80 for such instructions as DAA, but cannot easily be tested by the programmer. It is possible to examine it using the sequence PUSH AF/POP BC/ BIT 4,C and then testing the zero flag, but this is rarely done.

The PARITY/OVERFLOW flag does two jobs at once. The PARITY of a result is either odd or even, depending on the number of ones in the result (when written in binary). The Parity flag is assigned in exactly the opposite manner to that which you'd expect. If the parity is even, the flag is one (an odd number), and if the parity is odd, the flag is zero (an even number). The following instructions assign this flag according to the parity of the result: AND r, OR r, XOR r, RL r, RLC r, RR r, RRC r, SLA r, SRA r, SRL r, RLD, RRD, DAA, and IN r,(C). An OVERFLOW represents an "accidental" change of sign of the result - a carry from bit 6 into bit 7 effectively. The following instructions assign this flag according to whether or not we have an overflow: ADD A,r, ADC A,r, ADC HL,s, SUB A,r, SBC A,r, SBC HL,s, CP r, NEG, INC r, and DEC r.

The subtract flag, also called the N flag, simply lets the machine know whether or not the last instruction was an addition, or a subtraction. You can't get hold of this flag unless you make use of PUSH and POP as I've described under HALF-CARRY, but in general you'll know what the last instruction was anyway. This flag is primarily used internally by the Z80 for instructions such as DAA.

The CARRY flag you know about. It detects a carry from bit 7 into (the non-existent) bit 8, or in the case of register-pairs, from bit 15 into what would have been bit 16. It is also assigned by shift and rotate instructions, in which one bit is "lost" from a register and moves into the carry. This is probably the most frequently accessed flag of all.

### ALL THE INSTRUCTIONS

By now we've seen a fair number of Z80 instructions, so you'll be wanting to expand your vocabulary of these. Here now is a detailed list of all of the instructions that are available to you. I shall cover them in alphabetical order so that you may use this chapter as a kind of dictionary of instructions. For precisely the same reason I shall re-cover the ones you've already seen. You should reread them anyway since it will prove a useful memory aid.

**ADC** Starting with ADC. It comes in two forms: ADC A,r and ADC HL,s. Here we are using r to stand for either A, B, C, D, E, H, L, a numerical constant, or an address pointed to by either (HL), (IX+d) or (IY+d). s stands for one of the register pairs BC, DE, HL, SP, IX, or IY. ADC A,r is a single byte instruction. It calculates the sum A plus r plus the carry flag. The result is stored in A. ADC HL,s is a two byte instruction which evaluates HL plus s plus the carry flag, and stores the result in HL. Can you see why (ignoring the flags) ADC A,A does precisely the same job as RLA? ADC alters all of the flags.

**AND** Very similar to ADC except that the carry flag is not used in the initial calculation. It is however still altered by the final result. There are one or two important differences between AND and ADC however. Firstly the set of instructions ADD HL,s (where s means the same as it did in ADC) are one byte instructions rather than two, and secondly it is permissible to use two further sets of instructions ADD IX,s and ADD IY,s. Altering the value of IX however is not advisable if you are using SLOW IY may be safely altered but will always be reset to 4000 (hex) on return to BASIC.

**AND** Only one form here - AND r. The value of the A register is altered one bit at a time. If such a bit is zero it will be unaltered. If a bit is one it will take on the value of the corresponding bit of r. Thus AND 00 is always zero, AND FF will leave A unchanged. AND alters all of the flags - specifically the carry flag will always be reset to zero.

**BIT** Now this is a new one. What happens is that from time to time you'll want to know whether an individual bit of some register is one or not, but for some reason or other it becomes impractical to try and rotate or shift it into the carry. BIT is specially designed to help you out here. Suppose you wanted to know the value of BIT 5 of B. The instruction is simply BIT 5,B - the result is then either zero or non-zero, which you can exploit using JR Z for instance, or RET NZ. BIT does not alter the value of ANY of the registers, nor does it change the value of the carry flag. Its hex codes are listed in a table at the end of this book - it is a two-byte instruction. I tend to find it's not used very often, but when it is used it comes in very handy indeed.

**CALL** You've seen this one before - it's rather like GOSUB. Its exact function is as follows: PUSH the return address onto the stack, and JUMP to the call address. The return address is used by the RET instruction so it is vitally important that a subroutine should not alter the stack. You may only push things onto the stack in a subroutine if you pop them off again before you attempt to return. CALL may also be used with conditions - for example CALL Z,pq (pq is an absolute address) which means CALL pq if the last calculation was zero, otherwise continue with the next instruction.

**CCF** Complement carry flag. If the carry flag was zero then change it to one. If it was one then change it to zero.

**CP** In the form CP r it will calculate the result of subtracting r from A, however the answer NOT stored anywhere, nor is the previous value of either A or r altered. It will on the other hand alter all of the flags, so conditions like jump if zero, or jump if carry, will still work. CP r followed by JR Z will jump if A equals r.

**CPD** Imagine this as CP (HL), followed by DEC HL, followed by DEC BC. The zero flag is altered as if a single CP (HL) instruction had been executed. Another flag altered is the P/V flag, which works as follows: if BC decrements to zero then the P/V flag is also zero. If BC does not decrement to zero then the P/V flag is set to one. Thus JP PC will jump only if BC now equals zero. JP PE will jump only if BC is not now equal to zero. The carry flag is not altered at all by this instruction.

**CPDR** Basically this is the same as CPD except that the instruction is executed over and over again - a kind of automatic loop. CPDR stands for compare with Decrement and Repeat. The loop will end in one of two cases. a) if A equals (HL) - in which case the zero flag will be set, or b) if BC reaches zero - this will affect the P/V flag as in CPD. If neither of these conditions is true the instruction is re-executed.

**CPI** As CPD except that HL is incremented instead of decremented.

**CPDR** As CPDR except that HL is incremented instead of decremented.

**CPL** An abbreviation for complement. The register A is altered bit by bit. If any particular bit starts off as zero it is changed to one and vice versa. In other words if A starts off as 11010101 (binary) the instruction CPL will change it to 00101010 (binary). The flags are not altered, nor are any of the other registers.

**DAA** Suppose you wanted to add 16 (decimal) to 26 (decimal) without converting them to hex. The following seems plausible: LD A,16 then ADD A,26. Unfortunately, because the machine works in hex the final value of A will be 3C, not 42. The instruction DAA (Decimal Adjust accumulator) will change A from 3C to 42. How it works is rather complicated - it makes a note of what's been carried where and whether you've added or subtracted and so on - but it does always work. For instance the sequence LD A,42 then SUB A,06 will again leave A with 3C, but this time round DAA will change A to 36, since 42 (decimal) minus 6 (decimal) is 36 (decimal). The instruction changes every flag appropriately.

**DEC** This is another one of those instructions that comes in two forms. It can be dec r (a single register) or dec s (a register pair). dec r is very simple to understand - the value of the register r is decreased by one, the carry flag is unaltered, and the zero flag is changed appropriately. Dec s is the one you want to watch for, because the zero flag is NOT ALTERED! Nor are any of the other flags! Thus DEC BC followed by JR NZ,-3 is either an infinite loop or has no effect! You'll have to be very careful to remember this - a lot of my earlier programs crashed because I didn't.

**DI** Not a Welsh name, nor is it short for Diane or Diana. It is in fact an abbreviation (surprise! surprise!) It stands for Disable Interrupts, and although this sounds pretty confusing its use is immensely simple. An interrupt is what you get if you send little bleeps into the pins of the Z80 chip. DISABLING the interrupts means that if such a thing happens in future it is to be ignored. That's about all I can tell you I'm afraid - you'll have to consult the hardware boffs for a more detailed explanation.

**DJNZ** Yet another abbreviation - this time for Decrement B and Jump-Relative if Not Zero. So if B is 7, DJNZ will reduce it to 6. If B is zero, DJNZ will change it to FF. If B is one however, DJNZ will change it to zero, and will then jump to a new destination. The form of the instruction is DJNZ e, where e is a single byte. If B is not decremented to zero the e is ignored, if it is then e specifies how far to jump. If e is between 00 and 7F then the jump is FORWARDS, if e is between 80 and FF then the

jump is BACKWARDS (with  $FF-1$ ,  $FE-2$ , and so on). Start counting from the next instruction, so that  $DWZ 00$  is just the same as  $DEC 3$ , except that  $DWZ$  does not alter any of the flags.

**EI** Guess what? Another abbreviation. **EI** stands for Enable Interrupts, and is the opposite of **DI**. From now on, if the Z80 receives an interrupt, then execution of the current instruction is completed, and control then jumps to an interrupt routine. For a slightly better explanation look under **IM**.

**EX** At last - an instruction with a sensible name. **EX** means exchange. There are five different **EX** instructions - these are **EX AF,AF'**, **EX DE,HL**, **EX (SP),HL**, **EX (SP),IX**, and **EX (SP),IX**. They don't alter any of the flags. What they do is, as you'd expect, swap the values over - thus **EX DE,HL** replaces **DE** by the value **HL** used to contain, and **HL** by the value **DE** used to contain. The last three are rather interesting - the old value of **HL** (or **IX** or **IX**) is pushed onto the stack, but simultaneously the old value at the top of the stack is popped and loaded into **HL**. The position of the stack pointer is therefore unchanged. **AP'** (Pronounced **AP dash**) is a register pair distinct from the real **AF**, and this is the only instruction which uses it. It is used by the **SLOW** hardware, so don't use **EX AF,AF'** while you're in **SLOW**.

**EXX** As well as **AF'** there are also **BC'**, **DE'** and **HL'**, which are just a set of six new registers (or three new register pairs) which can only be accessed by this one single instruction. **EXX** is an exchange instruction. It means exchange **BC** with **BC'** (ie **B** with **B'** and **C** with **C'**), **DE** with **DE'**, and **HL** with **HL'** - all in the same go. This is quite safe, and does not affect **SLOW** in the way that **AF'** does. It is useful for preserving the values of the registers when calling a ROM subroutine which relies upon **A** but wipes out the other registers, eg **EXX/CALL ROM-SUBROUTINE/EXX**. The previous values of **BC**, **DE**, and **HL** are now unchanged. Some of the programs later on in this book will make use of this technique.

**HALT** Don't be fooled by your own intuition - this isn't the same as **STOP**. It means do nothing, or wait forever. Once you hit a **HALT** instruction it will just sit there, effectively executing **NOF** instructions, over and over again. In fact the only way you can get out of it, once you're stuck there, is by sending the little chip an interrupt signal, so **EI** followed by **HALT** is safe since the hardware ensures that interrupts turn up pretty frequently, whereas **DI** followed by **HALT** is rather disastrous.

**IM** There are three forms of this instruction. These are **IM 0**, **IM 1**, and **IM 2**. They are there to change the Interrupt Mode (yes, another abbreviation) to either zero, one, or two. What this means is that the next time an interrupt is detected the following will happen. **IF THE INTERRUPT MODE IS ZERO**: The interrupt device itself must supply an instruction to be executed. **IF THE INTERRUPT MODE IS ONE**: The instruction **RST 38** is executed. **IF THE INTERRUPT MODE IS TWO**: The interrupt device must supply one byte of data. This is used as the low part of an address. There is a register called **I** (which we so far haven't used) and the value of this register is used as the high part of an address. The machine then looks up this address and should find a second address stored there. Confusing isn't it? This second address is used as a subroutine call.

**IN** Short for input, but nothing like the **INPUT** we are used to in **BASIC**. It is this instruction from which Sinclair builds the **LOAD** routine and a keyboard scan. It has two forms - the first is **IN A,(n)** where **n** is a numerical constant. **n** refers to an external device - a different **n** for each different device. One byte of data is read from device **n**, and loaded into **A**. **IN A,(n)** has no effect on the flags. The

second form **DOES** alter the flags - it is **IN r,(C)**. The number held by the **C** register is used to specify the device. The number input is loaded into register **r**.

**IND** Input with decrement. This is a deliberate digression from alphabetical order so that all of the input instructions can go together. **IND** can be thought of as **IN (HL),(C)** followed by **DEC B** followed by **DEC HL**. The carry flag is not altered, but the zero flag is altered to show whether or not **B** has decremented to zero.

**INIR** As **IND** but the instruction re-executes over and over again, stopping only when **B** reaches zero.

**INI** As **IND** except that **HL** is incremented instead of decremented.

**INIR** As **INIR** except that **HL** is incremented instead of decremented.

**INC** Don't Panic! At long last we're back to sensible instructions we can all understand. **INC r** increases the value of register **r** by one. Every flag except the carry flag is altered. **INC s** on the other hand (where **s** is a register-pair rather than a single register) will not change ANY of the flags. It still does the same job of course, increasing the value of register-pair **s** by one and zooming back round to **0000** if **s** starts off at **FFFF**, but don't use a check for zero after an **INC s** instruction because it simply won't work. **INC HL/JR Z** means jump if the instruction before **INC HL** came to zero, NOT if **HL** has reached zero. **INC H/JR Z** does work.

**JP** If you can understand **GOTO 10** you can understand **JP 4300**. The destination is an address, not a line number, but the principle is exactly the same. **JP** is the machine language **GOTO**. We can also have conditional jumps, for example **JP NZ,4300** means jump to 4300 IF NOT ZERO. (In other words if the zero flag is not set.) There is another form of **JP** which also has an analogy in **BASIC** - variable destinations. If you understand **GOTO N** you'll understand **JP (HL)**. In this form you can't have conditions. **JP NC,(HL)** for instance is not allowed. Also only three registers may be used as variables - these are **HL**, **IX**, and **IX**. Even so these are very powerful instructions - **HL** can be the result of a calculation, possibly even generated at random.

**JR** The same as **JP** but slightly less powerful, and one byte shorter. Only four of the eight conditions may be used - **JR Z**, **JR NZ**, **JR C**, and **JR NC**. It is impossible to say **JR 10**. It is also impossible to say **JR (HL)**. **JR** does not use an absolute address - the **R** stands for relative. You write the instruction as **JR e (or JR Z,e or whatever)** where the **e** is a single byte which specifies how far we must jump. **JR 0** has no effect, and **JR FE** is an infinite loop, since **FE** represents minus two. The jump is forward if **e** is between 0 and 7F, and backward if **e** is between 80 and FF.

**LD** The most used instruction in the whole of machine language. All it does is to transfer data from one place to another. It has many, many forms, the simplest being **LD r1,r2**, that is to transfer data from one register to another. **LD A,(BC)** is also legal and is a one byte code, so is **LD A,(DE)**. These are reversible, ie **LD (BC),A** and **LD (DE),A** are also legal. Remember that the brackets mean the contents of the address **BC** (or **DE**). Two special registers **R** (the memory refresh register as it's called which is used in outputting to the screen) and **I** (see **IM**) may be loaded to and from **A** (but only **A**) as in **LD A,I**, **LD A,R**, **LD I,A**, and **LD R,A**. The register pairs may all be loaded with either numerical constants or the contents of absolute addresses - **LD s,nn** or **LD s,(pq)**. Conversely any address may be loaded with the contents of one of the register pairs - **LD (pq),s**. Note that register-pairs hold two bytes not one, and these

are transferred to and from  $pq$  and  $pq+1$ . You can do the same with  $A$  on its own - LD  $A, (pq)$  and LD  $(pq), A$  are both allowed, but no other register can do this on its own. Finally the register pair  $SP$  - the stack pointer - may be loaded directly with either  $HL$ ,  $IX$ , or  $IY$ .

In other words there's a lot you can do and a lot you can't do. You can't say LD  $HL, SP$  for instance, even though LD  $SP, HL$  is allowable. Fortunately, since LD is used so very, very often it is extremely easy to become familiar with.

**LDD** Load with decrement. Effectively LD  $(DE), (HL)$  followed by DEC  $HL$ , DEC  $DE$ , and DEC  $BC$  all in one go. The carry flag and zero flag are unaltered, as is the sign flag, but the  $P/V$  flag becomes zero if  $BC$  becomes zero, one otherwise, thus JP  $PC$  will jump only if  $BC$  is zero after the instruction.

**LDDR** As LDD, but the instruction is repeated continually until  $BC$  reaches zero.

**LDI** As LDP, except that  $DE$  and  $HL$  are both incremented instead of decremented.

**LDIR** As LDDR except that  $DE$  and  $HL$  are both incremented instead of decremented.

**NEG** Neg alters the accumulator and all of the flags. As you may have gathered from the name it negates  $A$ . If  $A$  contains 1 then NEG will change it to minus one (FF). If  $A$  contains minus six (FA) then NEG will alter it to plus six (06). The same effect may be achieved using CPL followed by INC  $A$  - this alternative means of negating a number does not affect the carry flag as NEG does, but NEG is faster.

**NOF** This wondrous little instruction (which incidentally is short for No Operation) has a very simple purpose - its purpose is to waste time, for it does nothing at all! It's almost like a REM statement in fact, except that you can't put messages after it. It has two major uses: 1) as a delay, and 2) to overwrite previous machine coding when debugging. I'd say it was virtually indispensable.

**OR** In the form OR  $r$  this instruction is practically the opposite of AND  $r$ . Bit by bit, the value of the  $A$  register is changed. If a bit is one then it will be unaltered, but if it is zero it will take on the value of the corresponding bit in  $r$ . If  $A$  contains 00 then OR  $r$  is the same as LD  $A, r$  (except for the flags). If  $A$  contains FF then OR  $r$  will not change it. All of the flags are changed as you'd expect them, and the carry flag is reset to zero.

**OUT** As with IN, OUT is nothing like the BASIC understanding of output. The instruction OUT  $(n), A$ , where  $n$  is a one-byte numerical constant, will transfer the contents of  $A$  to external device  $n$ . Similarly OUT  $(C), r$  will transfer the contents of register  $r$  to the device pointed to by register  $C$ . OUT is used in the ROM to SAVE things. OUT has no effect whatsoever on the flags.

**OUTD** Output with Decrement. The carry flag is unchanged, but the zero flag depends on the final result of  $B$ . OUTD is equivalent to OUT  $(C), (HL)$  followed by DEC  $HL$  followed by DEC  $B$ .

**OTER** A slightly different spelling in no way alters the fact that this is still an Output with Decrement and Repeat instruction - all it does is leads us to digress from alphabetical order in order to maintain consistency. Equivalent to OUTD repeated until  $B$  is zero.

**OUTI** As OUTD except that  $HL$  is incremented instead of decremented.

**OTIR** As OUTD except that  $HL$  is incremented instead of decremented.

**POP** Remove two bytes of data from the top of the stack and load them into a register pair. Any register pair may be used except for  $SP$ . In addition the flags register may be combined with  $A$ , allowing the instruction POP  $AF$ . Specifically, the low part of the register pair is popped first, and then the high part. The machine remembers that the stack is now two bytes shorter by altering the value of  $SP$  automatically.

**PUSH** PUSH  $s$  is the opposite of POP  $s$ . It stores the contents of any register pair (except  $SP$ , but including  $AF$ ) at the top of the stack. It "remembers" that it has done this by altering the value of  $SP$ . The high part of  $s$  is pushed first, then the low part, so that the low part is at the top. After a PUSH instruction  $SP$  will point to the address of this low part.

**RES** With this instruction you can actually alter individual bits of any register. In computing circles "set" means change to one, and "reset" means change to zero, so RES is the instruction that changes the required bit to zero. For instance, to reset bit 3 of  $B$  the required instruction is RES 3,  $B$ . RES has no effect on any of the flags.

**RET** RET is used to return from a subroutine. It works by popping an address from the top of the stack, and then jumping to that address. It is possible to alter the address to which a subroutine will return by altering the value at the top of the stack. For example POP  $HL$ /INC  $HL$ /PUSH  $HL$  will increase the return address by one. You could for instance store one byte of data immediately after the CALL instruction, then POP  $HL$ /LD  $A, (HL)$ /INC  $HL$ /PUSH  $HL$  will store that byte in  $A$  while at the same time ensuring that the subroutine will return to the address after that data. Another trick is to push an "artificial" return address onto the stack and then JP (or JR) to a subroutine instead of calling it. Now it will "return" to wherever you want it to go! Return may be used with conditions if needed. It does not alter the flags.

**RETI** Used to end an interrupt subroutine (see IN). Its function is the same as RET, but RETI must be used instead of RET because the chip does clever things if you get a second interrupt in the middle of an interrupt subroutine! As soon as an interrupt subroutine is called a DI instruction is automatically executed, but there are such things as non-maskable interrupts, that it almighty superhigh-powered interrupts that override even DI, these can cause confusion if you don't use RETI.

**RETN** Used to end a non-maskable interrupt subroutine. Its function is the same as RETI except that the Interrupt Mode (which was altered by the non-maskable interrupt in the first place) is also restored to its previous value.

**RLA** An abbreviation for Rotate Left Accumulator. Each bit of  $A$  is moved one position to the left. The leftmost bit is moved into the carry, and the rightmost bit takes on the previous value of the carry. For example, if  $A$  contained 10010101 (binary) and the carry contained 0 then after a RLA instruction  $A$  will contain 00101010 and the carry will contain one. Only the carry flag is altered by this instruction.

**RL** On the other hand, there is another instruction which may be applied to any register. It is RL  $r$ . In fact every now and again the instruction RL  $A$  tends to disguise itself as RLA - due possibly to printing errors or bad handwriting. On the face of it they seem to do the same thing - RL means Rotate Left and its function is exactly as described in RLA. The difference however, is in what happens to the flags, for RL will alter ALL of them, RLA will only alter the carry. RL may of course be applied to any register, not just  $A$ .

Incidentally - RL A does precisely the same thing as ADC A,A, down to the last flag - except one - one you can't get at - called the H flag. The only way you can possibly tell the difference is by following it with a DAA instruction. ADC A,A, by the way, is twice as fast.

**RICA** Almost the same as RLA, but not quite. Each bit of A is moved one position to the left. The leftmost bit is moved BOTH into the carry, AND into the rightmost position of A. If, as before, A started off with 10010101 and the carry was zero, then after RICA it will be 00101011. The carry will also be one. Only the carry flag is changed - the previous value of which is lost forever.

**RIC** RIC r will Rotate Left with Carry the register r in the same way that RICA does with A. RIC A is a valid instruction, which is not the same as RICA. RIC B is a valid instruction, but please note there is no such instruction as RICB. The spacing is very important here. RIC r will alter all of the flags.

**RDL** Not to be confused with RL D, this is a COMPLETELY DIFFERENT instruction which works as follows: Write the value of A and the value of address (HL) in hex. The second hex-digit of (HL) is shifted left so that it becomes the first digit. The first digit overwrites the second digit of A. The second digit of A moves to the second digit of (HL). Thus if A contains 25 (hex) and (HL) contains EB then after an RDL has been carried out A will contain 2E and (HL) will contain B5. RDL, incidentally, stands for Rotate Left Decimal.

**RRA** As RLA except that the bits are moved right instead of left.

**RR** As RL except that the bits are moved right instead of left.

**RRCa** As RICA except that the bits are moved right instead of left.

**RRc** As RIC except that the bits are moved right instead of left.

**RHD** The contents of (HL) are moved one hex-digit to the right, the rightmost digit moving into the rightmost digit of A, which in turn becomes the left digit of (HL). If A equals 25 and (HL) equals EB then after RHD A will equal 2B and (HL) will equal 5E. Note that RHD twice is the same as RLD once, and vice versa. All of the flags except carry are altered.

**RST** The same as CALL, except that it is only one byte long. ALTOGETHER! It is much less powerful though for two reasons: 1) you may not use conditions. RST 0 is legal but RST NZ,0 is not. 2) only one of eight specific addresses may be called. There are 0, 8, 10, 18, 20, 28, 30, or 38. On the OLD ROM, RST 0 is the same as NEW. On the NEW ROM however RST 0 will move RANTOP to its highest possible location, which the BASIC instruction NEW will not do. RST 0 is the same thing as pulling out the mains lead and then reconnecting it.

**SBC** SBC, like APC, comes in two forms. The first is SBC A,r, which will first of all subtract r from A, and will then subtract the carry digit. Similarly SBC HL,s will subtract both s and the carry flag from HL. SBC A,A is quite useful - if the carry is zero both A and the carry will end up zero - if the carry is one then A will be reassigned 1F and the carry will still be one.

**SET** The opposite of RES. SET 4,H will change the value of bit 4 of H to one. Any bit of any register may be set.

**SIA** Shift Left Arithmetic. The form is SIA r. It is similar to RL r except that the rightmost bit is automatically replaced by zero. It alters all of the flags. Note that SIA A does the same thing as ADD A,A, except that ADD A,A is faster.

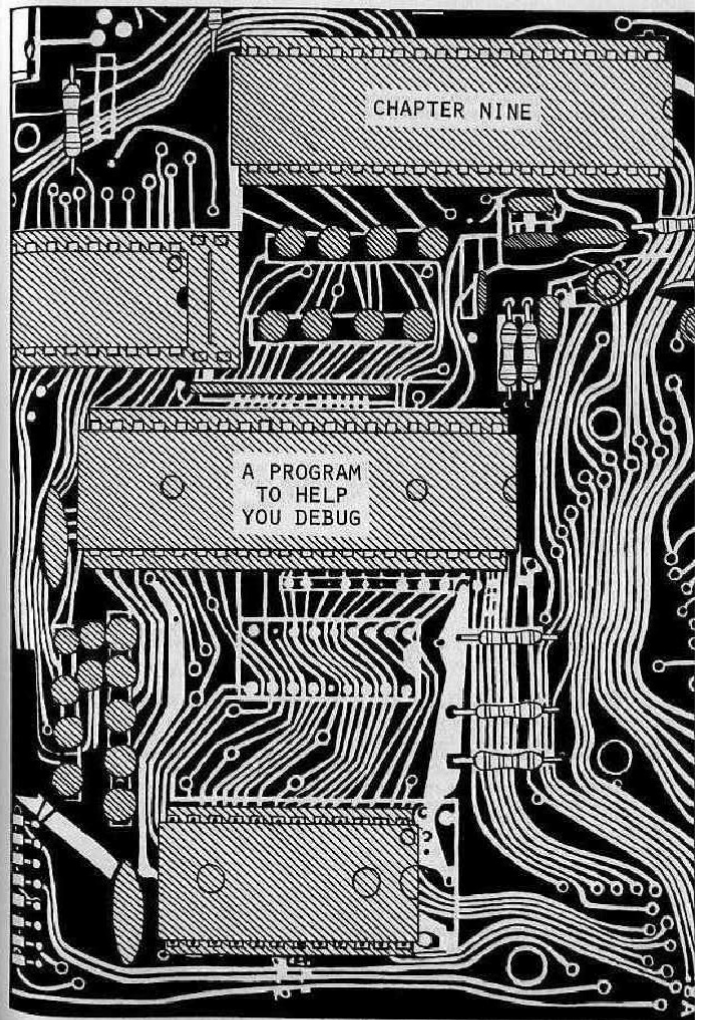
**SRA** Shift Right Arithmetic. Any register may be shifted right using the format SRA r. The rightmost bit falls into the carry, but the leftmost bit remains unaltered. Thus after a SRA instruction bit 6 will always be the same as bit 7. The effect of SRA is to divide both positive and negative numbers by two; FC (minus four) becomes FE (minus two). What happens if the number is odd?

**SRL** Shift Right Logical. As SRA except that the bits are shifted right instead of left, and the leftmost bit becomes zero.

**SUB** Sometime written as SUB r, sometimes as SUB A,r, both mean the same thing. The value of r is subtracted from the A register. Note that unlike ADD, there is no corresponding instruction SUB HL,s. If you wish to do this you must first of all reset the carry flag (usually by use of AND A) and then use SBC HL,s.

**XOR** XOR r alters all of the flags, resetting the carry to zero, and the A register alone. r is not altered. What happens is that A is altered bit by bit, in the same manner as AND and OR. If a bit is zero it takes on the value of the corresponding bit of r. If on the other hand a bit is one then its new value is the complement of the appropriate bit of r. XOR A is very useful since in one byte it zeroes both the accumulator and the carry flag. Incidentally so does SUB A.

*[Faint, illegible text from the reverse side of the page, visible through the paper.]*



Now we more or less know what machine language is, it's about time we learned a bit more about how to handle it. What we shall do now is to write a new program - **HEXLD2** - which will allow us to do five things. 1) Input machine code. 2) Insert machine code in between previous routines, but without overwriting anything. 3) Delete machine code, closing up the gap that it occupied. 4) List machine code. 5) SAVE machine code. The important point about this program is that the principle parts of it will themselves be in machine code, although all of the surrounding fabric will be BASIC. To work it all you will need to do is enter one of the following.

```
RUN      To List your stored machine code.
RUN 100  To Write new machine code.
RUN 200  To Insert new machine code.
RUN 300  To Delete previous machine code.
RUN 400  To Save machine code.
GOTO 500 To Reload saved machine code (OLD ROM only)
```

More to the point - you'll need **HEXLD2** in order to help you load it. The addresses used in this chapter assume that the machine code is being loaded into a **REM** statement in line one of a NEW ROM machine. If this is so you'll actually need 255 characters after the word **REM**. However, you don't have to use the same addresses as me if you don't want to. OLD ROM folk are specifically advised NOT to use a **REM** statement, since the machine code contains newline characters. To store machine code at different addresses to those I've used simply change the listed addresses to yours.

Let's create it one part at a time. First of all a special subroutine for OLD ROM people - designed to AUTOMATICALLY print a character to the screen, in much the same way that the NEW ROM **PRINT** routine does. The routine will also protect all of the registers. Study this listing:

FOR OLD ROM PEOPLE ONLY			
<b>E5</b>	<b>APRINT</b>	<b>PUSH HL</b>	Store the value of HL.
<b>D9</b>		<b>EXX</b>	Store the remaining registers.
<b>F5</b>		<b>PUSH AF</b>	And the A register.
<b>CDE006</b>		<b>CALL PREPOS</b>	Find print-position.
<b>F1</b>		<b>POP AF</b>	Retrieve A.
<b>CD2007</b>		<b>CALL PRINT</b>	Print character A.
<b>D9</b>		<b>EXX</b>	Retrieve HC and DE.
<b>E1</b>		<b>POP HL</b>	Retrieve HL.
<b>C9</b>		<b>RET</b>	End of subroutine.

Note that **HL** needs to be stacked, since **CALL PRINT** changes the value of **HL**. The next subroutine we'll need is a mechanism for printing to the screen the value of the A register in hexadecimal. This subroutine will INCLUDE a subroutine-call to **APRINT**, at least for OLD ROM people. New ROM people in fact already have an automatic print routine which protects all of the registers, since there is one in the ROM itself. It is not quite the same as the **PRINT** routine, since it also preserves the values of all the registers - this is something that **CALL PRINT** will not do. **CALL PRINT** will erase the values of B, C, D, E, H, and L. The address at which **APRINT** begins in the NEW ROM is 0010, and so **CALL 0010** would print a character without changing any register. This is very useful indeed.

One of the 280 instructions designed to speed things up a bit is **RST**. It is in effect the same as **CALL** except that only one of eight addresses may be called. It just so happens that 0010 is one of these possible addresses. **RST** is better than **CALL** for two reasons: 1) it is faster to execute, and 2) it is only one byte in length. The code for **RST 10** is **D7**. **D7** then has precisely the same effect as **CD0000**, that is, to print a character. OLD ROM users should note that although **D7** still produces a call to 0010, it will not print a character, since in the OLD ROM there is no **PRINT** subroutine located at this point. **RST** is short for **RESTART**.

<b>F5</b>	<b>HPRINT</b>	<b>PUSH AF</b>	Store A for later use.
<b>E6F0</b>		<b>AND FO</b>	This isolates the first digit.
<b>1F</b>		<b>RRA</b>	Move this first digit to its proper position within the A register.
<b>1F</b>		<b>RRA</b>	
<b>1F</b>		<b>RRA</b>	
<b>C61C</b>		<b>ADD A,1C</b>	Add twenty-eight to the character code, making it a hex-digit.
<b>D7</b>		<b>RST 10</b>	Print this hex-digit. OLD ROM users should of course replace <b>RST 10</b> by <b>CALL APRINT</b> .
<b>F1</b>		<b>POP AF</b>	Retrieve the original value of A.
<b>E60F</b>		<b>AND 0F</b>	Isolate the second digit.
<b>C61C</b>		<b>ADD 1C</b>	Add twenty-eight.
<b>D7</b>		<b>RST 10</b>	Print it. OLD ROM users should instead use <b>CALL APRINT</b> .
<b>C9</b>		<b>RET.</b>	

By the way, did you understand all those **ANDs** and **RRAs**? If you didn't I'll explain exactly what's going on.

In binary, **FO** is 1111 0000. This means that when you apply **AND** to **FO** and another number, then the first four binary digits of A will be unchanged, and the second four binary digits will all become zero. Do you remember how to change from binary to hex? You have to look at it four bits at a time. The first four representing the first digit, and the second four the second digit. Thus all we have done is to change the second digit to zero.

If A were 36 then it would become 30. If it were 99 it would become 90. If it were **D5** it would become **D0**. And so on. This is not what we want. We must shift A four bits to the right.

**RRA** moves A one bit to the right, replacing bit 7 (the leftmost bit) by the value of the carry. In this case the carry is zero, since we have just done an **AND** instruction. The new value of the carry will be the previous value of bit 0 (the rightmost bit). This will also be zero since there are now four zeroes at the right of A.

**RRA** then, repeated four times, will change A from 30 to 03, from 90 to 09, and from **D0** to **0D**. All that remains now is to add 28 (decimal) to this number and print it. We print it using the instruction **RST 10**.

Back to our new program. The BASIC part of the List routine will look like this:

```
10 PRINT "keyword LIST"
20 GOSUB 600
30 RAND USR 16539
```

to obtain the keyword **LIST** in line 10, either type **THEN LIST** (NEW ROM only) and delete the word **THEN**, or type the whole line as **10 LIST** quote backspace backspace **PRINT** quote newline.

```
600 LET A = 16533
610 PRINT "ADDRESS space":
620 INPUT A$
630 PRINT A$
640 POKE A+1,16*CODE A$+CODE A$(2)
-476
```

```

650 POKE A,16*CODE A$(3)+CODE A$(
(4)-476
660 CLEAR
670 RETURN

```

What about this USR routine at 16539 then? What will that do? And what about this business of POKEing 16533 and 16534? What's that all about? Well using my addressee, 16539 is the start of a routine called HLIST, which we haven't yet written. It is designed to actually LIST a machine code program in hexadecimal (hence H-List). The address 16533 is the number I've used to hold a "variable" called ADDRESS. That is to say, it is a place at which we can store a two-byte number. Any address may be used for this purpose provided that BASIC will not change that two-byte number.

This program demands four such "variables", or two-byte memory locations. They will be called BEGIN, ADDRESS, ADD2, and LIMIT. They will be used by the program as follows:

BEGIN	The address at which the subject-program begins.
ADDRESS	The address we are currently looking at.
ADD2	The address beyond which we must not progress.
LIMIT	The address at which the subject-program ends.

I ought to explain here what is meant by "subject-program". The program we are writing is a replacement for HEXLD2. As such it is to be called HEXLD3. This is the "object-program" - the one we are writing now. But the purpose of HEXLD3 is to enable us to be able to create and examine machine code programs. The program that HEXLD3 will be used to examine is called the "subject-program". These distinctions are clearly necessary in order to avoid confusion between the two different concepts. It is of course possible to use HEXLD3 to examine itself, in which case it becomes both the object and the subject, but for the time being keep these two ideas separate in your mind.

The addresses which I've used to store the "variables" BEGIN, ADDRESS, ADD2, and LIMIT are as follows:

Decimal	Hex	Explanation
16514	40B2	The start of the subroutine HPRINT
16531	4093	The variable BEGIN
16533	4095	The variable ADDRESS
16535	4097	The variable ADD2
16537	4099	The variable LIMIT
16539	409B	The start of the USR routine HLIST.

Lines 640 and 650 POKE into the variable ADDRESS - Giving the address at which our listing (input in hex as A\$) is to begin. This idea of using part of the RAM in machine-code-area to store numbers is a very useful one. You can use it in many different programs. The numbers will be safe there even after the program ends and you are in command mode. You can type RUN or CLEAR and they won't be wiped out. They will even SAVE and reload.

Now for the subroutine HLIST (Short for Hexadecimal List). It is a very very simple routine indeed, and should be no trouble for you to follow.

```

2A9940 HLIST LD HL,(LIMIT) Ensure that we don't progress beyond
229740 LD (ADD2),HL the end of the subject-program.
54 LD D,H
5D LD E,L
2A9540 LD HL,(ADDRESS) Compare the current address with
0616 LD B,16 (OLD ROM ONLY) final address.
AND
A7 NXTAD
ED52 SEC HL,DE
19 ADE HL,DE
301F JR NC,DONE
7C LD A,H
CD8240 CALL HPRINT
7D LD A,L
CD8240 CALL HPRINT
AF XOR A
D7 RST 10
D7 LD A,(HL)
7E CALL HPRINT Print the high-part of the current
CD8240 LD A,L address in hex.
B76 BIT 6,(HL) Print the low-part of the current
2004 JR NZ,NOPRINT address in hex.
AF XOR A Reset A to zero.
D7 RST 10 Print a space.
7E LD A,(HL) Print the contents of the current
D7 RST 10 address in hex.
3E76 NOPRINT LD A,76 If this character is unprintable
D7 RST 10 Print newline.
23 INC HL Look at the next address.
229540 LD (ADDRESS),HL Store the current address.
18DB JR NXTAD (NEW ROM ONLY)
10DB DJNZ NXTAD (OLD ROM ONLY)
CF DONE RST 08 See below.
00 DEFB 00

```

The above program will run as listed on a NEW ROM machine. OLD ROM users should replace every RST 10 instruction by CALL APRINT as before, and are reminded that the JR byte-count must be changed accordingly at two points in the program.

There are several things we can note about this program. Firstly, two new instructions have been used - BIT 6,(HL) and RST 08. Here's what they do.

BIT 6,(HL) tests the value of bit 6 of the address (HL). The result will either be 1 (if bit 6 is 1) or 0 (if bit 6 is 0). This result is not stored in any of the registers, but we can still check it with the next line JR NZ,NOPRINT, which says jump to NOPRINT if the last result (that is bit 6 of (HL)) is not zero.

Why do we need to do this? Take a look at the character set. In particular look at their character codes in hex. Notice that all of the expandable characters lie between C0 and FF (except for RND, INKEY\$, and PI on the NEW ROM - these are treated slightly differently by the ROM) and that all of the characters between 40 and 7F are not printable at all (again, except for RND, INKEY\$, and PI on the NEW ROM. The machine has to make a special check for these.) (You could argue that the NEW ROM cursor (7F) was printable, but of course it looks different depending on what mode the machine is in.) In fact all of the printable characters are either between 00 and 3F, or between 80 and FF, and conversely every character between 00 and 3F, or 80 and FF, is printable. What have all these in common? The fact that BIT 6 of the character code is zero. In binary these codes run between 0000 0000 and 0011 1111, and then from 1000 0000 to 1011 1111. So all we have to do to find out whether or not a character in the set is printable, all we have to do is to look at BIT 6. The above program won't attempt to print them unless BIT 6 is zero. This is because the RST 10 routine won't expand the expandable characters, nor will it replace the others by question marks. It will crash though!

The other new instruction is RST 08. This will cause an immediate return to BASIC, stopping the program with an error code. The byte immediately after the RST 08 instruction tells it which error code to use. An error code 1 needs the data 00, since this byte has to be one less than the report code. If we wanted to be really flash we could have used 10 and got an error code of 11.

Now follow the program through carefully and see what it does. Note the way we check whether or not the address ADE2 has been reached (it is stored in DE) - especially the use of AND A to reset the carry flag.

You can check that this program works by POKEing the address at which HPRINT starts into both BEGIN and ADDRESS, and by POKEing the address at which HPRINT ends into LIMIT. Then, if you type RAND USR HLIST (this is the location 16539 using my addresses) you should end up with a more or less instant listing of the subroutine HPRINT.

Now if you simply type RUN and enter 4082 the program will instantly list out the start of this program. In other words we are using it to examine itself. Typing CONT or CONTINUE repeatedly will continue the listing until the end of the program is reached, when you will get a report code of 9.

Now for the second part of our program, HEXLID. The BASIC part is to look like this:

```
100 PRINT "WRITE"
110 GOSUB 600
120 INPUT A$
130 PRINT A$;"two spaces";
140 RAND USR 16589
150 GOTO 120
```

This part calculates the length of the string A\$, which because of the CLEAR Statement in subroutine 600 is the first (and only) item in the variable store.

OLD ROM ONLY:

```
2A0840 WRITE LD HL,(VARS)
E5 PUSH HL
06FF LD B,FF
23 TNC HL
7E LD A,(HL)
04 TNC B
3D DBC A
2EFA JR Z,ANOTHER
E1 POP HL
CB28 SRA B
```

This routine leaves the length of the string divided by two (since it needs two characters to specify one byte of machine code) in the B register and leaves HL pointing to the byte immediately before the start of the contents of the string. Notice how LD A,(HL)/INC B/DEC A/JR Z is used to check for a character 1 (a quote mark, or end of string character) as well as counting the number of characters so far (in B). Can you also see how SRA B will divide B By two?

Strings are stored differently in the NEW ROM. This actually makes things easier, not harder! Look at the corresponding NEW ROM routine which does the same job.

```
NEW ROM ONLY:
16589 2A1040 WRITE LD HL,(VARS)
23 INC HL
46 LD B,(HL)
23 INC HL
CB28 SRA B
```

This works because the NEW ROM works by storing the length of a string immediately before the string itself. It takes two bytes for this, but notice that in both of our versions we are only using one byte for the length, so don't input more than 255 characters in one go.

Here's the rest of the routine.

```
28F4 JR Z,DONE
E5B9540 LD DE,(ADDRESS)
23 INC HL
7E LD A,(HL)
87 ADD A,A
87 ADD A,A
87 ADD A,A
87 ADD A,A
23 INC HL
86 ADD A,(HL)
C624 ADD A,24
12 LD (DE),A
13 INC DE
ED539540 LD (ADDRESS),DE
E5 PUSH HL
2A9940 LD HL,(LIMIT)
ED52 SBC HL,DE
E1 POP HL
3004 JR NC,CHECK
ED539940 LD (LIMIT),DE
1081 DJNZ NEXTBYTE
C9 RET
```

You can learn several things from this routine. Firstly, notice that if you input the empty string the program will jump back to the RST 08 instruction in the previous section. This is so that you can end the program without actually having to break out.

Now look at the first few lines from CHECK onwards. What they do is this - if the end of the program (the program that WRITE is editing) is greater than the current address, do nothing, otherwise make a note of the fact that the program has got longer by altering our variable LIMIT.

You now have two segments of machine code which, if you've typed them in properly, will work first go. Now delete the WHOLE of HEXLID2 (except of course for line 1) but be very careful not to attempt to list line one. The first line now contains more characters, when the keywords in the ROM are expanded, than will fit on the screen. In this circumstance the ROM will go into an infinite loop if it tries to list it - this is a design fault - the ROM should not be capable of making infinite loops. You won't be able to break out if it happens. To avoid it, type POKE 16403,10 (OLD) or POKE 16419,10 (NEW). Then type in lines 10 to 30, then delete the rest of the program one line at a time, lowest line number first. Now type in the rest of the program and SAVE it before you do anything else.

For NEW ROM users, it should be made clear that the REM statement will, when keywords are expanded, be longer than will fit on the screen, thus although the command LIST is acceptable (the result of which is that part of line one is listed and an error 4 message displayed), if you LIST 10, to ensure that line 10 is always at the top of the screen (sometimes this doesn't work - if not type POKE 16419,10 which always works) be warned never to delete line 10. If you do the ROM will go into an infinite loop trying to reshuffle the lines so that it can list them. In SLOW this can be quite amusing to watch, but it is always irritating because the only way you can get out of it is by pulling the plug.

Now to complete the transition from HEXLD2 to HEXLD3 let's rewrite the section that will SAVE things in upper memory. The BASIC:

OLD ROM	NEW ROM
400 DIM O(USR(ARRAY))	400 DIM O%(USR ARRAY)
410 RANDOMIZE USR(STORE)	410 RAND USR STORE
420 SAVE	420 SAVE "HEXLD3"
500 RANDOMIZE USR(RETRIEVE)	500 RAND USR RETRIEVE
510 CLEAR	510 CLEAR
520 STOP	520 STOP

As you can see there are three different parts of machine code. The first, in line 400, alters nothing, but returns a numerical value to BASIC, which is then used by BASIC to reserve the correct amount of space using a DIM statement. Let's look at that part first:

Using my addresses, ARRAY is 16635, STORE is 16651, and RETRIEVE is 16669.

2A9940	ARRAY	LD HL,(LIMIT)
8F5B9340		LD DE,(BEGIN)
A7		AND A
ED52		SBC HL,DE
229740		LD (ADD2),HL
for the OLD ROM only:		
CB2C		SRA H
CB1D		RR L
for the NEW ROM only:		
44		LD B,H
4B		LD C,L
for both:		
C9		RET

The first part is obvious. The beginning address is subtracted from the end address. Again we see AND A being used to zero the carry flag so that SBC gives the right answer. Now, for OLD ROM users, this number is divided by two, because arrays use two bytes per element. For NEW ROM users we move the answer into the BC register because this is what will return to BASIC. Now for the machine code that accompanies line 410. Use RUN 100 to load it in the first place.

You may be wondering why ADD2 was loaded with the number of bytes in the code to be SAVED. Well ADD2 is just a convenient place to store it, since it will be needed in line 410.

2A1040	STORE	LD HL,(VARS)
110600		LD DE,0006
19		ADD HL,DE
EB		EX DE,HL
2A9340		LD HL,(BEGIN)
ED4B9740		LD BC,(ADD2)
EDB0		LDIR
C9		RET
2A1040	RETRIEVE	LD HL,(VARS)
110600		LD DE,0006
19		ADD HL,DE
8F5B9340		LD DE,(BEGIN)
ED4B9740		LD BC,(ADD2)
EDB0		LDIR
C9		RET

In case you're beginning to lose track, here's a quick round up of all the addresses we've used so far:

Decimal	Hex	Routine/Variable
16514	4082	HEPRINT
16531	4093	BEGIN
16533	4095	ADDRESS
16535	4097	ADD2
16537	4099	LIMIT
16539	409B	HLIST
16589	40CD	WRITE
16635	40FB	ARRAY
16651	410B	STORE
16669	411D	RETRIEVE
16687	412F	next spare byte.

Briefly, STORE moves machine-code from upper memory and stores in an array. RETRIEVE moves it back from the array to its previous position. Both of the routines start off by working out the address of the first free byte in the array. The array is the first item in the variable store, but because the OLD and NEW ROMs think differently, we have to add two to this location in the OLD ROM, and six on the NEW ROM. Can you spot the different ways in which this is done?

This is also the first time we've used the instruction LDIR. What is does is to automatically move a block of elements from address (HL) to address (DE), assuming that the number of elements contained in this block is BC. This is of course precisely what we want to do. LDIR does alter the value of each of the register pairs BC, DE, and HL, but that doesn't concern us since the next thing we do is RET.

LDIR is very, very useful indeed, but you must remember which way round it goes. It loads from (HL) into (DE). Have you ever pressed 'record' instead of 'play' when trying to load programs from tape? Well that's exactly what will happen to your machine code if you get DE and HL the wrong way round for LDIR - it will just be wiped out - and there's no going back.

As long as you can see exactly what's happening you're OK. If you can't then get a piece of paper and write down the values of each register at each stage, work through until you're convinced you know exactly what's happening all the way through.

We now have a BASIC program called HEXLD3 which contains a fair number of machine code subroutines. As it stands it will both LIST and WRITE machine code, and can also be used to SAVE any machine code or data which is stored in spare RAM space high in memory. This is all that HEXLD2 did. You now have the ability to enter your own machine code programs very easily, but what you can't yet do is edit them if you make a mistake. That is what the next section is for - it is called INSERT, and will insert whatever you input between the surrounding code, without overwriting it. The BASIC part of the routine is this

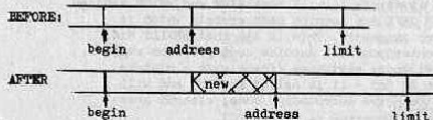
```
200 PRINT "INSERT"
210 GOSUB 600
220 INPUT A$
230 PRINT A$;"two spaces"
240 RAND USR 16687
250 GOTO 220
```

And the machine code which goes with it (which NEW ROM users should write to address 16687) is as follows:

OLD ROM			NEW ROM		
2A0840	INSERT	LD HL,(VARS)	2A1040	INSERT	LD HL,(VARS)
E5		PUSH HL	23		INC HL
01F1FF		LD BC,FFFF	4E		LD C,(HL)
23	MORE	INC HL	23		INC HL
7E		LD A,(HL)	46		LD B,(HL)
03		INC BC			
3D		DEC A			
28FA		JR Z,MORE			
E1		POP HL			
		CR28	COPYUP	SRA B	
		CB19		RR C	
		2002		JR NZ,NOTEMPTY	
		CF		RST 08	
		08		DEFB 08	
		C5	NOTEMPTY	PUSH BC	
		2A9940		LD HL,(LIMIT)	
		K05B9540		LD DE,(ADDRESS)	
		A7		AND A	
		ED52		SHC HL,DE	
		23		INC HL	
		44		LD B,H	
		4D		LD C,L	
		E1		POP HL	
		ED5B9940		LD DE,(LIMIT)	
		19		ADD HL,DE	
		229940		LD (LIMIT),HL	
		EB		EX DE,HL	
		EDB8		LDIR	
		CDCD40		CALL WRITE	
		C9		RET	

Now exactly how this works is quite complicated, so think carefully. The part between INSERT and COPYUP finds the length of the string *A*. As you can see it required a completely different method for each ROM. See WRITE on this, since it is very similar here.

Between COPYUP and NOTEMPTY the length of the string is divided by two, and if it is zero returns to BASIC with error code 9. This is the job of the RST 08/DEFB 08 sequence. From then on we are concerned with moving part of the program being edited. Look at the diagram below.



As you can see, we need to load a complete block of elements from one point to another, but unlike before the new and old positions overlap. This is a slight problem, and we have to be very careful how we load it. If we were to simply assign HL to ADDRESS(before) and DE with ADDRESS(after), and then use LDIR as before (having assigned BC to the number of elements in the block first) then since LDIR moves things one byte at a time the first few elements would end up in the middle of the block, only to be copied up for a second time. The program would be completely corrupted.

We can get round this flaw by sneaking up on the problem sideways while it's not looking. What we do is we block load it from the other end! This means loading HL with LIMIT(before) and DE with LIMIT(after) and use LDIR instead of LDIR.

Having found the length of the new section, this length is pushed onto the stack. BC is then loaded with the length of the block to be moved. See how this is worked out. Then HL and DE are correctly assigned, making use of the fact that the length of the new section is at the top of the stack, and the new limit is stored in our "variable" LIMIT.

After the block load is successfully carried out we call the WRITE subroutine to fill the shaded area in the diagram with the contents of the input string. This will work because the above program does not change the value of the variable ADDRESS. WRITE will simply overwrite the shaded region, moving the current address pointer to its new position. We then return to BASIC for the next input.

To test the program, use WRITE to write "9D9E9FA0A1a2A3A4A5" to the point just beyond where our program currently ends. This will list as *9D9E9FA0A1a2A3A4A5*. Now use INSERT. Give it the address of the inverse five, and input "00"/"201E"/"00". Here / means newline. When you list it you'll find four new characters have been inserted. Notice that the routine allows you to input as many characters as you like in one go, and that it allows you to press newline as many times as you like. Newline on its own (ie inputting the empty string) will break out of the program.

The final section to add to our program is DELETE. This will look (in BASIC) like this

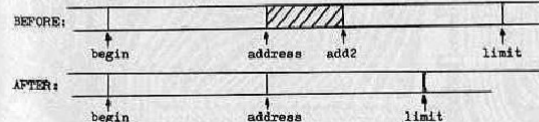
```

300 PRINT "DELETE"
310 GOSUB 600
320 LET A = 16535
330 GOSUB 610
340 RUN USR 16732

```

The first four lines load the initial and final addresses into the variables ADDRESS and ADD2. Line five calls the machine language routine that will do the task for us.

Here's what the machine code has to do. Look at the diagram below. Here the shaded region must be removed.

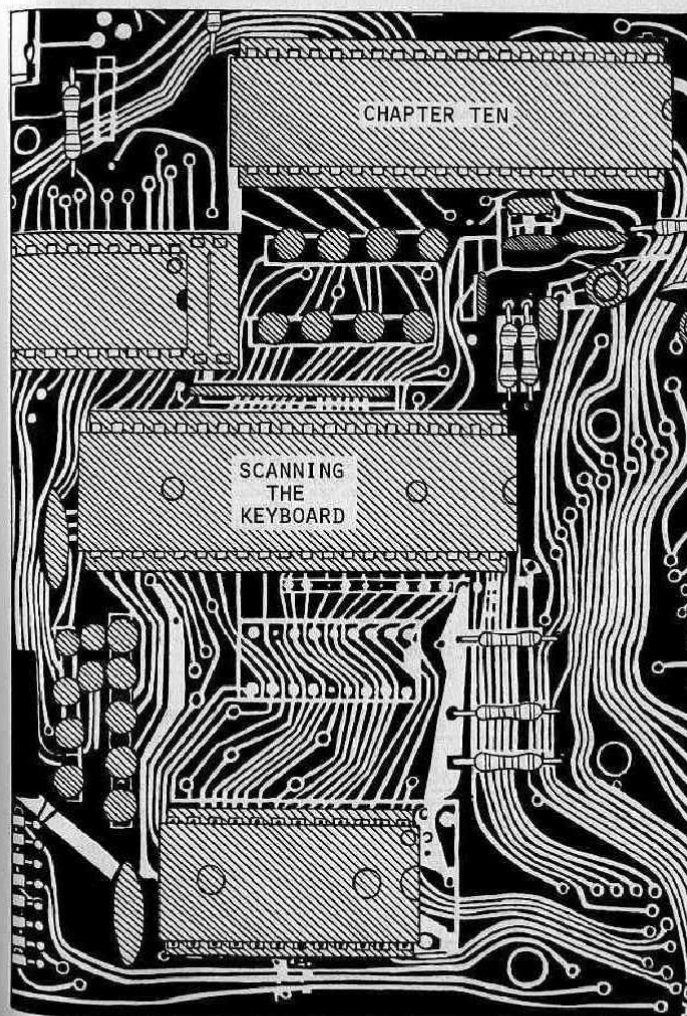


This is quite simple - we just use LDIR quite straightforwardly. You might think there would be some effort involved in calculating the new limit, but not so. LDIR alters the value of HL and DE for us in quite an advantageous way - as we shall see.

2A9940	DELETE	LD HL,(LIMIT)
ED5B9740		LD DE,(ADD2)
D5		PUSH DE
A7		AND A
ED52		SEC HL,DE
44		LD B,H
4D		LD C,L
E1		POP HL
23		INC HL
ED5B9540		LD DE,(ADDRESS)
ED80		LDIR
1B		DEC DE
ED539940		LD (LIMIT),DE
CF		RST 08
08		DEFB 08

As LDIR moves from one end of the blocks being shifted to the other, HL and DE move with it, so HL ends up to the right of the original block, and DE ends up to the right of the copy. Thus a simple DEC DE after the LDIR will set it to exactly the right place for our new limit. Load this routine to address 410D (OLD)/415A (NEW), using INSERT. You should now have one or two spare characters after the end of the program. Use DELETE to wipe them out - this will of course test whether or not you have typed in DELETE correctly.

Now SAVE this program permanently. This is the final version. All you have to do in order to use it in future is to type RUN 100 and enter the address of the variable BEGIN. (403C or 4093). Then input the address to which the program you are about to write will begin, then simply newline on its own. RUN 100 a second time to actually begin inputting a program.



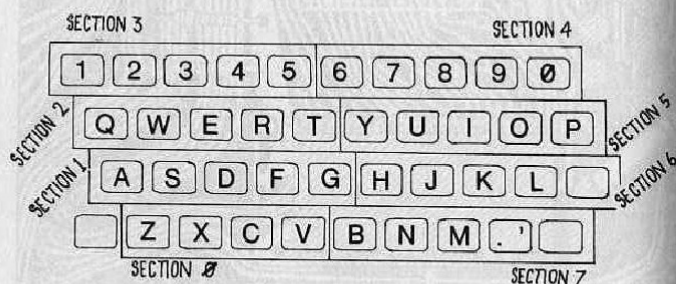
Now it's time to explore how we can make use of some of the other subroutines that are remarkably well-hidden within the ROM. Specifically we'll cover two of these subroutines, which between them will enable us to scan the keyboard and locate which, if any, of the keys on the keyboard are being depressed. On the NEW ROM we can make use of these subroutines just by calling them, but we can't on the OLD ROM because they're simply not there. For the benefit of the people with OLD ROMs I shall include a section at the end of this chapter explaining how these programs may be made to work by actually inputting these subroutines yourselves. This section will also be of interest to those of you with NEW ROMs, since it will give you an insight into how the subroutines actually work.

The first such subroutine is an amazing little keyboard scan, which begins at address 02B5. It may be accessed simply by calling that address, ie CALL KSCAN, or CDB02 in hex. It doesn't actually produce a very useable answer though. Let's see exactly what it does do.

It returns a value to the HL register pair. Actually it returns separate and independent values - one to H and one to L. Here's how the value of L is interpreted:

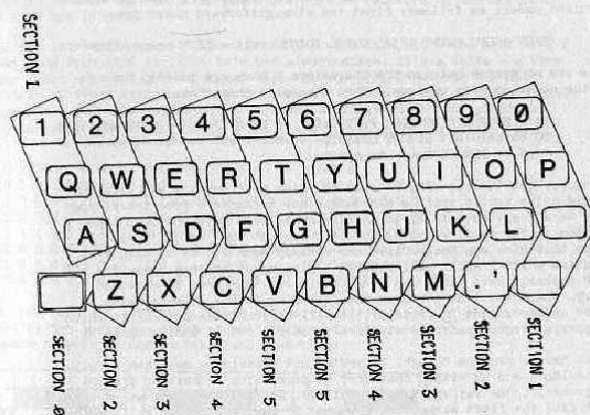
Imagine the keyboard (excluding SHIFT) divided up into eight horizontal sections, each containing five keys (except for section zero which only contains four, because SHIFT is omitted). Notice how each section has a corresponding number between zero and seven. Now, if there is no key depressed then L will return a value FF. However, if one or more keys are depressed, then the appropriate BIT (of L) will be reset to zero. In other words, if you are pressing Q, W, E, R, or T then bit 2 will be reset - if you are pressing B, N, M, full-stop, or space, then bit 7 will be reset. This means that L can return the following:

	BINARY	HEX
If no key is depressed	11111111	FF
If a section 0 key is depressed	11111110	FE
If a section 1 key is depressed	11111101	FD
If a section 2 key is depressed	11111011	FB
If a section 3 key is depressed	11110111	F7
If a section 4 key is depressed	11101111	F3
If a section 5 key is depressed	11011111	DF
If a section 6 key is depressed	10111111	EF
If a section 7 key is depressed	01111111	7F



As an exercise see if you could work out what L would return if both S and P were depressed at the same time.

The value returned by H is determined by a similar principle, but notice how the keyboard is divided up here - not horizontally but vertically. Notice also that the SHIFT key has a section all to itself - section 0. Now if you press key S for instance then H will return FB (in binary 11110111). We have already seen that L would give FB as well, so that HL returns FEFB. Can you see why it is impossible for this value to be obtained from any other key?



Now let's see what would happen if you pressed SHIFT S. Both bits zero and two would be reset giving, in binary, 11110101. In hex this is FA, so HL would return as FAFB - which is different to the value produced without shift. We can see the precise effect of SHIFT from this table:

	WITHOUT SHIFT		WITH SHIFT	
	BINARY	HEX	BINARY	HEX
If no key is depressed	11111111	FF	11111110	FE
If a section 1 key is depressed	11111101	FD	11111100	FC
If a section 2 key is depressed	11111011	FB	11111010	FA
If a section 3 key is depressed	11110111	F7	11110110	F6
If a section 4 key is depressed	11101111	DF	11101110	DE
If a section 5 key is depressed	11011111	EF	11011110	EE

It should by now be reasonably clear how each individual key, with or without shift, produces its own unique code in the HL register pair. If two keys are both in the same horizontal section they cannot possibly both be in the same vertical section. Note that SHIFT on its own returns a value of FEFF which is not the same as no key depression at all.

The subroutine which I've called KSCAN does have one big disadvantage though - it will completely wipe out the previous values of all the registers! If you want to preserve them you'll have to make use of the stack as follows:

```

F5      PUSH AF
C5      PUSH BC
D5      PUSH DE
CDBEO2  CALL KSCAN
D1      POP DE
C1      POP BC
F1      POP AF

```

Now we want to turn these rather obscure numbers into real character codes. It just so happens that all of these codes are rather cleverly stored in the ROM beginning at address 007E. By "rather cleverly" I mean in a most convenient order, as follows: First the straightforward characters:

```
007E      XCV ASDFG QWERT 12345 09876 POIUY newline LKJH space .MNB
```

(There are no spaces between the characters - they are printed here to make the ordering more obvious.) Then the shift characters:

```
00A5      ;:/? STOP LPRINT SLOW PAST LIST "" OR STEP <- > EDIT AND THEN
          TO cursor-left RUBOUT GRAPHICS cursor-right cursor-up cursor-down
          ")(< >= FUNCTION +=- *% &,%< >=
```

Can you see how the ordering relates to which sections the key lies in? We could quite easily write a subroutine now to convert from the strange number we already have in HL to an address between 007E and 00CB (the last item in the table - the =) but it turns out that we don't need to because that nice man Uncle Clive has already done it for us with a subroutine which I shall call FINDCHR beginning at address 07BD. The ROM people probably have their own name for it but they keep it shrouded in mystery. The subroutine performs the following task - given a value as defined above, in the BC register, it will work out the address at which the appropriate character is stored - the final result ending up in HL.

It does have a problem though. If you're not pressing a key then surely you shouldn't end up with a character to print! You'll have to prevent this yourself. One way would be as follows. Notice though how we move the result from the first subroutine into the BC register before calling the second.

```

CDBEO2  START      CALL KSCAN
44      LD B,H
4D      LD C,L
51      LD D,C
14      INC D
3E00    LD A,00
2804    JR Z,NOCHR
CDBEO7  CALL FINDCHR
76      LD A,(HL)
...      NOCHR      ...
          rest of program

```

There are several things to note about this example. Firstly that two separate instructions, LD B,H and LD C,L, are needed to transfer HL to BC since there is no single instruction LD BC,HL. Secondly that the condition JR Z means if D is zero, not A - LD does not alter any of the flags. If D is zero after being incremented then it must have been FF beforehand, which means that L must have been FF after it came out of the first subroutine. This is the check that a key is being pressed. A is loaded with zero and if no key is pressed it remains zero, otherwise it takes on the code of whichever character you're touching on the keyboard.

There is here a slight ambiguity in that zero is also produced if you press space. You could use LD A,01 instead of LD A,00 since the character whose code is one (1) is not available from the keyboard. Now there is no ambiguity since zero means space and one means no character is being pressed. If you have SLOW at your disposal you could omit LD A,00 altogether and use JR Z,START instead of JR Z,NOCHR. Now the program will WAIT until a key is pressed before continuing. Without SLOW it will still wait but you'll have to suffer a blank screen in the meantime.

The A register now contains a value corresponding precisely to the function INKEY\$. In this way real time games are just as feasible in machine code as they are in BASIC.

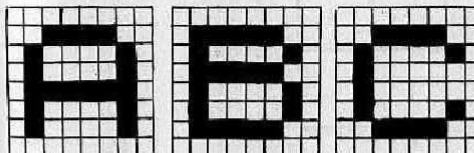
Another interesting part of the ROM is the very last bit - the half of a K that runs from 1E00 to 1FFF. It's not a subroutine, it's a table - a very long table - actually the longest table in the ROM. It stores the dot pattern of every symbol used by the computer - that is all of the printable characters. It takes eight bytes to store a single character symbol, so for example, the characters A, B and C are represented, in binary, by:

```

0 0 0 0 0 0 0 0    0 0 0 0 0 0 0 0    0 0 0 0 0 0 0 0
0 0 1 1 1 1 0 0    0 1 1 1 1 1 0 0    0 0 1 1 1 1 0 0
0 1 0 0 0 0 1 0    0 1 0 0 0 0 1 0    0 1 0 0 0 0 1 0
0 1 0 0 0 0 1 0    0 1 1 1 1 1 0 0    0 1 0 0 0 0 0 0
0 1 1 1 1 1 1 0    0 1 0 0 0 0 1 0    0 1 0 0 0 0 0 0
0 1 0 0 0 0 1 0    0 1 0 0 0 0 1 0    0 1 0 0 0 0 1 0
0 1 0 0 0 0 1 0    0 1 1 1 1 1 0 0    0 0 1 1 1 1 0 0
0 0 0 0 0 0 0 0    0 0 0 0 0 0 0 0    0 0 0 0 0 0 0 0

```

Can you pick the letters A, B and C from the digits above? The pattern is held by the positions of the "ones" amongst the "zeroes". When they finally appear on your TV screen they look like this:






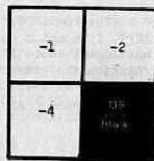
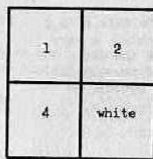
Suppose we now wished to reconstruct these letters in an enlarged form - using a pixel (quarter-square) for each dot. This means that each character we print should be a graphics character (space and inverse-space both count as graphics characters) chosen so that the correct quarters are black.

There are two ways of doing this. One is to make use of the NEW ROM character codes, in which the graphics are arranged in a very clever order - unfortunately we would not be able to adapt this system to the old ROM. The second is to include sixteen bytes of data within our program representing the graphics symbols in any order we care to choose. Let's take a look at the first method first.

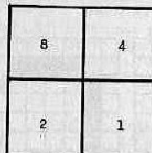
Suppose the bottom right corner is WHITE. If we give the other pixels numbers 1, 2 and 4 then simply adding them up gives the required character code. You can check this by comparing the diagram below with the character set in the Sinclair manual.


If the bottom right hand corner is BLACK then we need to give the other pixels the numbers -1, -2, and -4. To work out the code of any graphics symbol here we start off with the number 135 (decimal) and subtract appropriately the required number for each black pixel. Again you can check this by comparing the diagram below with the Sinclair Manual.

Incidentally it is worth pointing out here that many copies of the Sinclair Manual incorrectly give the character of 135 as . This is a misprint - it should of course be . Try typing PRINT CHR\$ 135 to check. Character seven is  - the manual gives this correctly.







The character code of the OLD ROM graphics symbols are unfortunately rather random, so there is no simple system for working out the code, given which pixels should be black and which should be white. In order that the program to follow should work on both ROMs we shall adopt a slightly different method. Instead of distinguishing two different cases (that is the colour of the bottom right-hand pixel) we shall treat every quarter-square the same, and code them as follows:



We would then have to include in our program a DATA section which lists the graphics symbols in the order space .

Move RAMTOP to address 4380 (this is a hex address) by typing POKE 16388,128 POKE 16389,67 then NEW. Now load the following program to address 4380. (In decimal this is 17280, meaning 1K users will still be able to run it.) As it stands this program is best run in SLOW. We shall see how to alter it so that it will run in FAST later.

```
00870485 DATA DEFN 
02850681 DEFN 
01860582 DEFN 
03840780 DEFN 
CDBB02 START CALL KSCAN
20 INC L
20FA JR NZ,START
```

This is the table of graphics symbols in the required order.  
Wait for human to take finger off of key.

```
CDBB02 WAIT CALL KSCAN
44 LD B,H
4D LD C,L
51 LD D,C
14 INC D
28F7 JR Z,WAIT
CDBB07 CALL FINDCHR
7E LD A,(HL)
A7 AND A
17 RLA
17 RLA
D8 RET C
17 RLA
1600 LD B,00
CBL2 RL D
5F LD F,A
21001E LD HL,OTABLE
19 ADD HL,DE
0804 LD C,04
0604 OUTERLOOP LD B,04
56 LD D,(HL)
23 INC HL
5E LD E,(HL)
23 INC HL
E5 PUSH HL
AF INNERLOOP XOR A
CBL2 RL D
17 RLA
CBL2 RL D
17 RLA
CBL3 RL E
17 RLA
CBL3 RL E
17 RLA
218043 LD HL,DATA
85 ADD A,L
6F LD L,A
7E LD A,(HL)
D9 EXX
C10808 CALL PRINT
D9 EXX
10E6 DJNZ INNERLOOP
E1 POP HL
3E76 LD A,76
D9 FFX
C70808 CALL PRINT
D9 EXX
0D DEC C
20D4 JR NZ,OUTERLOOP
18AF JR START
```

Wait for new key to be pressed.

Locate appropriate character code.

Multiply by eight, but return to BASIC if a non-printable character is pressed.

Find start of dot pattern.

Transfer two lines of dots into D and E

Compute which graphics character is to be printed.

Get this character from the table of graphics symbols.

Print this symbol

Next print position.

End of current line.

Next line begins. Start again.

The program is now complete. Make sure you are in SLOW mode and start the program off by typing RAND USR 17296. DO NOT type RAND USR 17280 since this is purely data and will not run. You should see a completely blank screen. Press "C", and watch what happens. Now press "A". Interesting isn't it? Try experimenting with different keys to see what happens - and what happens when you run out of screen?

You may have been confused by the use of the instruction EXX which was used four times in the above program. Its function is very easy to explain. As you know, the registers B, C, D, E, H, L, and A can be very easily

manipulated, but there are also seven other registers, called B', C', D', E', H', L', and A'. (Pronounced A-dash or A-prime.) These are not so easy to manipulate and can in practice only be used for storage purposes. The instruction EXX means exchange B and D', C and C', D and D', E and E', H and H', L and L'. Thus all the registers except A lose their previous values but take on the values of their alternative registers. Likewise the alternative registers take on the original values of the usual registers.

The reason we need to do this is because the ROM subroutine PRINT destroys the previous values of BC, DE, and HL. We could have preserved them by pushing them onto the stack, but EXX works just as well here and is only one instruction.

Let's take a closer look at the above program and sort out exactly what each bit does. First of all we find the right character code, which gets stored in the A register. The instruction AND A resets the carry flag to zero. RLA will then multiply A by two. Now we know that this character is on the keyboard and can be obtained in one touch, so it is not an inverse character. Rotating left then will move the leftmost bit, which must be a zero, into the carry flag. RLA a second time will again multiply by two (since we know the carry is zero), however, if the character is NOT PRINTABLE (such as newline or STOP) then bit 6 of the original value will be a one, this will now be moved into carry. The instruction RMT C ensures that if this circumstance ever occurs the program will terminate.

Knowing then that the carry is still zero we can use RLA once more to multiply by two. Here however, bit 5, which a necessary part of the character code, will be moved into the carry flag. To move the carry digit into B we use two instructions LD B,00 and LD D, D will then contain either zero or one. LD B,A ensures that register-pair DE now contains eight times the original value of A.

The other interesting part is the first nine lines of the INNER-LOOP. A is loaded with the first two bits of D and the first two bits of E. This gives a number between zero and fifteen which corresponds to the required graphics symbol. It is NOT the character code, it is the specially designed code we worked out earlier on. Notice how the NEXT bits of D and E are now automatically in place at the extreme left.

For those of you who do not have SLOW I suggest replacing the last instruction, JR START by RET. You could then have a surrounding BASIC program as follows:

```
10 RAND USR 17296
20 PAUSE 40000
30 RUN
```

#### THE SUBROUTINES

Old ROM users will by now be feeling quite envious at NEW ROM people for having these subroutines at their disposal. Of course there is a keyboard scan in the OLD ROM, but it isn't a subroutine - ie it doesn't end in RET. One call to it and you're stuck there forever! What we'll have to do is rewrite them ourselves. We can do this by taking all of the important bits from the subroutines in the NEW ROM.

First of all KSCAN. This is the required subroutine. Don't worry if there are parts of it you don't understand - all will become clear in due course.

```
21FFFF KSCAN LD HL,FFFF
01FFFF LD BC,FFFF
ED78 IN A,(C)
F601 OR 01
F680 OR 80
57 LD D,A
2F CPL
FE01 CF 01
9F SEC A,A
80 OR B
A5 AND L
6F LD L,A
7C LD A,H
A2 AND D
67 LD H,A
CB00 RLC B
ED78 IN A,(C)
36ED JR C,LOOP
1F RRA
CB14 RL H
C9 RET
```

Now - if you enter this subroutine into RAM you can then replace every CDB02 in the chapter by a call to the appropriate address in RAM. The other subroutine you'll need to be able to emulate is FINDCHR. This may be done as follows.

```
1600 FINDCHR LD D,00
CE28 SRA B
9F SBC A,A
F626 OR 26
2E05 LD L,05
95 SUB L
85 ADD A,L
37 SCF
CB19 RR C
36FA JR C,LOOP
0C INC C
C0 RET NZ
48 LD C,B
2D DEC L
2E01 LD L,01
20F2 JR NZ,LOOP
217D09 LD HL,KTABLE-1
5F LD B,A
19 ADD HL,DE
C9 RET
```

The address 007D, referred to in my listing as KTABLE-1, is for the NEW ROM only. THE ADDRESS OF KTABLE IN THE OLD ROM IS 006C, and so this line should be changed to LD HL,006B. This is far easier to understand than the first subroutine. The second and third lines are rather interesting.

If you remember BC should contain a code corresponding to one of the keys at the start of the subroutine. Now bit zero of B is a one if SHIFT is not pressed, and zero if shift is pressed. SRA B will shift B to the right, will set bit 7 to one (Do you remember the difference between SRA and SRL?), and will set the carry flag equal to the previous value of bit zero.

SEC A,A will first of all subtract A from A - effectively resetting it to zero - and will then subtract the carry flag. In other words, if SHIFT is pressed A will end up as 00, if SHIFT is not pressed A will end up as FF.

The fourth line, OR 26, will ensure that A is 26 for a shifted character, FF for a non-shifted character.

You should recall here that B contains information about which VERTICAL section the key is in, and C about which HORIZONTAL section. If you take a closer look at the order the characters are stored in the keyboard table (KTABLE) which was shown a few pages back you'll see that the horizontal-section-number needs to be multiplied by five, and the vertical-section-number added to it, in order to find a specific key in the table. This is what the next part does:

L is loaded with 5 - the multiplying factor. Notice how the next two lines cancel each other out the first time round the loop. This is one way of adding L, nought times should we need to. The next two lines are SCP and RR C. This is not the same thing as SRA C, since bit 7 could be zero. (ie if a horizontal-section-7 key is pressed.) Apart from shifting C to the right it also moves one bit into the carry. If this bit is a one we haven't found the right section yet and the loop is re-executed. Note that five is added each time round the loop. Note also that if A starts off as FF it is just as easy, if not easier, to think of it as minus-one.

Now that we're out of the loop, C should be all ones, that is, it should be FF, so that INC C should ensure that it becomes zero, so what's this PET NZ instruction for? Of course this condition is simply to check that you're not holding down two keys at once. What would C contain if you were?

LD C,B moves the vertical-section-data into the B register, so that the same loop may be used over again.

DEC L followed by LD L,1 looks confusing. Actually it's not. At the moment L is five, and so DEC L makes it four, which is NOT ZERO. LD L,1 doesn't alter the zero flag, so JR NZ,LOOP sends it back through the same loop, but this time checking the vertical sections, and only incrementing by one instead of five.

When it comes out of the loop DEC L will reduce to zero, so after reloading L with one JR NZ will not be satisfied and the program will continue.

LD HL,KTABLE-1. Why minus one? Well if there was a "real key" in the position where SHIFT is and you were pressing it then A would end up as zero. Since there isn't the smallest value A can end up as is one, which happens if you hold down "Z", hence LD HL,KTABLE-1 takes this into account.

LD B,A is effectively loading A into DE. This works because B is already zero - see the first line of the program. Then ADD HL,DE will find the correct address. Notice that we could have replaced these two instructions by ADD A,L followed by LD L,A. This has the advantage that the first instruction (LD B,00) becomes unnecessary, and that DE is not at all altered by the subroutine. The ROM however uses the version as listed.

KTABLE in the OLD ROM looks like this:

```
006C 210V ASDFC QWERT 12345 09876 POIUY newline LKJH space .MNB
0093 :17/ [ ] NOT AND THEN TO cursor-left RUBOUT HOME
      cursor-right cursor-up cursor-down *)($" edit +=- MN F,>< OR
```

for the actual printing process itself, the instruction CALL PRINT for the NEW ROM should be replaced by PUSH AF/CALL PRPOS/POP AF/CALL PRINT. In HEX this is F5/CDE006/F1/CD2007.

The Character Table (CTABLE) which gives the dot patterns for the characters is located in the OLD ROM at address 0E00, rather than 1E00. Again it is stored at the very end of the ROM. All of the characters are slightly different.

The data for the table of graphics symbols in the character printing program should run 00 07 06 03 05 82 08 84 04 88 02 85 83 86 87 80 if the program is to be used with an OLD ROM. Replace the PAUSE 40000 BASIC statement given in the following text by INPUT A\$

#### GRAFFITI

It only requires a slight modification to the original version in order to make a really excellent program, demonstrating the immense speed which machine code offers over BASIC. In this program, GRAFFITI, you touch a key and an enlarged version of the required symbol appears on the screen. In this program the whole screen is used (even the bottom two lines) thus allowing a total of forty-eight symbols on the screen. To load it move RAMTOP to any address not less than 4D00 and NEW (ie this can't be done in 1K - at least not in this version). The program is as follows.

2A0C40	GRAFFITI	LD HL,(D-FILE)	Set the print position
23		INC HL	to the start of the screen.
220E40		LD (DP-00),HL	
36B0	START	LD (HL),B0	Print a cursor
CD8B02	PAUSE	CALL KSCAN	Wait for human to take
2C		INC L	finger off of key.
20FA		JR NZ,PAUSE	
CD8B02	WAIT	CALL KSCAN	Wait for new key to
44		LD B,H	be pressed.
4D		LD C,L	
51		LD D,C	
14		INC D	
28F7		JR Z,WAIT	
CD8D07		CALL FINDCHR	Locate the correct
7E		LD A,(HL)	character code.
A7		AND A	
17		RLA	Multiply by eight, but
17		RLA	return to BASIC if a
D8		RET C	non-printable character
17		RLA	is pressed.
1600		LD D,00	
CB12		RL D	
5F		LD E,A	
21001E		LD HL,CTABLE	Find start of dot
19		ADD HL,DE	pattern.
0E04		LD C,04	
0604	OUTERLOOP	LD B,04	
56		LD D,(HL)	Transfer two lines of
23		INC HL	dots into D and E
5E		LD E,(HL)	
23		INC HL	
E5		PUSH HL	
AF	INNERLOOP	XOR A	Compute which graphics
CB12		RL D	character is to be
17		RLA	printed.
CB12		RL D	
17		RLA	
CB13		RL E	

```

17      RLA
CB13    RL E
17      RLA
21-data-address
85      LD HL,DATA
6F      LD L,A
7E      LD A,(HL)
2A0E40  LD HL,(DE-CC)
77      LD (HL),A
23      INC HL
220E40  LD (DE-CC),HL
10E3    JNZ INNERLOOP
D5      PUSH DE
111D00  LD DE,C01D
19      ADD HL,DE
220E40  LD (DE-CC),HL
D1      POP DE
E1      POP HL
9D      DEC C
20CF    JR NZ,OUTERLOOP
1180FF  LD DE,E780
2A0E40  LD HL,(DE-CC)
19      ADD HL,DE
220E40  LD (DE-CC),HL
7E      LD A,(HL)
FE76    CP 76
209B    JR NZ,START
116400  LD DE,0064
19      ADD HL,DE
220E40  LD (DE-CC),HL
17C      INC HL
ED581040 LD DE,(VARS)
ED52    SEC HL,DE
19      ADD HL,DE
385A    JR C,START
C9      RET

```

Get this character from the table of graphics symbols.

Print this character in required position. Store new print position.

Move print position ready for next row of symbols.

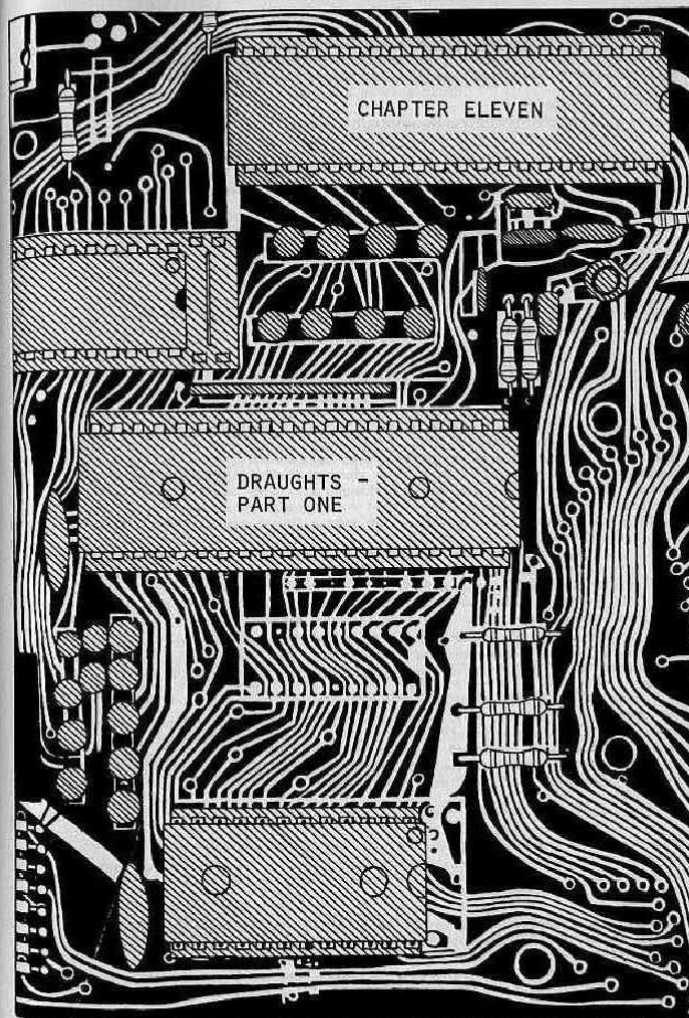
Move print position ready for next enlarged character.

Check for end of line.

Move print position to left of screen ready for next enlarged character.

Check for end of screen.

This program is intended to be run on a ZX81 in the SLOW mode. See if you can work out how to adapt it so that it will print inverse characters instead of ordinary ones. It may even be possible to offer a choice!



# **DRAUGHTS**

Now that we can enter and edit machine code, it's about time we started using it for something useful, and hopefully interesting. Draughts is a program we have to be very careful with. Here's what it will look like in BASIC:

```

1 INPUT A$
2 RAND/RANDOMISE USR(something)

```

As you can see, the vast, vast majority of it will be entirely in machine code. The machine code will begin immediately after the BASIC program ends. However, in order that we may edit it we shall temporarily store it a little higher up in memory than that - in the fourth K.

Also, in order that we may have the BASIC part of the program at the right location it will be necessary to MOVE the machine code part of HEXILD3. New ROM users should start typing POKE 16389,74, and then NEW, and then load the program HEXILD3.

Now, to move it, write the following program to the few spare characters at the end of the REM statement:

```

010002  MOVE    LD BC,0200
11004A    LD DE,4A00
210040    LD HL,4000
KDB0     LDIR
C9       RET          Run this.

```

Now for the tedious bit. Every address used in the machine code part either begins with 40 or 41. You'll have to go through the listing and change each 40 to a 4A, and each 41 to a 4B. (The changes are to be made in the copied version, not the original version.) That done, change every address in the BASIC parts that calls a USR routine. To make a change you must add 2560 to each number. Now delete line one by typing its line number. The program should still work, but now you'll need to type RUN 400 in order to SAVE it. Make sure that the variable BEGIN (Now at 4A3C or 4A93) contains a value of 4A00. New ROM users change line 500 to:

```

500 RAND USR (PEEK 16400+256*PEEK 16401+161) -In this way RETRIEVE is
called from within the variables area, ie address (VARS)*161.

```

Now type RUN 100 to start the WRITE routine and re-enter the board printing routine. Again you'll need to load it to address 4009. The listing is the same as it was before. Turn to chapter seven and simply retype the whole thing.

The instruction RAND USR 19477 should now print a picture of a draughts board in the top left hand corner of the screen. Try it and see. Now each part of this program will be explained in great detail, so don't worry if a program this size seems a daunting prospect. Right now we are only going to input the first part. It starts off with some data.

```

4C97  FAFB0605 TABLE  DEFB FA FB 06 05

```

This represents the directions in which we are about to allow moves. The numbers in the data are -6, -5, 6 and 5, which, in the board numbering system the computer will use, are simply the numbers we add to one square to reach another.

The first, and simplest thing to do, is to make a copy of the board as it appears on the screen. The copy is called WKBOARD, for it is the part of RAM on which the computer will do its working out. The address of WKBOARD is to be 407C. That's not a misprint, it really does say four zero three C. For OLD ROM users this is just beyond the end of the BASIC part of the program, but for NEW ROM users it is slap bang in the middle of the system

variables. Is this wise?

We will in fact be overwriting the 33 byte area FREEBUF and part of the calculating store MEMBOT. This doesn't matter since we will not be using LPRINT, not be attempting to use floating point calculations, and in fact not using this area at all. This will not cause a crash.

During the construction of this program, OLD ROM users should use the address 4B3C instead, since 403C is in mid-program. You can always change it when the program is complete.

Here's the copying routine. You should load this to address 4CE4.

```

2A0C40  BOARDCOPY LD HL,(D-FILE)  Make a copy of the board
110D00    LD DE,000D             from the screen to the
19        ADD HL,DE              working area.
113C40/4B LD DE,WKBOARD
062A    LD B,2A
EDA0    NSCOPY  LDI
23      INC HL
10FB    DJNZ,NSCOPY
C9      RET

```

Notice the way LDI was used instead of LDIR. This is a very useful way of saving space. What we are doing is incrementing HL each time round, so that only the black squares are copied, not the white ones. This loop is repeated 2A (forty-two) times, since in addition to the squares on the board, one or two characters from the border are also copied. Notice that although LDI decrements BC, it is C that is decremented, not B, so that the DJNZ instruction will still count correctly.

OLD ROM users can easily check that the routine is working by listing from 4B3C using HEXILD3, after the program is run. NEW ROM users can check by replacing the RET instruction to LD HL,WKBOARD/LD (ADDRESS),HL/JF HLIST. You must not return to basic (NEW ROM users that is) since FREEBUF will be wiped out by doing so. You can quite safely return after you've listed.

The next part of the program is just as simple. If you take a look at the board printing program, you'll see that the last thing printed is a row of fourteen spaces. What this is is a "window" in which our machine code program can display messages to the user, so the next thing to do is to fill this window with spaces in order to wipe out any error message that may have been there.

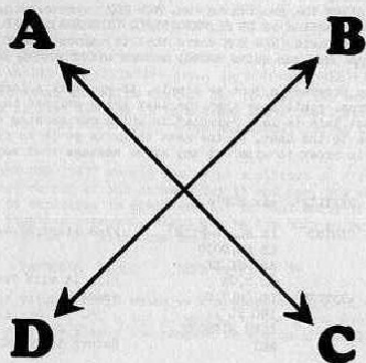
```

4CF5  000000  NEXTLINE six NOP's
4CF8  000000
4CFE  2A0C40  CLWIND  LD HL,(D-FILE)  Find start of window.
4D01  117000    LD DE,0070
4D02  19        ADD HL,DE
4D04  060E    LD B,0E             Fill it with fourteen
4D06  3600  WIPROUT LD (HL),00   spaces.
4D07  23      INC HL
4D09  10FB    DJNZ WIPROUT
C9      RET          Return to BASIC.

```

Notice that we have actually overwritten the previous routine's RET instruction, so that it will automatically continue into this one. The next part is for NEW ROM users only. OLD ROM users please ignore it.

	1	2	3	4	5	6	7	8	
1		W		W		W		W	1
2	W		W		W		W		2
3		W		W		W		W	3
4									4
5									5
6	B		B		B		B		6
7		B		B		B		B	7
8	B		B		B		B		8
	1	2	3	4	5	6	7	8	



The following will cause line one (that is BASIC line one) to be re-executed as soon as the next RET instruction is received. Note that this overwrites the six NOPs in the previous section.

```

ACF5 217D40 NEXTLINE LD HL,FIRSTLINE
ACF8 222940          LD (NEXTLIN),HL

```

This fools the ROM into thinking that the next line to be executed begins at address 407D, which is the first byte of the program. It doesn't return to BASIC immediately however, it will continue with draughts until a RET instruction is reached.

Now the program seriously starts. We assume that a move has been input as AB, which is the first item in the variable store.

Here's how to input a move. Look at the diagram of the board. There are sixty-four squares, but only thirty-two of them are playable. Each square has a coordinate from 11 to 88. Notice that these are printed without separation. The first digit refers to the number down the left (and right) hand side of the board, and the second digit refers to the number along the top or bottom of the board.

There are four different directions you may move in. These are called A (up-left), B (up-right), C (down-right) and D (down-left). This is indicated on the diagram. To input a move simply type in the coordinates and a letter (A, B C or D). There should be no spaces in this input. For instance, to move from square 61 to square 52 you should input "61B".

Now for a program to interpret this input. Follow this carefully:

```

4D09 2A1040 (NEW ROM)  MOVE
      2A0840 (OLD ROM) LD HL,(VARS)
      23              INC HL
      7E              LD A,(HL)
      3D              DEC A
      3D              DEC A
      3D              DEC A
      2001            JR NZ,NOTZERO
      2F              CPL
4D14 5F              NOTZERO LD E,A

```

A small amount of additional explanation concerning the input here, which applies to OLD ROM users only. To input a simple move, such as from 61 to 52, you in fact need to input "shift W space 61B". A simple move must always be preceded by shift W space, and this also applies to single jumps. Double jumps, triple jumps etc are a little different, and we shall cover them later. As I have said, this is for OLD ROM users only.

The above routine initially loads A with the length of the input string, and then subtracts three, so that for an ordinary move A ends up as zero, for a double jump A ends up as one, for a triple jump A ends up as two, and so on. Then IF A is 00 it is changed to FF. This is so that we can check up on whether or not a player has made a move, or a jump, later on in the game.

This quantity, which is ordinarily FF, is stored in the register E. We then continue.

4D15	25	INC HL	The first character of the
	25	INC HL	coordinates is found.
	7E	LD A,(HL)	
	47	LD B,A	This number is multiplied
	87	ADD A,A	by eleven, since the board
	4F	LD C,A	on screen is eleven char-
	87	ADD A,A	acters across.
	87	ADD A,A	
	25	INC HL	The position within the
	E5	PUSH HL	string is stored.
	80	ADD A,B	
	81	ADD A,C	
	86	ADD A,(HL)	The next coordinate is added.
	1F	RRA	Divide by two, since the
			copy contains only the black
			squares.
3805		JR C,NOERROR1	If the coordinate points to
			a black square there is no
			cheating.

In the above routine the first coordinate is multiplied by eleven, by making use of registers B and C, and then the second coordinate is added. Note that if you input "12" as your square then because of the Sinclair character codes the program thinks that the first coordinate is actually 1D, and that the second coordinate is 1E. This actually leads to a result of 5D. Rotating right gives 2E, together with a carry indicating that the player has not cheated by giving a white square instead of a black one. The next five bytes deal with what happens if the player has cheated. These are

4D25	E1	ERROR1	POP HL	Restore the stack pointer.
	CDA74C		CALL ERROR	Call to an error message
	1D		DEPM 1	subroutine.

The subroutine ERROR, which requires one byte of data (here the byte 1D, the character code of "1") looks like this:

4C9B	2E31312A	IMOVE	DEPM 11LE	These are the words "ILLEGAL
	2C265100		DEPM GAL	MOVE" - data to be printed.
	32345B2A		DEPM MOVE	
4CA7	E1	ERROR	POP HL	Fetch the byte of data
	7E		LD A,(HL)	
	2A0C40		LD HL,(D+FILE)	Find the start of the window.
	117000		LD DE,0700	
	19		ADD HL,DE	
	EB		EX DE,HL	
	219B4C		LD HL,IMOVE	Copy the words onto the
	010C00		LD BC,000C	screen.
	EDB0		LDIR	
	15		INC DE	Print the byte of data onto
	12		LD (DE),A	the screen.
	C9		RET	Return to BASIC.

Notice what happens. The message "ILLEGAL MOVE 1" appears on the screen, and no piece is moved. The player is then required to re-input her move which will then be checked in exactly the same way.

If no error is found (yet) the program continues.

4D2A	C60E	NOERROR1	ADD A,OE	Find the position of the
				square in WKBOARD.

OE is simply the required factor to exactly match A to the low part of the address of the working-board square. For instance, adding OE to 2E gives 3C, and 403C is the start of WKBOARD.

4D2C	6F		LD L,A	
	2640/4B		LD H,WKBOARD-high	
	4E		LD C,(HL)	Find which piece is on
				that square.
	0680		LD B,80	Replace that square by a
	70		LD (HL),B	black empty square.
4D35	E3	LOOP	EX (SP),HL	Store the square position,
				and retrieve the pointer
				to the input string.
	25		INC HL	
	227B40		LD (PTRNTR),HL	Store this value.
	7E		LD A,(HL)	
	C671		ADD A,71	Find the direction being
	6F		LD L,A	moved from the TABLE.
	264C		LD H,TABLE-high	
	56		LD D,(HL)	
	E1		POP HL	Retrieve square position.
	78		LD A,B	Check whether the player is
	A2		AND D	moving one of her own pieces,
	2F		CPL	and in a legal direction.
	A1		AND C	
	FE27		CP 27	
	20DE		JR NZ,ERROR1	

A brief explanation of the last six lines here. A is loaded by 80. D is the direction to be moved, which will be FA, FB, 05, or 06. AND D will therefore produce 00 for a backward direction, and 80 for a forward direction. CPL will change this to FF or 7F. C is the piece to be moved. If it is a black king it will be 27, if it is a black piece it will be A7, so AND D will produce a value of 27 if EITHER the piece being moved is a king, OR if the piece is moving forwards. If you try to move a piece backwards, or give a square which does not contain one of your own pieces, then a value of 27 will NOT be produced. In this case the program will send an "ILLEGAL MOVE 1" error message.

4D48	7D		LD A,L	Find destination square.
	82		ADD A,D	
	6F		LD L,A	
	7E		LD A,(HL)	Check the contents of that sq.
	B8		CP B	Is it an empty square?
	2008		JR NZ,NEXT	
	7B		LD A,E	If so, is this a single
	3C		INC A	move?
	2815		JR Z,CONTINUE	
	CDA74C		CALL ERROR	If not a single move, give
	1E		DEPM 2	"ILLEGAL MOVE 2" message.
4D57	B0	NEXT	OR B	
	FEBC		CP BC	Does square contain a comp-
	2804		JR Z,NOERROR3	uter's piece?
	CDA74C	ERROR3	CALL ERROR	Give message "ILLEGAL MOVE
	1F		DEPM 3	3" if not.
4D60	70	NOERROR3	LD (HL),B	Overwrite computer's piece
				with a black empty square.
	7D		LD A,L	Find next destination
	82		ADD A,D	square.
	6F		LD L,A	

4D64	7E	CONTINUE	LD A,(HL)	Find the contents of the new square.
	B6		CP B	Is this square empty?
4D68	20F4		JR NZ,ERROR3	Give "ILLEGAL MOVE 3" if not.

At this stage the program will jump or move as the case may be (in other words it will decide for itself - you don't need a special input) and will so far check for three types of error. These are:

- 1) Attempting to move a piece that is not your own, or moving one of your own non-king pieces backwards.
- 2) Attempting to make a non-jump move in the middle of a multiple move sequence.
- 3) Attempting to move to a square which is non empty.

You may like to check all of these things. This isn't too difficult to do. Simply write JP 4DDE to the end of the program and add the following routine.

4DDE	2A0C40	REPRINT	LD HL,(D-FILE)
	110D00		LD DE,000D
	19		ADD HL,DE
	EB		EX DE,HL
	213C40/4B		LD HL,KBBOARD
	062A		LD B,2A
	ED40	LDI	LDI
	13		INC DE
	10FB		DJNZ LDI
	C9		RET

This will copy the computer's working-board back onto the screen so that you can see what has happened. You can also alter the data for the board-print routine, and so set up a board in mid-game in order to test some of the error checks if you want.

To make the program run, add the following BASIC program lines.

OLD ROM	NEW ROM
1 INPUT A\$	1 INPUT A\$
2 RANDOMIZE USR(19683)	2 RAND USR 19683
3 RUN	3 STOP
4 RANDOMIZE USR(19477)	4 RAND USR 19477
5 RUN	5 RUN

The program is activated by the command RUN 4. Don't forget you can still use HEXLED3 to list, but you must now use RUN 10 to bring this into operation. If you type RUN on its own accidentally you will get an input prompt. Break out immediately! If you don't this results will be unpredictable. I don't think it will crash, but just to be on the safe side....

And now a check to determine whether or not the human player has reached the other end of the board. If so, this next routine will automatically change her piece into a king.

4D68	7D	CONTINUE	LD A,L	If the low part of the
	FE40		CP 40	current address is less than
	300C		JR NC,NOKING	40hex then the other side
				has been reached.
	7B		LD A,E	If this is not the last
	3C		INC A	move then give an "ILLEGAL
	FE02		CP 02	MOVE 4" message.
	3804		JR C,NOERROR4	
	CDA74C		CALL ERROR	
	20		DEPN 4	

0E27	NOERROR4	LD C,27	Make piece a king.
71	NOKING	LD (HL),C	Put back on board.
85		PUSH HL	Store current position on board.

Notice the new error check. If a player attempts to make a king in mid-move, that is, if she jumps to the back row and intends to jump out again in the same go, then an error will be detected and "ILLEGAL MOVE 4" printed to the screen. This is because according to official rules a piece does not become a king until after you remove your fingers from it. Of course in this game your fingers are never on the piece in the first place, but we presume that this is what the rules are intended to mean.

Remember that E contains FF for a single jump, and 01 for a double jump. LD A,E/INC A/CP 02 will only give an error if E is one or more. If E is 00, (which if you've input a multiple jump it will eventually be) the move will go ahead successfully.

4D7B	2A7B40	LD HL,(POINTER)	Retrieve the position pointed to in the input string.
	1D	DEC E	Decrease the number of moves left in a multi-jump seq.
	7B	LD A,E	Check whether last move has been made.
	E3	EX (SP),HL	
	17	RLA	
	30AB	JR NC,LOOP	The input pointer is replaced at the top of the stack ready for the next time round the loop.
	E1	POP HL	
4D85	C3DE4D	JP EDPRINT	Exit.

Well, all of the possible error checks have been made, and the program contains a loop which will allow for the inputting of multiple jumps. Here's how a multiple jump should be input. To jump from square 63 first in direction A, then in direction B, then finally in direction C, just input "63ABC" - it's that simple. OLD ROM users need to note the following convention though:

OLD	single moves or single jumps should be preceded by shift W space.
ROM	double jumps should be preceded by shift E space.
ONLY	triple jumps should be preceded by shift R space.
	4-ply jumps should be preceded by shift D space.

And so on... The sequence is W, E, R, D, F, S, A, T, G. I doubt very much whether you'll ever need a 4-ply jump though. Even using a triple jump seems rather unlikely.

The next thing that should happen is that the computer should make a move in response, but we'll leave that to another chapter, since it has a bit of decision making to do. But there is one question to be answered first. What if it now has no pieces left to move? What if the player's last move removed its last piece? This has to be checked for. If this is the case then the player has won, and we must somehow indicate this.

Here is the final check:

4D85	0EBC	LD C,BC
4D87	CDEC4C	CALL GAMBOVER
4D8A	C3DE4D	JP EDPRINT

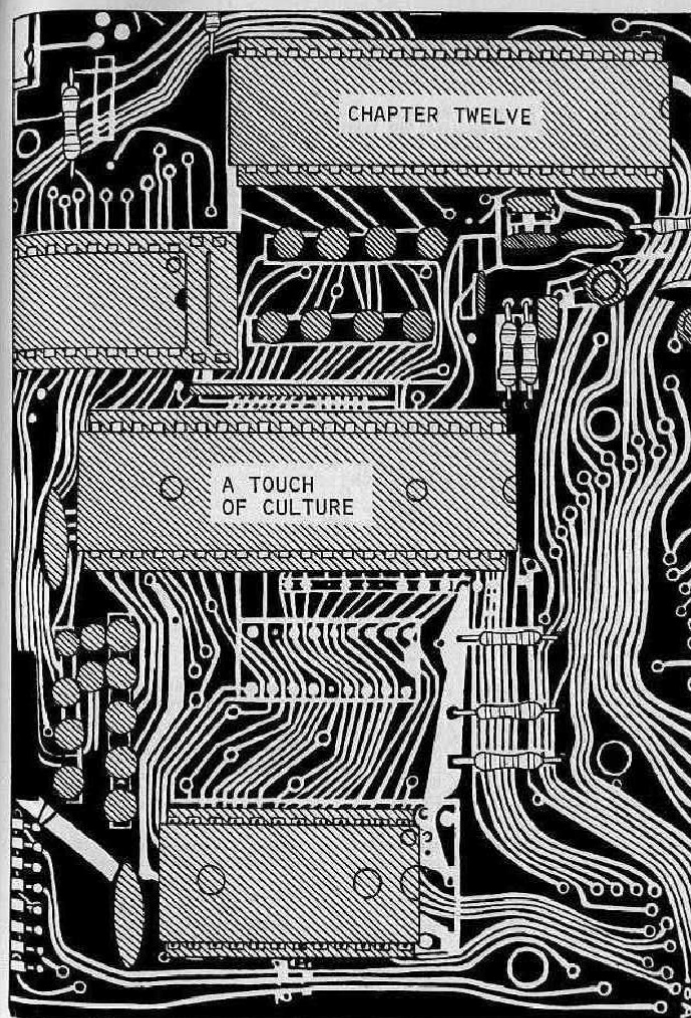
And the subroutine....

4CBC	213C40/4B GAMEOVER	LD HL,WKBOARD	Look at first square,
062A		LD B,2A	
7E	POSSIBLY	LD A,(HL)	Find contents of square.
F680		OR 80	Make it an inverse graphic.
B9		CP C	Is it what we're looking
C8		RET Z	for? If so we're OK and
			can return to draughts.
23		INC HL	Look at next square.
10F8		DJNZ POSSIBLY	Try again.
4CC9	the next six bytes are for the new rom only. Old Rom users should		
	replace them with six NOPs (00).		
219740	STOPPROC	LD HL,STOPLINE	Fool the ROM into thinking
222940		LD (NEXTLIN),HL	that line 3 is to be carried
			out next.

Now we reach the exciting bit. What happens if the player HAS won? I'm not actually going to tell you - just input it and find out. To test it you'll have to alter the data that sets up the initial board, and arrange it so that you can take all of the computer's pieces.

4CCF	240C40	INVERT	LD HL,(D-FILE)
066C			LD B,6C
23	COVER		INC HL
7E			LD A,(HL)
F625			CP 25
3006			JR NC,NOINV
A7			AND A
2803			JR Z,NOINV
F680			OR 80
77			LD (HL),A
1CF2	NOINV		DJNZ COVER
E1			POP HL
C9			RET

Notice how, in the last two lines the return address is removed from the stack, so that the next item on the stack is the return to BASIC address. The next RET will of course do just that.



## MUSIC

Music from your TV speaker? Is it possible? More to the point - is it possible on a ZX? The answer is yes!

As you know, your machine is designed to work without sound. It does make a kind of horrible buzzing noise, but hardly anything you'd want to make music out of. The manual itself tells us to turn the volume right down so as to cut the noise out completely.

The little computer, on the other hand, has a mind of its own. Completely ignoring its own design specifications it thinks to itself "Anything a bigger computer can do, I can do better", and as a result of this rebellion you'll find that **REAL MUSICAL NOTES** can be produced with just a tiny speck of machine code.

Those of you who have tried the music routines in Interface are undoubtedly thinking to yourself "Huh! I've heard this so called 'music' - it's rubbish!" Well I assure you this is not the same thing. The reason? Well one big advantage machine code does have over BASIC is precision - and this program is in machine code, not BASIC. The music is musical. You can even tune it if you have a tuning fork handy.

This is called **CATHY'S PROGRAM**, dedicated to someone who believes computers should be artful, not just attack you with space invaders. The machine code is best stored in a REM statement. The addresses given in the listing assume you have a **NEW ROM** machine. If you have an **OLD ROM** machine all you have to change is the addresses (although you will have to supply two of the subroutines yourself - see chapter ten)

### Cathy's Program

9B897369	NOTES	C D E F	This data represents
00937E005E		- C* D* - F*	the various notes that
001B312824		- C D E F	are available from the
0000362C00		- - C* D* -	keyboard.
00000F161E		- - A* C* F*	
000A0C121A		- C B A G	
000000414C		- - - A* C*	
00383C4653		- C B A G	
78	PAUSE	LD A,B	Subroutine causing a
3D	HOLD	DEC A	delay of a precise
20FD		JR NZ,HOLD	length.
C9		RET	
call here → CDBB02	START	CALL KSCAN	Wait until a key is
44		LD B,H	pressed.
4D		LD C,L	
51		LD D,C	
14		INC D	
28F7		JR NZ,START	
CDBD07		CALL FINDCHR	Find which key is being
110440		LD DE,NOTES-7E	pressed.
19		ADD HL,DE	
46		LD B,(HL)	Select note.
AF		XOR A	
B8		CP B	Check that this note is
28EB		JR Z,START	not a "pause".
D8FF		IN A,(FF)	Play this note.
CDA940		CALL PAUSE	
D3FF		OUT (FF),A	
CDA940		CALL PAUSE	
18E0		JR START	Go round loop again.

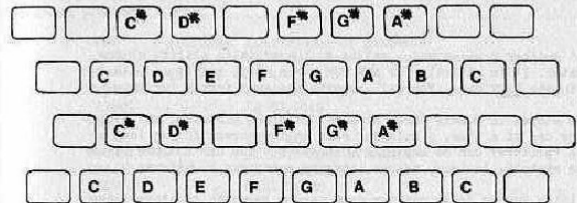
If you store the whole machine code routine in a single REM statement in line one, then you only need one more line of BASIC to make the program complete. This is line 2 RUN USR 16558, which calls the machine code from the address labelled START. Delete any extra lines you may have, and SAVE the program a couple of times before you RUN it.

You now have two octaves at your disposal - the keyboard below shows where the notes are. A fair number of tunes may be played quite successfully.

Always run the program in the FAST mode - it's not that the speed makes the notes sound different - it's simply that the program doesn't work AT ALL when in SLOW.

The notes as listed in the program are roughly right, but exactly how they sound will depend mainly on your television set, (incidentally you may have to alter the tuning slightly to get the best sound quality,) so in case you need to "re-tune" the notes, here's how you do it:

The data at the start of the program (labelled NOTES) contains one byte for each note. A zero indicates there is no note on that key. The data is in the following order:



data	key	note
9B 89 73 69	Z X C V	C D E F lower octave
00 93 7E 00 5E	A S D F G	- C* D* - F* lower octave
00 5B 31 28 24	Q W E R T	- C D E F upper octave
00 00 36 2C 00	1 2 3 4 5	- - C* D* - upper octave
00 00 0F 16 1E	0 9 8 7 6	- - A* G* F* upper octave
00 0A 0C 12 1A	P O I U Y	- C B A G upper octave
00 00 00 41 4C	n l K J H	- - - A* G* lower octave
00 38 3C 46 53	ap . M N B	- C B A G lower octave

to alter the frequency of any note just change the byte of data that represents it. To make a note higher you must decrease the number, and to make it lower you must increase the number.

## THE PROGRAM'S DISADVANTAGES

(And how you can cure them)

The biggest disadvantage is the lack of a RET instruction anywhere in the program, which means that once you enter the program you can never leave. You can cure this by adding a few lines somewhere near the START label. As an exercise, see if you can adjust the program so that it returns to BASIC whenever the key SHIFT-ZERO (rubout) is pressed. (HINT: HL equals PCEP when it returns from KSCAN)

The second disadvantage is that if you press SHIFT while playing notes some very random things seem to happen. See if you can make the shift key inactive (except for breaking out as described above) by adding a SET 0,H instruction somewhere in the program.

XX Music is a fascinating subject, and it is possible to store in data a list of notes to be played, and how long each note is to be played - a tune in other words. I'll leave that one to you though, because the only real way to learn is by experiment. We'll leave the subject of music altogether now and turn to something slightly different: pictures....

## PICTURES

This is yet another program which relies on the artistic ability of the human operator. It is strictly for NEW ROM users ONLY, but it is intended to be run in the FAST mode. You will require at least four-K for this.

The program stores in memory three or more different pictures, and cycles through them one at a time, displaying each on the screen for as long as you want. A "picture" can be anything whatsoever - you can compose it out of graphics symbols, letters, spaces, inverse asterisks - whatever.

The first thing you do is to reserve some memory in which to store these pictures. If you have 4K type POKE 16588,182/POKE 16589,70/NEW for three pictures, or POKE 16588,206/POKE 16589,75/NEW for two pictures. If you have 16K you can find enough room for about twenty pictures. To work out how far down you have to move RAMTOP with 16K just start off with 32768 and subtract 793 for each picture.

Now you're ready: Write the following machine code to a REM statement in line one:

```
2A0C40  STORE  LD HL,(D-FILE)
11B646      LD DE,PICTURE1
011903      LD BC,0519
EDB0        LDIR
C9          RET
```

The address labelled PICTURE1 refers to those people using 4K. For those same people PICTURE2 would be 49CE and PICTURE3 would be 4CE7. If only two pictures will be used you should omit PICTURE1, not PICTURE3. If you have 16K you have more or less limitless freedom. In the interests of simplicity you could use addresses 5000, 5400, 5800, 5C00, and so on.

Now type POKE 16389,77 followed by CLS if you are using 4K, or if you are using 16K but earlier POKED 16389 with a number less than 77.

Now write a BASIC program (without deleting line one) which prints a picture. The last line of this program should be RAND USR 16514. 4K users may find themselves running out of space. If this is so you'll just have to give up and make do with two pictures instead of three.

A useful fact to know is that if you make the first line of your program (first apart from the REM that is) POKE 16418,0 then you can print to all twenty-four lines of the screen. Even PRINT AT 23;0; works!

Now delete all the PRINT lines. DO NOT TYPE NEW. Change the address in the machine code to that of a different picture, and write a new BASIC program printing a different picture, again ending in RAND USR 16514. Do this until every picture you wish to cycle through has been stored.

Now move RAMTOP back to the address described in paragraph three Type NEW. Now you are ready....

For the first time in the book we are going to make use of the PAUSE facility. The instruction CALL PAUSE will display the TV picture indefinitely, or until a key is pressed. To PAUSE for a specific number of TV frames it is necessary to LD (FRAMES) with the required number first. Enter this machine language program:

```
0602  PICTURES LD B,number of pictures
21B646 LD HL,address of first picture
C5     NEXTPIC PUSH BC
ED5B0C40 LD DE,(D-FILE)
011903 LD BC,0519
EDB0    LDIR
E5      PUSH HL
21C0001 LD HL,length of pause
225440  LD (FRAMES),HL
ED2902  CALL PAUSE
E1      POP HL
C1      POP BC
10EB   DJNZ NEXTPIC
C9      RET
```

This is the complete program. See how it works - the first picture is copied into the display file using LDIR, and the PAUSE subroutine is called from the ROM. Then when the PAUSE is over the next picture is copied onto the screen, and so on. The value of HL is not changed between each picture, since they are stored in memory immediately after each other. If they are not (for instance if you are using easy to remember addresses) you'll need to alter the program slightly. HL should point to the start of a new picture each time round the loop.

The BASIC program to go with this is

```
10 RAND USR pictures
20 RUN
```

In this way you can break out of the program at the end of the sequence. Alternatively you could replace the last RET instruction by JR PICTURES, which would eliminate the need for a second BASIC instruction. You can of course always break out during a PAUSE.

## LIFE

In the last program in this chapter we turn the tables slightly. We humans have been artistic for long enough - now it's time to let the computers take their turn....

This program is called **LIFE** - it is supposed to represent the birth/growth/death cycle of a colony of cells living on a square grid. It produces rather fascinating results. Before your very eyes you see a constantly evolving pattern - starting off totally random - which finishes sometimes with the ultimate death of the cell colony, sometimes with a fixed and unmoving cell structure which has reached equilibrium, and sometimes with a continuous cycle of patterns, called dynamic equilibrium. It really is amazing to watch.

**LIFE** was invented in 1970 by a man called John Conway of Cambridge University, and it's rather surprising that the Tate Gallery hasn't yet got a copy of it. Although it is in fact about the growth of cells which follow hard and fast mathematical rules it in reality becomes a rather effective pattern generating algorithm.

The principle of **LIFE** is very simple. A grid - usually square - is dotted with approximately one quarter of its available squares filled with cells. These positions are usually chosen entirely at random. This configuration of the grid is called **GENERATION ZERO**.

Successive generations are then worked out by a fairly simple to understand principle. Each square on the grid has eight neighbouring squares. These squares either contain another cell or they are empty. Every cell with two neighbouring cells; or with three neighbouring cells, will survive to the next generation, but no other cells will survive. A new cell is born in every empty space which has precisely three neighbouring cells, but no other cells are born. With these fairly simple rules it is rather surprising that the game should produce the rather impressive results that it does.

In this version of **LIFE** our grid is sixteen by sixteen, because of course sixteen is a fairly easy number to work with in hexadecimal. Further, our grid is rather strangely constructed in a curved space continuum, meaning that every square on the left hand edge is connected to the corresponding square on the right hand edge, and vice versa, also every square on the top edge is connected to the corresponding square on the bottom edge and vice versa.

The program is best run in **SLOW**, although of course it will run in **FAST** if you add a **PAUSE** or **INPUT** statement.

**NEW ROM** people are advised to store the machine code in a **REM** statement. **OLD ROM** people are advised to store the machine code anywhere but a **REM** statement, since it contains characters 76h. The machine code contains exactly one hundred and thirty nine bytes.

The surrounding **BASIC** program is

```
2 RAND USR START
3 RAND USR NEXTGEN
(4 PAUSE 25 or INPUT A$ - optional extra for FAST users)
5 GOTO 3
```

where **START** and **NEXTGEN** are addresses in the machine code program. In the following listing we assume that the first address is 4062. You can quite easily change it if you wish.

EF010110	TABLE	DEFB EF 01 01 10	Data representing the displacements
10FF7FF0		DEFB 10 FF FF F0	of the neighbouring squares.
call here			
0E10	START	LD C,10	C counts the number of rows printed.
0610	NEWROW	LD B,10	B counts the number of columns.
2A5240	NEXT	LD HL,(SEED)	This next section generates a
54		LD D,H	random number.
5D		LD E,L	
29		ADD HL,HL	
29		ADD HL,HL	
19		ADD HL,DE	
29		ADD HL,HL	
29		ADD HL,HL	
29		ADD HL,HL	
19		ADD HL,DE	
225240		LD (SEED),HL	The new random-number-seed is stored.
7C		LD A,H	
FECA		CP C4	Decide which character to print, based
3804		JR C,BLACK	on choice of random number.
3EB4		LD A,B4	
1802		JR CHAR	
3E80	BLACK	LD A,80	
D7	CHAR	RST 10	Print this character.
10E3		DJNZ NEXT	Same for the next character in the row.
3E76		LD A,76	
D7		RST 10	Print a newline symbol at the end
0D		DEC C	of the row.
20DB		JR NZ,NEWROW	Same for next row.
C9		RST	Generation zero printed completely.
0600	NEXTGEN	LD B,00	B counts the number of cell positions.
110043		LD DE,DUMP	DE stores the start of the working-
			area used to compute the next gen.
2A0C40		LD HL,(D-FILE)	
E5		PUSH HL	Stack the start of the display-file.
7E	COPY	LD A,(HL)	Copy the current generation (but not
23		INC HL	newlines) to the working space.
FE76		CP 76	
28FA		JR Z,COPY	
12		LD (DE),A	
13		INC DE	
10F6		DJNZ COPY	
110043		LD DE,DUMP	Stack the start of the dump.
D5		PUSH DE	
0E00	NEXTCELL	LD C,00	C Counts the number of neighbours a
			particular cell has.
D1		POP DE	
E1		POP HL	
7E		LD A,(HL)	Skip over the next character in the
FE76		CP 76	display file if it is a newline.
2001		JR NZ,VALID	
23		INC HL	
E5	VALID	PUSH HL	
EB		EX DE,HL	Store the position within the dump of
E5		PUSH HL	the cell being examined in HL, and
			also stack it.

119240		LD DE, TABLE	Point DE to table of displacements.
1A	NEXDIS	LD A, (DE)	Find displacement.
FE0E		CP OE	If this "displacement" is OE we have
280B		JR Z, COUNTED	reached the end of the table.
13		INC DE	Point DE to next item in table.
85		ADD A, L	Find neighbouring cell-position.
6F		LD L, A	
7E		LD A, (HL)	Is there a cell there?
FE84		CP B4	
20F3		JR NZ, NEXDIS	
0C		INC C	Increase count if so.
18F0		JR NEXDIS	
E1	COUNTED	POP HL	Retrieve cell position.
79		LD A, C	
FE02		CP 02	Are there less than two neighbours?
380F		JR C, NOCELL	If so no cell appears.
FE04		CP 04	Are there four or more?
300B		JR NC, NOCELL	If so no cell appears.
FE03		CP 03	Are there precisely three?
2803		JR Z, CELL	If so, a cell does appear.
7E		LD A, (HL)	
1806		JR PUT	
3E84	CELL	LD A, B4	
1802		JR PUT	
3E80	NOCELL	LD A, 80	A now contains the right character.
E3	PUT	EX (SP), HL	Retrieve print position.
77		LD (HL), A	Print character.
23		INC HL	Move print position along one.
E3		EX (SP), HL	Retrieve cell-position.
23		INC HL	Look at next cell-position.
E5		PUSH HL	Stack this position.
7D		LD A, L	Check the value of L to find out
A7		AND A	whether or not we have printed the
20FF		JR NZ, NEXTCELL	last cell-position.
E1		POP HL	Restore the stack to its original
E1		POP HL	state and return to BASIC
C9		RET	

If you used the same addresses as in the listing then START is 16522 and NEXTCEN is 16562. SAVE the program. Do not RUN it yet because if you do it will crash! NEW ROM users MUST first of all type POKE 16380, 67 followed by NEW, and OLD ROM users should ensure that they have at least 2K of memory. You will then have to reLOAD the program from tape.

The first thing you should type is RAND/RANDOMISE. You may now type RUN.

An interesting point about this program is that it is capable of producing its own random numbers. The part labelled NEXT does this - you should study how this is achieved, and by all means use the same principle in your own programs.

LIFE will print out a randomly constructed generation zero in just ONE SECOND when in the SLOW mode. The successive generations will then be produced at the staggering rate of three and a half generations per second! If you find this is much too rapid you can slow it down by adding a few more lines of BASIC - I suggest LET X=0/LET X=X+1/PRINT AT 17,0;X with the last two being inside the loop - this has the added advantage of telling you how many generations have been shown.

Finally you should follow the manner in which this program, unlike some other LIFE programs, calculates each new generation entirely on the basis of the previous one. It does not work out the new first row and then calculate the second row by counting the neighbours in the now-changed new first row, the second row is determined by the previous status of the first row, (this is what the area of memory labelled DUMP in the machine code listing is for), thus each new generation is correctly set up.

There are many other pattern generating programs, some much simpler, but none with the elegance of LIFE. If you own 16K you might like to try writing a 24 by 24 LIFE, or even a 24 by 32 version - remember, in machine code there is nothing to stop you printing on the very bottom two lines.

The biggest LIFE you could possibly hope to achieve is 48 by 64 using white quarter-squares for cells, but that would be quite a complicated program. If you feel really enthusiastic you might like to have a bash at this monumental task. I will let that decision rest with your sanity.

The next chapter completes the discussion on DRAUGHTS and leaves you with the horrifying prospect of completing the program....



# DRAFTS

This is the section which decides upon which is the "best" move the computer can make, after the human's move.

You may have to follow this thinking we are about to embark upon very carefully. Here in brief is a systematic breakdown of the way in which the move is chosen.

We scan the board, one (black) square at a time, and whenever we find a computer's piece we sit and think about it for a bit. To each move we find possible we assign a numerical value, such that the bigger the number, the better we think the move is. It then follows that to select a move we merely have to choose the one with the highest possible value.

Of course this idea won't let the computer plan ahead - it can only think one move at a time. In order to construct this list of moves, and accompanying numerical values we don't actually have to store every single move we find. Having located a possible move, and worked out its score, what happens is this:

If the score is LOWER than those on the list, the move is ignored.

If the score is EQUAL to those on the list, it is added to the end.

If the score is HIGHER than those on the list, then the list is abolished and a new one started.

In this way the list is always as short as it can possibly be. When the final decision time actually arrives the computer now merely has to select one of these moves at random. Next question - where will the list be stored? Answer The Stack. This simplifies things, but it does mean that we must keep a record of where the start of the list is. We shall store this at address 407B (OLD ROM 4022) and call this quantity LBASE. You will notice that in an earlier part of the program we used 407B/4022 to store a quantity called POINTER. Don't worry - this is quite alright. POINTER is not used in the previous section, and its value does not need to be preserved. LBASE was not used in the last section, and again its value does not need to be preserved. Using the same space twice for two different things is a space-saving trick you should get to know.

The decision making of the computer begins at address 4DBA. The first instruction is LD (LBASE),SP. The start of the list is now preserved. We can play around with the stack now as much as we like, as long as we remember to restore its value before we return to BASIC. The second and third instructions are LD BC,0000 and PUSH BC, which will indicate that there is nothing at all in the current list.

The checking loop thus looks like this. Notice that a new variable SQCHK is used, it is listed as residing at 4077, but OLD ROM owners should replace this address by 401C:

4DBA	ED737B40	BOARDSCAN	LD (LBASE),SP	Initialise the list.
	010000		LD BC,0000	
	C5		PUSH BC	
	213C40		LD HL,WKBOARD	Scan the board, one square
	7E	NXTCHK	LD A,(HL)	at a time.

F680	OR 80	
FEEC	CP BC	Have we found a computer's
		piece?
227740	LD (SQCHK),HL	
CA434E	JP Z,EVALUATE	
2A7740	LD HL,(SQCHK)	
2C	INC L	Have we reached the end
7D	LD A,L	of the board yet?
FE66	CP 66	
20EC	JR NZ,NXTCHK	Loop back if not.

As you can see, this particular bit is quite straightforward. You only need to (temporarily) add a few extra instructions to avoid crashing. These are:

4E43	C3D54D	EVALUATE	JP 4DD5	These additional lines
4DA9	C3D54D	CHOOSE	JP 4DD5	are temporary only. They
4DD5	ED7B7B40		LD SP,(LBASE)	will stop the program
4DD9	0EA7		LD C,A7	crashing, but will not
4DDB	CDB4C		CALL CAMEROVER	run it.

Can you see that loading SP with (LBASE) eliminates the need to POP everything from the stack before returning. LDING SP will fool the machine into thinking that the stack hasn't changed since we went into the loop.

Now we need to think about what form we want the list to take. Let's examine the problem in reverse. What form would we like the list to take, in order to make removing items from the stack easier.

The first item on the stack should be the number of steps involved in the move - that is one for a single move/jump, two for a double jump, three for a triple jump, and so on. The second item should be the numerical value which the items in the list have been assigned - the priority as we shall call it. Following these items of information we should have the list itself, starting with the square to be moved from, followed by a sequence of one or more directions in which to be moved, immediately after this the second item in the list in the same form, then the third, and so on...

You'll notice that each thing we need on the stack will only need to be one byte in length. The number of steps cannot possibly be more than 255. The priority can be chosen however we like - we can always make it one byte if we wish. The initial square can be stored by only stacking the low part of its address in WKBOARD. The directions to be moved can be stored in the same manner as before - 05, 06, FA, or FB for plus or minus five or six. In order to make this program as space efficient as we can it makes sense to do just that.

To make a random decision let's assume there are B possible choices. We want therefore to choose a random number between 1 and B - or as we shall do between 0 and B-1. We shall do this by the following means:

4DA9	3A3440	CHOOSE	LD A,(FRAMES)low	Select a random number
	90	REPEAT	SUB B	between 0 and B-1. This
	30FD		JR NC,REPEAT	number to be stored in
	80		ADD A,B	the A register.
	C3D54D		JP 4DD5	

OLD ROM users should replace the address 4034 by 401E. The final JP 4DD5 is merely a means of exiting the program.

Imagine the list is complete and we are about to remove one item from it. The stack now looks like this:

no. of steps	priority	initial square	direction one	initial square	direction one	direction one
↑ sp						↓ lbase

If we now use the instruction POP BC, B will contain the priority, and C the no. of steps. The priority is now a redundant piece of information, since it was only needed to construct the list in the first place. C however is very important. In the diagram above C would be one, but it doesn't have to be.

The stack now looks like this - but let's generalise a bit more by assuming there are two steps per move, not one:

initial square	direction one	direction two	initial square	direction one	direction two	direction two
↑ sp						↓ lbase

If A is an indication of which of these moves we are to choose then it seems logical that we must remove A of them from the stack. Then the required move would be at the top of the stack. Thus if A is zero we do nothing, otherwise we must use some kind of loop. Can you see that POP HL followed by DEC SP will remove one byte from the stack rather than two, and that INC SP can be used to skip over one of the bytes.

The required loop is this:

4DB0	C1	POP BC	Find the number of steps per move.
41		LD B,C	
2808		JR Z,FIRSTOFF	Do nothing if A is zero.
33	NSQOFF	INC SP	Remove a total of A complete moves from the stack.
33	NEXTOFF	INC SP	
10FD		DJNZ NEXTOFF	
41		LD B,C	
3D		DEC A	
20F8		JR NZ,NSQOFF	

The selected move is now at the top of the stack. To carry it out let's first take a look at what the stack is now like:

initial square	direction one	direction two	.....
↑ sp			

To find the initial square the sequence is POP HL followed by LD H,WKBOARD-high. You see "initial square" is the low part of the address. By assigning H with the high part we ensure that the register pair HL contains the absolute address of the square from which we must move. H must be assigned after the POP HL instruction though, since there is no real way we can manage to remove L on its own. Finally the instruction LD B,C once more will assign B with the number of steps we have to make. The procedure for carrying out these steps is much simpler than before since we don't have to check for cheating - we shall write the program such that the computer cannot cheat.

4DBA	E1	FIRSTOFF	POP HL	Find the absolute address from which we must move.
2640			LD H,WKBOARD-high	

To remove one direction at a time from the stack we shall use the sequence DEC SP/POP DE. In this way E will be assigned with the required direction. D will contain useless information.

4DBF	41	LD B,C	
3B	NEXTSTEP	DEC SP	Find which direction the computer is to move.
DL		POP DE	Get computer's piece.
4E		LD C,(HL)	Overwrite with black sq.
3680		LD (HL),80	Find destination square.
7D		LD A,L	
83		ADD A,E	
6F		LD L,A	
7E		LD A,(HL)	Is this square empty?
FEB0		CP 80	
2805		JR Z,SQUARE	If so, move.
3680		LD (HL),80	If not, jump.
7D		LD A,L	
83		ADD A,E	
6F		LD L,A	
71	SQUARE	LD (HL),C	Put piece in position.
10EB		DJNZ NEXTSTEP	Same for next direction.

You should now be at address 4DD5, at which is stored the sequence

4DD5	ED7E7B40	LD SP,(LRASE)
	CEA7	LD C,A7
	CDEB4C	CALL GAMDOVER
4DEE	2A0C40	EDPRINT LD HL,(D-FILE)
	...	
		and so on down to
4DF0	C9	RET.

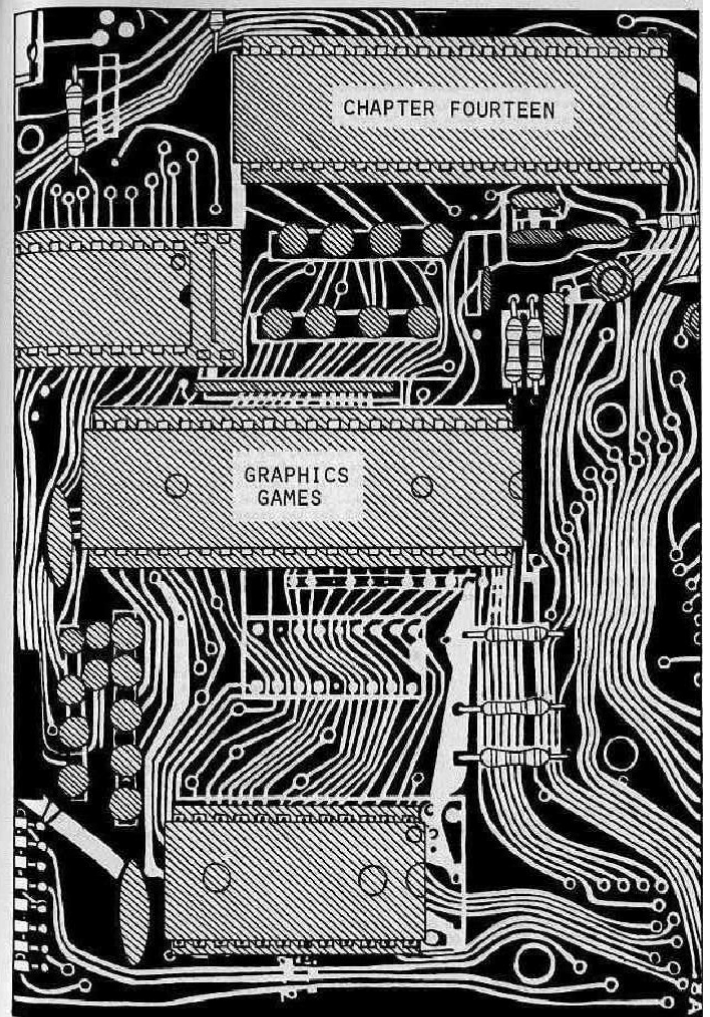
This means that provided the stack is correctly set up we can actually see this whole mechanism working. What I want you to do now is to write a short routine to set up the stack so that all of the possible opening moves are stored. You should be able to do this all by yourself. I will tell you though that the routine should be placed at address 4B43 (what will eventually be the EVALUATE routine) and should be terminated by the instruction JP CHOOSE (C3A94D). One way of doing this bit would be LD HL,something/PUSH HL/LD HL,something/PUSH HL/and so on, but if you can think of a better way by all means use it.

You may now RUN the draughts program by typing RUN 4. You will be asked for an input - make your move as you have been doing in the past. Now watch what happens to the computer's side - one of the pieces should move! Break out of the program, since as yet it can only decide upon the first move of the game.

Now RUN it again - again by typing RUN 4. Does the computer make the same move? If it does it's purely coincidence, since choosing from the list is done at random. Try again, and again, remembering to break out of the program each time and re-run. You should get a different result each time.

We'll leave the program at this stage and continue later on with the mechanism of setting up the stack correctly in the first place, and actually deciding which moves are better than others.

In the next chapter we'll look at some complete (and short) games designed to demonstrate what machine code can achieve in terms of speed, and in very few bytes compared with BASIC.



# SPIRALS

In this fant moving real-time graphics game (intended for use with SLOW) you are placed at the start of a square spiral and must reach the end of it in the minimum possible time. Your score is constantly displayed - it starts at 99900 and decrements continuously, but you can't cheat by breaking out early with a high score - the program won't allow that. Now and again the score will reach zero before you reach the end of the spiral. If that happens you obviously need more practice!

This fascinating and highly amusing game is unfortunately for NEW ROM users with SLOW only. It will not work in FAST because although the program will still consider itself to be running perfectly smoothly, the average human operator won't know what's going on because of the fact that the screen in front of them is completely black.

This is a fascinating game to watch - witnessing the score decrease before your very eyes is surprisingly effective. You can make the game as difficult as you like by altering the initial value of the "timing" - held in BC. I've given it 0400, but you could use 0800 for a slower game, 0200 for a faster game, and so on.

There is one difficulty built in though - if you hit a wall you don't just bounce off, you actually become embedded in it, and the only way you can get out is to exactly reverse your direction. It can be quite tricky.

Well good luck on your race - keep a record of the high scores (no cheating) and see if you can master it.

The keys will move you as follows: Any key on the bottom row will move you downwards (except for shift, which has no effect), any key on the top row moves you up. The middle two rows move you left and right, with the left-hand ten keys (QWERTASDFG) moving you to the left, and the ten right-hand keys (YUIOPHJKL;/) moving you to the right. This system was adopted instead of using the cursor controls 5, 6, 7, and 8 for two reasons.

- 1) It is easier for people to understand and become familiar with.
- 2) It is easier to program, since we only need to test one register after the keyboard scan instead of two.

The program lists as follows, and can be relocated to any desired location by changing just one address. The program should be called from the point labelled START.

E1	SPRINT	POP HL	This subroutine prints
7F		LD A(HL)	out a picture of the board,
23		INC HL	along with your initial
E5		PUSH HL	score. It must however be
FFFF		CP FF	provided with a list of
C8		RET Z	data terminated by FF.
D7		RST 10	
1CF6		JR SPRINT	
CD-sprint START	CALL SPRINT		Calls the subroutine. The
			following is data for the
			subroutine.

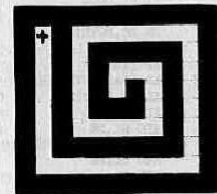
```

DEFB 80 80 80 80 80 80 80 80 80 80 76
80 15 80 00 00 00 00 00 00 00 76
80 00 80 00 80 80 80 80 80 80 76
80 00 80 00 80 00 00 00 80 80 76
80 00 80 00 80 00 80 00 80 80 76
80 00 80 00 80 80 80 00 80 80 76
80 00 80 00 00 00 00 00 80 80 76
80 00 80 80 80 80 80 80 80 80 76
80 00 00 00 00 00 00 00 00 00 76
80 80 80 80 80 80 80 80 80 80 76
76
3E 34 3A 37 00 38 28 34 37 2A 00 33 34 3C 00 25 25 25 1C 1C FF
    
```

2A0C40	SETUP	LD HL, (D-FILE)	
110E00		LD DE, 000E	
19		ADD HL, DE	
227B40		LD (POSITION), HL	
210000		LD HL, 0000	
227940		LD (LASTMOVE), HL	
2A0C40	LOOP	LD HL, (D-FILE)	
118B00		LD DE, 000B	
19		ADD HL, DE	
7E	DECIMAL	LD A, (HL)	
A7		AND A	
2008		JR NZ, POSITIVE	
0605		LD B, 05	
23	RESET	INC HL	
361C		LD (HL), 1C	
10FB		DJNZ RESET	
C9		RET	
3D	POSITIVE	DEC A	
FE1B		CP 1B	
2005		JR NZ, OK	
3625		LD (HL), 25	
2B		DEC HL	
18EA		JR DECIMAL	
77	OK	LD (HL), A	
010004		LD BC, SPEED	
0B	DELAY	DEC BC	
78		LD A, B	
B1		OR C	
20FB		JR NZ, DELAY	
CDBB02		CALL KSCAN	
7D		LD A, L	
2F		CPL	
6F		LD L, A	
E681		AND B1	
2805		JR Z, NOTDOWN	
110C00		LD DE, 000C	
181C		JR CHXMOVE	
7D	NOTDOWN	LD A, L	
E618		AND 18	
2805		JR Z, NOTUP	
11F4FF		LD DE, FFFF	
1812		JR CHXMOVE	
7D	NOTUP	LD A, L	
E660		AND 60	
2805		JR Z, NOTRIGHT	
110100		LD DE, 0001	
1808		JR CHXMOVE	
7D	NOTRIGHT	LD A, L	
E606		AND 06	
26B2		JR Z, LOOP	
11FFFF		LD DE, FFFF	
2A7940	CHXMOVE	LD HL, (LASTMOVE)	
7D		LD A, L	
B4		OR H	
2807		JR Z, MOVE	
19		ADD HL, DE	
7D		LD A, L	
B4		OR H	
2802		JR Z, MOVE	
18A1		JR LOOP	

This section initialises the two "variables" used in our program.

Decrement the score.



A timed delay. Altering the initial value of BC changes the speed of the game.

Scan keyboard. L now contains a value corresponding to the direction required.

Find direction.

Is player embedded in wall?

If so, is player reversing?

```

2A7B40 MOVE LD HL,(POSITION) Reassign square with black
7E LD A,(HL) or white space as required.
E680 AND 80
77 LD (HL),A
19 ADD HL,DE Find new position.
7E LD A,(HL) Draw black or white cross
F615 OR 15 as appropriate.
77 LD (HL),A
227B40 LD (POSITION),HL
210000 LD HL,0000 Store direction moved if
17 RLA a wall has been hit.
3002 JR NC,NOTHIT
62 LD R,D
6B LD L,E
227940 NOTHIT LD (LASTMOVE),HL
2A0C40 LD HL,(D-FILE) Check to see whether the
113600 LD DE,0056 finishing square has been
19 ADD HL,DE reached.
ED5B7B40 LD DE,(POSITION)
ED52 SBC HL,DE
C8 RET Z
C3-loop JP loop

```

#### BREAKOUT

In this version of BREAKOUT, which incidentally may only be run on a NEW ROM in SLOW, you move the bat with any of the keys on the keyboard - those on the left will move you to the left, and those on the right will move you to the right. The game is intended to be played only by those people with 3½K or more, but it can be persuaded to run in less if the following few lines of machine code are added to the program - these should precede the main program:

```

FD362200 EXTRA LD (IY+22),00
210003 LD HL,0300
AF SPACES XOR A
D7 RST 10
2B DEC HL
7C LD A,H
B5 OR L
20P9 JR NZ,SPACES

```

The reason for this is that the main BREAKOUT program assumes that the screen is initially completely full - that is, that it contains twenty-four rows, each consisting of thirty-two spaces followed by a newline. If your machine has less than 3½K on board then this will not be so, because of the way that the ROM sets up the screen. To rectify this we first LD (IY+22) with 00. IY is always 4000 at the start of any USR routine, so IY+22 is 4022, which is the systems variable DE-SZ. This represents the number of rows in the bottom half of the screen (the part we cannot print to) - by telling the machine that this number is zero it follows that the number of rows that we cannot print to is also zero, thus the whole screen is at our disposal. HL counts the number of spaces to be printed to ensure that we do not try to run off the end of the screen.

BREAKOUT is a program in four parts. These parts are 1). Initialise everything. 2). Restart the game for each new ball. 3). Move the ball. 4). Move the bat. We will go over each of these steps in scrutinous detail.

Firstly to initialise everything. This involves a) printing the playing board, b) defining the initial ball position, and c) setting the initial speed of the game. To print the board:

128

```

20002200 TABLESTART DEFW 0020 0022
E0FFDEFF DEFW FF80 F4DE
2A0C40 BREAKOUT LD HL,(D-FILE) Load all of the bricks into position.
118500 LD DE,0085
19 ADD HL,DE
018080 LD BC,8080 B is the number of bricks, C is a
23 NXBRK INC HL constant used quite frequently in
7E LD A,(HL) this section.
F876 CP 76
28FA JR Z,NXBRK
3608 LD (HL),08
10F6 DJNZ NXBRK
2A0C40 LD HL,(D-FILE) Put top wall in position.
061E LD B,1E This part puts in the first thirty
23 NXBL INC HL blocks.
71 LD (HL),C
10F6 DJNZ NXBL
23 INC HL
369C LD (HL),9C The current score - zero - is entered.
23 INC HL
71 LD (HL),C The last block is set in place.
23 INC HL
23 INC HL
111F00 LD DE,001F DE is one more than the number of
0617 LD B,17 spaces between the walls.
71 SIDES LD (HL),C Both side walls are loaded into
19 ADD HL,DE position.
71 LD (HL),C
23 INC HL
23 INC HL
10F9 DJNZ SIDES
0620 LD B,20 Now the base-line is drawn in.
361B BASE LD (HL),1B
23 INC HL
10FB DJNZ BASE

```

You'll notice that in this version of the game I've ensured that a row of full stops is printed below the very bottom of the screen. This provides a convenient test for whether or not the ball has hit the base. Finally, to set the ball position and speed, the procedure is:

```

111CFE LD DE,FEFC This is the displacement from the
19 current print position to the ball's
223C40 ADD HL,DE starting point.
210009 LD (BALLINIT),HL Locate this starting point.
224640 LD HL,0900 Store it.
LD (SPEED),HL This is the initial speed.
Store it.

```

This is actually all the initialisation we need. You'll notice several things missing - for example although the ball is located it is not actually printed. The bat is not mentioned at all! The reason is that the bat is redrawn every time the game is restarted, and so is the ball. Why bother to find the initial position then? Well in this version, the ball starts off in a slightly different position each time. This ensures that it is possible to wipe out all of the bricks.

The variable SPEED has a dual purpose. Firstly it determines the speed of the game - that is, the speed at which the bat and ball will move (the bat moves at precisely twice the ball speed), but secondly it determines when the game is over. When SPEED decrements to zero (the lower the number, the faster the game) we know that the game is over.

129

Section two of the game does the following tasks. a) change the initial ball position, whilst also noting the current ball position and printing the ball. b) Set the initial direction of movement of the ball to up/right. c) change the speed of the game and check for end of game. d) print the bat, and at the same time delete any previous bat symbol that may have been there. e) give the human player a chance to recover from the last session, since presumably she won't want one ball to leap into the game immediately the last one vanishes. The section is this. Look at the manner in which the bat is printed and the previous bat overwritten.

```

2A3C40  RESTART  LD HL,(BALLINIT)  Change the starting position of
23      INC HL              the ball.
223C40  LD (BALLINIT),HL
224040  LD (BALLPOS),HL      Start the ball here.
3634    LD (HL),34         Print the ball.
21B0FF  LD HL,FF80         Set the initial direction.
224440  LD (DIRECTION),HL
3A4740  LD A,(SPEED)high  Increase the speed
3D      DEC A
03      RET 2             Return to BASIC if lives have run
324740  LD (SPEED)high,A   out.
2A0C40  LD HL,(D-FILE)    Reprint the bat in its starting
11B702  LD DE,02B7        position
19      ADD HL,DE
3600    LD (HL),00
3E03    LD A,03           A contains the bat symbol.
23      INC HL
77      LD (HL),A
23      INC HL
77      LD (HL),A
23      INC HL
77      LD (HL),A
224240  LD (BATPOS),HL    Store the initial bat position. (This
23      INC HL            is the position of the centre of the
77      LD (HL),A         bat.
23      INC HL
77      LD (HL),A
0618    LD B,16
23      INC HL
3600    LD HL,00          Now erase the rest of the row, in
10FB    DJNZ ERASE        case a previous bat symbol remains
210000  LD HL,0000        there.
1803    JR DELAY          Set a very long delay, for the player
                          to recover for the next ball.

```

The last two lines, which cause a short pause between sessions, will become clear when the start of the next section is given.

To move the ball we first of all go through a timed delay loop (controlled by SPEED - the speed of the game) and then unprint the previous position of the ball. The contents of the next square in the direction the ball is travelling are examined, and one of the following will happen:

If a full stop has been reached then the ball has gone off the bottom of the screen - the game is restarted.

If either a space (ie nothing hit) or a brick is located, the ball is reprinted, at this new position.

If anything other than a space is reached, the direction of movement of the ball is changed at random.

If the ball was not reprinted then find the contents of the next square in this new direction and re-examine the situation.

If a brick was hit, the score is increased by 1.

130

Now, in order that we may choose a new random direction validly we require a table of directions to choose from. These valid directions are 0020, 0022, FF80, and FFDE. You should store these numbers, low part first, at any address in RAM, and call the start of this table TABLESTART. The program which will then achieve all of this is as follows:

```

2A4640  LOOP    LD HL,(SPEED)  This is a short delay loop which
2B      DELAY    DEC HL        controls the speed of the game.
7C      LD A,H
B5      OR L
20FB    JR NZ,DELAY
04      INC B
CB40    RIT 0,B
205A    JR NZ,MOVEBAT
2A4040  MOVEBALL LD HL,(BALLPOS) The ball is only moved every other
3600    LD (HL),00           time round the loop, so that the
ED5B4440 LD DE,(DIRECTION)   bat moves twice as fast as the ball.
19      ADD HL,DE           The current ball position is found.
7E      LD A,(HL)          Erase the ball.
FE1B    CP 1B              Find the next position of the ball.
28A6    JR Z,RESTART       position.
4F      LD C,A             Has the ball hit the base?
E6F7    AND 77             Start next ball if so.
2005    JR NZ,DONTMOVE     Only reprint the ball if the new
3634    LD (HL),34         position is either empty or contains
224040  LD (BALLPOS),HL    a brick.
B1      OR C               Retrieve previous contents
283E    JR Z,MOVEBAT       Change direction if not a space.
B5      PUSH HL
2A3240  LD HL,(SEED)       Generate new direction at random.
54      LD B,H
5D      LD E,L
29      ADD HL,HL
29      ADD HL,HL
19      ADD HL,DE
29      AND HL,HL
29      ADD HL,HL
19      ADD HL,DE
223240  LD (SEED),HL
7C      LD A,H             Choose this direction from a
B606    AND 06             table.
06tablestartlow  ADD A,06tablestartlow
6F      LD L,A
26tablestarthigh LD H,06tablestarthigh
5E      LD E,(HL)
23      INC HL
56      LD D,(HL)
ED534440 LD (DIRECTION),DE
E1      POP HL
79      LD A,C             If the contents of the square is
FE08    CP 08              not a brick, then move again.
20FB    JR NZ,MOVEBALL
2A0C40  LD HL,(D-FILE)     Having established that a brick has
111F00  LD DE,001F        been hit, the score is increased by
19      ADD HL,DE          one.
7E      LD A,(HL)
FE80    CP 80
2002    JR NZ,DIGIT
3E9C    LD A,9C
3C      INC A
FE46    CP A6
2005    JR NZ,INCREASED
369C    LD (HL),9C
2B      DEC HL
18EF    JR CARRY
77      INCREASED LD (HL),A

```

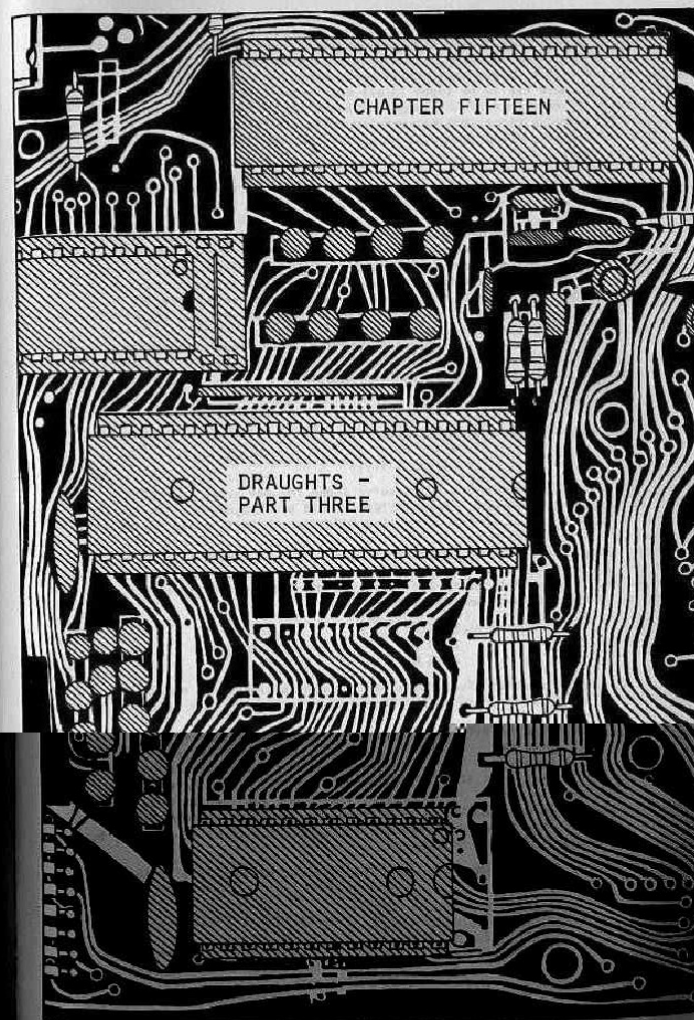
131

An interesting point to watch for is the way in which the score is increased. Compare the mechanism to that used in SPIRALS to decrease the score. There are one or two differences between this and the last. Firstly of course we are here using INVERSE digits instead of ordinary digits, though this difference is rather trivial. Secondly the BREAKOUT score increases instead of decreases. Thirdly, the SPIRALS score would terminate at zero, whereas the BREAKOUT score can increase indefinitely.

To move the bat, first of all the keyboard is scanned, and if a left-hand key is pressed the bat is moved to the left, provided of course there is not a wall in the way, and if a right-hand key is pressed then the bat is moved to the right, if possible. Note that if a left and right key are pressed simultaneously the bat should not move at all. In our program such a circumstance would cause the bat to move first to the left, and then to the right.

Study this, the final part of the program, and watch the way the bat is actually moved. Remember that the variable BATPOS stores the position of the middle of the bat.

C5	MOVERAT	PUSH BC	Preserve the value of B.
CDEB02		CALL KSCAN	Scan the keyboard.
C1		POP BC	
7D		LD A,L	
2F		CPL	
F5		PUSH AF	Stack contains a value corresponding
E60F		AND 0F	the key pressed.
2817		JR Z,NOTLEFT	If the player moves left....
2A4240		LD HL,(BATPOS)	Locate the bat.
2B		DEC HL	
2B		DEC HL	
2B		DEC HL	
7E		LD A,(HL)	Is there a wall to our left?
F8B0		CP 80	If so, don't move.
2829		JR Z,CYCLE1	
3603		LD (HL),03	Extend the bat to the left.
23		INC HL	
23		INC HL	
224240		LD (BATPOS),HL	Store new bat position.
23		INC HL	
23		INC HL	
23		INC HL	
3600		LD (HL),00	Decrease bat to the right.
F1	NOTLEFT	POP AF	
E6F0		AND F0	
2819		JR Z,CYCLE2	If the player moves right....
2A4240		LD HL,(BATPOS)	
23		INC HL	
23		INC HL	
23		INC HL	
7E		LD A,(HL)	Is there a wall to the right?
F8B0		CP 80	If so don't move.
280E		JR Z,CYCLE2	
3603		LD (HL),03	Extend bat to the right.
2B		DEC HL	
2B		DEC HL	
224240		LD (BATPOS),HL	Store new bat position.
2B		DEC HL	
2B		DEC HL	
2B		DEC HL	
3600		LD (HL),00	Decrease bat to the left.
E5		PUSH HL	Same for next time round.
E1	CYCLE1	POP HL	
C3100	CYCLE2	JP LOOP	



# INSTRUCTIONS

The story so far... Once upon a time a human being input a move to a ZX computer. The computer checked this move to make sure that no cheating was going on, and cast a wicked spell on the poor human if it was which meant that the whole move had to be typed in all over again. The move was made. The computer started to search through the board for pieces that it could move. Having found a piece, but not knowing whether or not it could move, it then miraculously found itself at an address called EVALUATE. Where do we go from here?

Let's start off by saying that a neutral move - that is a move which achieves nothing, but also loses nothing - has a "priority" of 80. (hex).

The first point worth noting is that if a piece is in imminent danger of being captured then it stands to reason that we ought to move it out of the way - unless something more important crops up. Secondly, if a piece is preventing another piece from being captured, then we should be less likely to move it. Both of these conditions apply regardless of which direction we consider moving the piece. It stands to reason then that we should work out this part of the priority first, before we start analysing each of the different directions. We must therefore work out a numerical value that corresponds to the square that we are looking at. This value will then be added to 80, after which each direction in turn will be analysed.

EVALUATE will therefore start off

```
4013 CDF14D EVALUATE CALL SQUAREVAL
      C680 ADD A,80
      522140 LD (INITIAL),A
```

The last instruction stores the value we've found for use later on in the game. On the OLD ROM the address of INITIAL should be changed to 4019. Now let's take a closer look at the subroutine SQUAREVAL. It will assign a value as follows - starting with zero, if a piece is in danger it will add five, or seven for a king. If it is protecting a piece it will subtract five, or seven for a king. Further, the subroutine, as with all subroutines from now on, must not be allowed to alter the values of any register except A. One way of doing this is to begin the subroutine

```
4DF1 C5 SQUAREVAL PUSH BC
      D5 PUSH DE
      E5 PUSH HL
```

Here is the complete subroutine. Follow it through carefully. It should be sufficiently annotated for you to make sense of exactly what it's doing.

```
C5 SQUAREVAL PUSH BC Store the current value of the
D5 PUSH DE registers on the stack, to be
E5 PUSH HL retrieved at the end of the subroutine.
0600 LD B,00 B is being used as a flag here. The
first time round the loop it will be
zero, the second time round it will be one. Watch the checks on B
carefully. The loop will check for protection the first time round, but
for danger the second time round.
```

11974C STARTOFF: LD DE, TABLE DE is a pointer, which points to the
table of directions of movement.

1A NOWT LD A,(DE) C now contains such a direction.

4F LD C,A

D62E SUB 2E If this "direction" is 2E we have passed
282A JR Z,EXIT the end of the table. We should exit
with value zero.

1C INC E Move pointer to next direction in table.

E1  
E5  
2640

POP HL  
PUSH HL  
LD H,40

L contains the low part of the current square. We retrieve it without altering the stack, and reassign H to the high part of this address.

7D  
81  
CB40  
2001  
81  
6F  
3E7F  
B1  
A6  
FE27  
20B5

LD A,L  
ADD A,C  
BIT 0,B  
JR NZ,LA  
ADD A,C  
LD L,A  
LD A,7F  
OR C  
AND (HL)  
CF 27  
JR NZ,NOWT

Find square to be looked at in this direction. Watch how B affects what happens.

7D  
91  
6F

LD A,L  
SUB C  
LD L,A

Watch how A is constructed here. If a human's piece is present A will end up as 27 UNLESS that piece is a non-king which can't move toward us. Then it will produce A7. No other piece can generate the result 27.

7E  
37  
17  
CB40  
2006  
FE79  
20D7

LD A,(HL)  
SCF  
RLA  
BIT 0,B  
JR NZ,LB  
CF 79  
JR NZ,NOWT  
LD A,(HL)

This is another way of checking for a computer's piece regardless of whether or not it is a king, but watch the carry flag.

17  
3F  
3E81

RLA  
CF  
LD A,81

Now notice the clever way we decide on 5 for a piece, or 7 for a king.

17  
CB40  
2006

RLA  
BIT 0,B  
JR NZ,LC

A now contains 5 or 7 as needed. The loop is now ended.

04  
67  
E3

INC B  
LD H,A  
RR (SP),HL

This is what happens if B was zero. The value 5, 7, or 0 is stored on the stack behind HL.

E5  
18C3

PUSH HL  
JR STARTOFF

57

LD D,A

This is what happens if B was one. D now contains the current value 0, 5, or 7.

7D  
91  
6F

LD A,L  
SUB C  
LD L,A

The square behind us is located.

7E

LD A,(HL)

The contents of this square are examined.

FE80

CF 80

If it is not a blank square we are not in danger.

28ED

JR NZ,NOWT

The current value is retrieved.

7A

LD A,D

E1

POP HL

D now contains the previous value 0, 5, or 7.

D1

POP DE

The final square-value is calculated. The remaining registers are removed from the stack.

92

SUB D

End of subroutine.

D1

POP DE

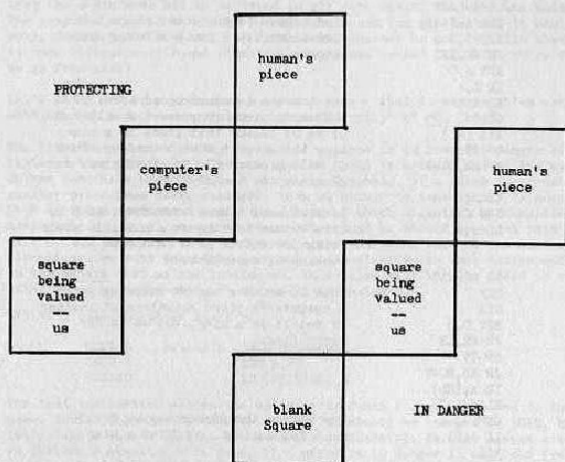
C1

POP BC

C9

RET

This works because if you take a look at the diagram below you'll see very clearly the conditions under which we define a piece as being "in danger" or protecting. Compare carefully what the subroutine does both times round, with each of the diagrams.



Now for the rest of that decision making routine EVALUTE. It contains a deliberate mistake - see if you can find it! (The program will still run perfectly smoothly even with the mistake still in.) If you can't see it out on your own I'll tell you later on.

This routine is designed to compute a numerical value - a "priority" - for any individual move. Having done so it will compare this priority with those moves stored on the stack. If the new priority is less, it will forget this move and go on to explore a new one. If the new move is equal in priority it will be stored on the stack. If the new priority is more than those on the stack then the list will be abolished, and a new list started.

The registers in the routine have the following jobs:

- A- a general purpose working register.
- B- counts the number of items in the list. You may remember the CHOOSE routine earlier on relied on B containing this number of items.
- C- a general purpose working register.
- DE- a pointer which looks at the table of allowable directions of movement.
- H- the direction being moved.
- L- the low part of the address of the current square.

The routine begins at address 4E43:

```

CDF14D  EVALUATE  CALL SQUAREVAL  Check for danger and/or protection
C680      ADD 80      at current square.
322140      LD (INITIAL),A

```

```

11974C  LD DE, TABLE  Set pointer to start of table.
4D      LD C, L        Remember low part of the address of
                        the current square for later use.
69      NEXTPGND  LD L, C  Retrieve this value.
2640    LD H, 40      Assign high part of this address.
1A      NATDIR    LD A, (DE) Select direction of movement.
1C      INC E       Move table pointer.
CB7E    BIT 7, (HL)  Check whether or not we are looking
                        at a king.
2804    JR Z, ANYDIR If so we can move in any direction.
CB7F    BIT 7, A      Check whether current direction is
                        forward or backward.
20F6    JR NZ, NEXTDIR If backward, pick a new direction.
FE2E    CP Z         If this direction is Z then we have
CAA04D  JP Z, KPCHKNC covered all four directions.
C5      PUSH BC      Temporarily stack B - the number of
                        items in the list of moves.
47      LD B, A       Store current direction temporarily.
81      ADD A, C       Find the address of the destination
6F      LD L, A       square in this direction.
7E      LD A, (HL)    Find the contents of this square.
60      LD H, B       The direction being moved is now
                        stored in H, as required.
C1      POP BC        The number of choices of moves on the
                        stack - B - is recovered.
FE80    CP 80         Is this destination square empty?
20E3    JR NZ, NEXTPGND If not, pick a new direction to examine.
ED537940 LD (SCANSQR), DE Temporarily store the value of DE.

```

Note that while we need to temporarily store DE somewhere, we must not stack it, since we are shortly about to use the stack to examine our list. OLD ROM owners should interpret the address (SCANSQR) as 4020.

```

CDF14D  CALL SQUAREVAL  Check for danger and/or protection at
                        destination square.

```

This is necessary because a move into danger is bad, and moving to protect another piece is good. Notice that by design the subroutine SQUAREVAL will not change the value of any register except A. One unfortunate flaw in the subroutine means that moving a king into danger will only generate the value five, rather than seven. Can you see why? Follow the subroutine through if you can't. Finally you should note that SQUAREVAL only requires L to be assigned initially, not HL. This is deliberate.

```

57      NEGFPRI  LD D, A  Negate this quantity, since we do
3A2140  LD A, (INITIAL)  not want to move into danger, and we
92      SUB D     do want to move to protect another
57      LD D, A   piece. Add in the original square-
                        value and store the result in D.
1B01    LD E, 01  The number one is the number of steps
69      LD L, C    involved in this move.

```

We now have D containing the computed priority of this move, and E containing the number of steps in this move.

```

B3      EX (SP), HL  We now have H containing the priority
                        of the list, and L containing the no.
                        of steps for each move on the list.

```

```

A7          AND A
ED52        SBC HL,DE      Compare these two sets of quantities.
280D        JR Z,EQUAL
19          ADD HL,DE
E3          EX (SP),HL     Restore HL and the stack-top
3013        JR NC,FORGETIT If computed priority is less, then
                                do nothing.
ED7B740     LD SP,(LBASE)  Otherwise begin new list.
0600        LD B,00        Zero items on list so far.
15          PUSH DE        Stack the priority and no. of steps.
1802        JR NEXTITEM
19          EQUAL ADD HL,DE  Restore HL and the stack-top.
E3          EX (SP),HL
04          NEXTITEM INC B   Increase no. of items in list.
E5          PUSH HL

```

Now H contains the direction moved, and L the low part of the initial square. The top of the stack therefore now looks like this:

initial square	direction one	no. of steps	priority
↑ sp			

This is not quite what we want - we want it to look like this:

no. of steps	priority	initial square	direction one
↑ sp			

So we now want to swap the first and second bytes at the top of the stack with the third and fourth bytes. We want to do this without altering the position of the stack pointer, and without altering any of the registers. The following will achieve this - follow it through carefully -

```

33          INC SP          Move the stack pointer to the
33          INC SP          initial square. (final position)
E3          EX (SP),HL      store initial square and direction 1.
3B          DEC SP          Move the stack pointer back where it
3B          DEC SP          came from.
E3          EX (SP),HL      Store the number of steps and priority.

```

Note that even HL remains unchanged by this method. EVALUATE needs only two more instructions to complete it. These are

```

ED5B7940    FORGETIT LD DE,(SCANSQR) Restore the previous values of D
1850         JR NEXTMRND and E, and do the same for next
                                direction.

```

As it stands the program will not test whether or not a computer's piece has reached the back row (and thus become a king). This is not a programming error, this is quite deliberate. The reason is that this is something I'd like you to do for yourself. Study the way in which the check on a human's piece is made - the low part of the destination address is compared with the low part of the address of the boundary between the back row and the second row - and make a similar test. You should find this a very simple addition to the program.

The EVALUATE routine is now complete. The whole program is now a closed structure - there are no holes in it now, no RET statements temporarily taking the place of subroutines that aren't there. If you now RUN the program (by typing RUN 4) it will actually make moves! Of course it won't do much else, but you should now be able to see how far we've progressed.

Oh - there is of course that deliberate mistake to think about. If you didn't notice it in the listing you probably noticed it by playing it. The problem is that the computer won't jump. As you can imagine this leads to a very poor game on its part.

The mistake is in the line labelled TEST. It currently says JR NZ,NXTMRND, which means that if a square in any particular direction is simply not empty then it will try a different direction. The line should read JR NZ,WHAT, where WHAT is a routine (which we haven't yet written) which is designed to decide whether the destination square contains a human's piece, whether a jump is possible - even whether or not a multiple jump is possible - and to evaluate the priority of whatever it finds.

Here is one such subroutine. It is not the only possible one, but a suggestion of one means of doing it. This particular version will cope only with single jumps, not with multiple jumps: The routine begins at 4B9B:

```

ED537940    WHAT LD (SCANSQR),DE  Temporarily store the value of DE
57          LD D,A              Store the contents of the square
                                we are now looking at in D.
B67F        AND 7F              Is it a human's piece?
FE27        CF 27
2806        JR Z,FOUND
ED5B7940    LD DE,(SCANSQR)  If not, retrieve the original value
1899        JR NEXTMRND      of DE and resume the search.
3B81        FOUND LD A,B1     Assign A with either five or seven
CB12        RL D              depending on whether or not we have
3F          CCP                found a king.
17          RLA
17          RLA
57          LD D,A              Store this in D.
5C          LD E,H              Store the current direction in E.
7D          LD A,L              Find the next square in this direction.
84          ADD A,H
6F          LD L,A
2640        LD H,WKBOARD-low
7E          LD A,(HL)          Find the contents of this square.
63          LD H,E              Restore H to its previous value.
FE80        CF 80              Is this square empty?
2807        JR Z,JUMP
ED537940    LD DE,(SCANSQR)  If not, restore the original value
C34F4B      JP NEXTMRND      of DE and resume the search.
CBF14D      JUMP CALL SQUAREVAL Check for danger and/or protection
                                at destination square.
92          SUB D              Take contents of square into account.
18A2        JR NEXTPRI        Check this new priority to see if it's
                                worth stacking.

```

As you can see, the principle for finding a single jump is relatively straightforward. With this routine in place the computer will now play an adequate game of draughts, but although the human player is allowed to make multiple jumps, the computer will not. This addition I leave you to write yourself. I will, however give you a couple of hints.

First of all, the registers all have specific uses. All that is, except for A and C. These are as follows:

- B - The number of choices of move available.
- D - The priority of the current move.
- E - The number of steps in the current move.
- H - The direction being moved this step.
- L - The low part of the address of the current square (within WKBOARD)

I suggest giving C a use too - it should be used to store which step of a multiple-step move we are currently examining. In other words, on the second step C will be two, on the third step C will be three, and so on. It is fairly easy to preserve the values of all of the registers by making proper use of the stack.

Nesting the subroutines and loops properly, so that the same routine is used to check for a third move as is used to check for a second move, is not as difficult as you might think - it merely requires a bit of positive thinking. It also has the advantage that, in theory, the computer can actually make twelve-fold jumps with no extra programming. The looping is not the biggest problem.

There are two problems which will face you. These are:

- 1) Having stored C-1 steps of the current move on the stack, how do we store step C? (ie how do we insert it into the middle of the stack)
- 2) Having established that the current move now stands at C steps, and can be increased no more, one of the following must happen: If C is less than E then the current move is abolished; if C is equal to E, the stack is left unchanged; if C is greater than E then the whole list of moves on the stack except the current move is abolished.

Let's take a look at the first problem first. Assuming C-1 steps are stacked, the situation we now have is this:

E	priority	initial square	dir. 1	dir. 2	dir. C-1	initial square	dir. 1	dir. 2	dir. E
sp									

We wish to insert "direction C" between "direction C-1" and the initial square of the second move. The following subroutine will do just that, but follow it through very carefully because its mechanism is quite intricate.

```

C5  ADDSTEP  PUSH BC      The number of bytes at the top of the
D5  PUSH DE   stack which need to be shifted down
E5  PUSH HL   is C plus two, but once BC, DE, and HL
3B0B LD A,0B  have been pushed onto the stack the
81    ADD A,C   actual number is C plus eight.
210000 LD HL,0000
44    LD B,H
4F    LD C,A    This number is stored in BC.
39    ADD HL,SP HL points to the top of the stack,
54    LD D,H
5D    LD E,L
1B    DEC DE    DE points to one byte below this.
EDB0  LDIR     Part of the stack is moved down.
3B    DEC SP    The stack pointer is moved also.
E1    POP HL
7C    LD A,H
12    LD (DE),A The current direction is put in place.
D1    POP DE
C1    POP BC    The registers are retrieved.
0C    INC C     C is increased to indicate that we
                  are now at the next step.

```

You'll notice that the sequence LD HL,0000/ADD HL,SP is necessary because there is no such instruction as LD HL,SP (even though LD SP,HL is allowed). LDIR is used to shift the required part of the stack down one byte. The exact number of bytes to be shifted must first be very carefully calculated, and stored in BC in order that LDIR will work properly. Coincidentally LDIR will leave DE finally pointing to just the right address for us to store the current direction. Since HL is at the top of the stack we may remove it, and load the current direction (H) into position, via A, before we remove DE and BC. Thus the stack pointer is still where we want it, and none of the values of any register (except A) have been changed.

The stack now looks like this:

E	priority	initial square	dir. 1	dir. 2	dir. C-1	dir. C	initial square	dir. 1	dir. 2	dir. E
sp										

Finally, C is incremented because we are now ready to examine the next step.

The two procedures involved in the second problem may be solved by careful study of the above process. To abolish the current move is simple - DE is popped, the stack pointer is then incremented by the exact number of bytes, and DE is pushed back again. The second procedure, that of abolishing the whole list except for the current move may be achieved by loading HL with the position within the stack of "direction C", DE with the contents of the variable LEASE, and then using LDIR, however, you'll have to do some thinking in order to work out BC (the number of bytes to be moved) and the new position of the stack pointer. If you understand how ADDSTEP works it will not be all that difficult to do.

With this problem to solve, I will leave you. It's not impossible I assure you. Finally, consider the length of this program so far - our addresses still begin with 4E, and we are allowed to go as far as 4FFF (although we need some left over for the screen and the stack). 1K draughts is quite, quite possible. With thought you may even be able to shorten it further.

#### DOWNLOADING

Although the program is only 1K it is currently stored in the fourth K. To download it into the first K the procedure is this.

Change every address beginning with 4C to the corresponding address which begins 40. Do the same for 4D, changing it to 41, change 4E to 42, and 4F to 43.

Delete all lines of BASIC except the following:

OLD ROM	NEW ROM
1 RANDOMISE USR(printboard)	1 INPUT A\$
2 INPUT A\$	2 RAND USR game
3 RANDOMISE USR(game)	
4 GOTO 2	(USE ANY FIVE DIGIT NUMBER FOR NOW)

Reserve enough space for the machine code using a series of REM statements from line 5 onwards. On the OLD ROM a REM statement with 46 characters after the word REM occupies exactly fifty bytes. On the NEW ROM a REM statement with 44 characters after the word REM occupies fifty bytes. The machine code will eventually overwrite not only the characters after the word REM, but the word REM itself and even the line numbers.

OLD ROM: type POKR 16463,-1  
NEW ROM: type POKR 16535,-1  
All of your REMs should disappear from the listing.

Now, using a machine code program, which you should store somewhere in the third K, copy all of the draughts program from address 4C97 onwards, down to 4097 onwards.

OLD ROM: copy the board printing routine to the point immediately after the draughts program proper finishes.

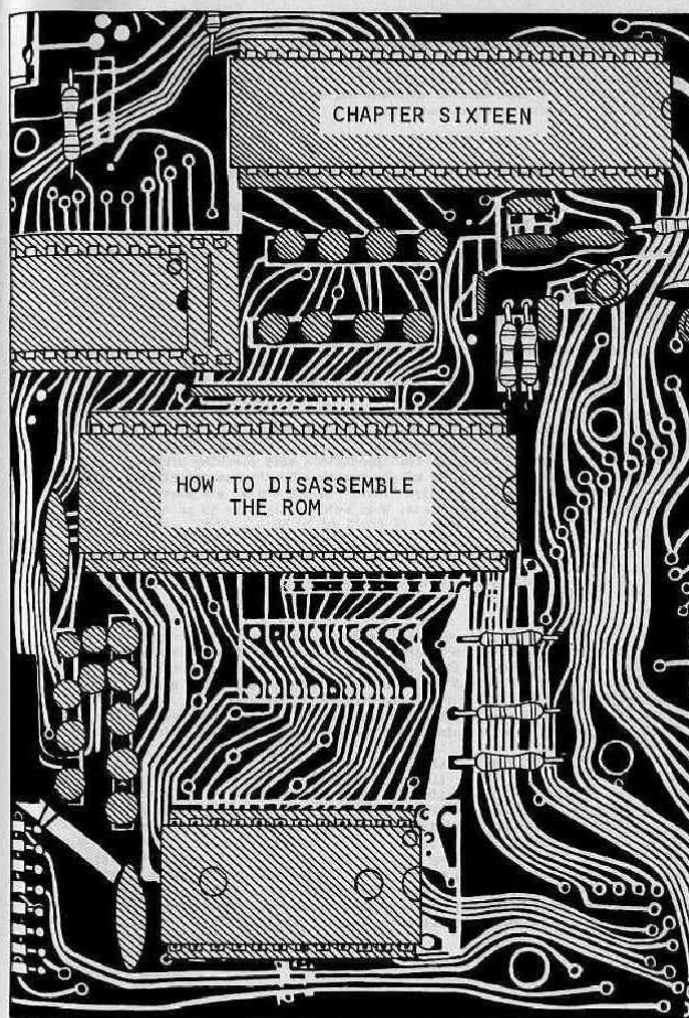
NEW ROM: DO NOT copy the board printing routine at all. Instead, leave it at 4C09, and replace the instruction RET by the following machine code program.

217D40	LD HL, FIRSTLINE	Fool the ROM into thinking that the
222940	LD (NEXTLIN), HL	first line of program is about to
C50703	JP SAVE	be executed, then jump to the SAVE
		routine.

Start your cassette recorder up, so that it is recording, not playing, and type as a direct command RAND USR 19487. This should be done in the FAST mode. The program will then do the following tasks. 1) Print the playing board, 2) Specify that line one is about to be executed, and 3) SAVE the program, and the current display file (with the board pre-set-up) and the fact that line one is about to be executed. When you re-load from tape you will be in mid-program, with the first move (yours) about to be made.

The label "printboard" for the OLD ROM refers to the address at which the board printing routine is to be placed. The label "game" refers to the address 16612.

For the OLD ROM, the address WKBOARD should be changed to that of the board printing routine throughout. In this way the same space is effectively used twice. For the NEW ROM, the address WKBOARD should be left unchanged at 403C.



There are three "levels" at which we may disassemble, each slightly more sophisticated than the previous. The first two levels are not all that satisfactory, but they are very easy to program.

The first "level" we have already achieved - the `USR` routine `HLIST` which we saw earlier in the book will do this for us. That is, given an address such as 0808 it will produce an output like this:

```
0808 57
0809 ED
080A 4B
080B 39 T
080C 40
...
```

and so on. This is not really disassembly, although you can of course look these bytes up in the tables at the back of the book, but it's quite a time consuming task, and you're also very likely to get lost halfway through. The second "level" is not much better, but again is quite easy to program. What I'm talking about is an output something like this:

```
0808 57
0809 EIMB3940
080D 79
080E FE21
...
```

and so on. As you can see, each instruction has its component bytes listed out to exactly the right length. This produces a very pleasing display, and there is little or no chance of you "getting lost" when actually looking these bytes up in tables. The third "level" is the one we are actually aiming at - the one everybody wants. What we'd really like is an output like this:

```
0808 LD B,A
0809 LD BC,(4039)
080D LD A,C
080E CP 21
...
```

and so on. This can be quite easy to program - simply make the computer look up the appropriate words from a table instead of doing it ourselves - however this would take up rather a large amount of space just to store the table. Around 4K in fact. The method I will describe to you will allow such a program to fit in just 1K, but be warned: it's rather difficult. There is actually a "fourth level" of disassembly, which I won't even attempt to touch, but you may like to think about. Imagine an output like this:

```
PRINT LD D,A
LD BC,(S-POSN)
LD A,C
CP 21
JR Z,EXIT
...
```

As I've said, I'm not even going to touch this one. The only extra it involves is storing yet another table, this time containing all of the labels used. Let's go back a bit now to something relatively simple. Let's consider a slightly improved version of `HLIST` which reaches the "second level" of disassembly, and works out the length of each instruction before printing it.

All we need is a table containing just two pieces of information for each byte. These are a) the number of bytes in an instruction beginning with this byte, and b) the number of bytes in an instruction beginning with `DD` or `FD` followed by this byte. As you know, some confusion may arise over those instructions beginning with `CB` or `ED`, but we don't actually need any tables or anything to cope with these provided we remember the following rules:

All instructions beginning `CB` are two bytes in length.

All instructions beginning `DDCB` or `FDDB` are four bytes in length.

All instructions beginning `ED` are two bytes in length, except for `LD B,(pq)`, `LD DE,(pq)`, `LD SP,(pq)`, `LD (pq),BC`, `LD (pq),DE`, and `LD (pq),SP`. The byte immediately after `ED` for these six instructions is 4B, 5B, 7B, 43, 53, or 73. In binary, all of these numbers have the form 01-- -011. No other instructions have this form.

There are no instructions beginning `DEED` or `FEED`.

Thus we need a table containing a very small amount of information relating to each byte. Firstly, those instructions which do not begin `DD`, `ED`, or `FD` can only be one, two, or three bytes in length. This means that to store the required information we only need two bits. Secondly those instructions which begin `DD` or `FD` can only be two, three, or four bytes in length, so ignoring the `DD` or `FD` itself this leaves one, two, or three bytes. Again we need only two bits. This makes four bits altogether, and we can thus represent the appropriate lengths for each byte by a single hexadecimal digit. Our program then will make use of the following table, called `LENS`. It should be stored such that each element of the table has the same high part of its address:

LENS	DEFB
5F	55 55 A5 55 55 55 A5
AF	55 55 A5 A5 55 55 A5
AF	F5 55 A5 A5 F5 55 A5
AF	F5 99 E5 A5 F5 55 A5
55	55 55 95 55 55 55 95
55	55 55 95 55 55 55 95
55	55 55 95 55 55 55 95
99	99 99 55 55 55 55 95
55	55 55 95 55 55 55 95
55	55 55 95 55 55 55 95
55	55 55 95 55 55 55 95
55	55 55 95 55 55 55 95
55	55 55 95 55 55 55 95
55	FF F5 A5 55 FE FF A5
55	FA F5 A5 55 FA F5 A5
55	F5 F5 A5 55 F5 FA A5
55	F5 F5 A5 55 F5 F5 A5

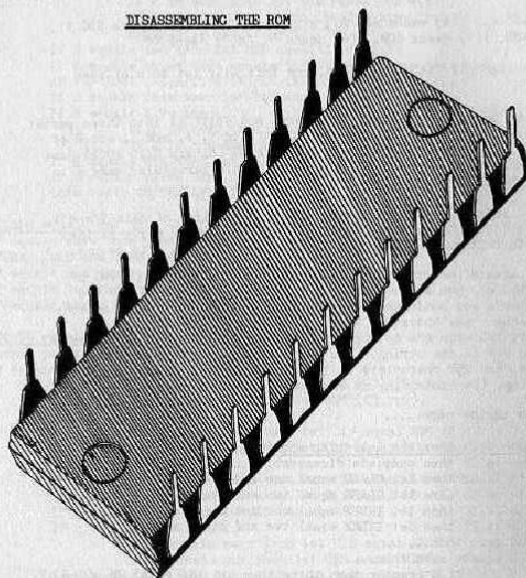
As you can see, there are sixteen rows, and sixteen hex digits in each row. Those instructions beginning with `DD` or `FD` which do not exist, such as `DD00`, have simply been assigned the appropriate number of bytes as if the `DD`/`FD` were not there.

The following program will "disassemble" to a string of bytes of the right length. It assumes that the table `LENS` exists, and it assumes that a subroutine `HPRINT` exists which prints the contents of the `A` register in hexadecimal without corrupting the other registers. This subroutine was in fact given earlier on in the book.

28	START	DEC HL	HL is just the address from which
29	NEXT	INC HL	we are disassembling.
3E76		LD A,76	
D7		RST 10	Print a newline.
7C		LD A,H	
CDhprint		CALL HPRINT	Print H in hex.
7D		LD A,L	
CDhprint		CALL HPRINT	Print L in hex.
AF		XOR A	
D7		RST 10	Print a space.
0800		LD C,00	C is just a flag to let us know
			whether or not an instruction
			begins with DD or FD.
			Obtain the byte to be disassembled.
			Does it begin with either DD or FD?
7E	BYTE	LD A,(HL)	
FEED		CP DD	If so, print "DD" or "FD" and look
2804		JR Z,DDFD	at the next byte.
FEFD		CP FD	Change the flag C accordingly.
2007		JR NZ,NORM	Continue with next byte.
CDhprint	DDFD	CALL HPRINT	Does the instruction begin ED?
23		INC HL	
0C		INC C	If so, print "ED" and look at the next
18F0		JR BYTE	byte.
FEED	NORM	CP ED	
201A		JR NZ,NOTED	
CDhprint		CALL HPRINT	Is it of the binary form 01--011?
23		INC HL	
7E		LD A,(HL)	
E6C3		AND C3	
FE43		CP 43	
2004		JR NZ,CNE	B counts the number of bytes to be
0603		LD B,03	printed after the byte ED.
1802		JR THREE	
0601	ONE	LD B,01	
CDhprint	THREE	CALL HPRINT	Print the next B bytes.
23		INC HL	
7E		LD A,(HL)	
10F9		DJNZ THREE	
18C2		JR NEXT	Continue with next byte.
E5	NOTED	PUSH HL	Temporarily store HL.
CB2F		SRA A	Divide A by two.
F5		PUSH AF	Store the carry flag.
C6lens-low		ADD A,LENS-low	Find the required position in the table.
6F		LD L,A	
26lens-high		LD H,LENS-high	
F1		POP AF	Retrieve the carry flag.
7E		LD A,(HL)	
3804		JR C,DIG2	Use the carry flag to decide on which
1F		RRA	digit from the table will be used.
1F		RRA	
1F		RRA	
1F		RRA	
0D	DIG2	DEC C	Use C to decide which two bits
2002		JR NZ,OK	to use.
1F		RRA	
1F		RRA	
E603	OK	AND 03	Put this number in B to use as
47		LD B,A	a count.
E1		POP HL	Retrieve the address of the byte to
28		DEC HL	be disassembled.
23	NKBYT	INC HL	
7E		LD A,(HL)	
CDhprint		CALL HPRINT	print B bytes in hex.
10F9		DJNZ NKBYT	
189E		JR NEXT	Continue with next byte.

Now we ascend to the "third level" - REAL disassembly in other words. However, I am not going to write the program for you this time round - you'll have to do it by yourself. I will explain precisely what it is you have to do in order to make a 1K disassembler, but the actual program itself must be your creation.

#### DISASSEMBLING THE ROM



The following is an algorithm which will enable you to disassemble the hex codes into assembly, that is to change, for example, 69 to LD L,C, or from CB7E to BIT 7,(HL). One way would be to list a vast table - such as I have included in the appendices - but while alright for human beings it lacks the elegance of a well thought out computer program. The data alone would occupy around 4K. This algorithm will enable you to write your own machine language program occupying significantly less - two or even one K all told depending on how efficient your program is.

In this algorithm, the following conventions will be used:

r(0) means B, r(1) means C, r(2) means D, r(3) means E, r(4) means H, r(5) means L, r(6) means X, r(7) means A.

s(0) means BC, s(1) means DE, s(2) means Y, s(3) means SP.

q(0) means BC, q(1) means DE, q(2) means Y, q(3) means AF.

n(0) means 0, n(1) means 1, n(2) means 2, n(3) means 3, n(4) means 4, n(5) means 5, n(6) means 6, n(7) means 7.

c(0) means NZ, c(1) means Z, c(2) means NC, c(3) means C, c(4) means PO, c(5) means PE, c(6) means F, c(7) means M.

x(0) means ADD A, x(1) means ADC A, x(2) means SUB, x(3) means SBC A, x(4) means AND, x(5) means XOR, x(6) means OR, x(7) means CP.

Define two variables, CLASS and INDEX, and initially let both of them equal zero.

Write the byte being disassembled in binary, and split it into three parts: F, G, and H. F consists of bits 7 and 6, G of bits 5, 4, and 3, and H of bits 2, 1, and 0. Thus to disassemble the byte 69 (binary 0110 1001) just split it into three parts thus: 01/101/001. In this particular case F is one, G is five, and H is one.

Next, split G into two parts: J and K, with J consisting of bits 2 and 1, and K just bit 0. If G then were binary 101 as above then split it like this: 10/1. In this case we would define J to be two, and K to be one.

Set aside an area of memory called DIS. This is to contain a STRING of unknown length. How you store this string is up to you. There are two different methods you could use - either terminate the data with an end-of-data character (any character will do, FF is as good as any), or begin the area DIS with one byte representing the number of characters of data there are in the string. (You only need one byte since DIS will never be more than 255 characters in length.) DIS should initially be an empty string, (ie containing no characters at all.)

The algorithm begins here.....

If CLASS equals zero then the following applies:

- 1) If the byte is 76 then complete disassembled instruction is HALT.
- 2) If the byte is CB then let CLASS equal one and start again.
- 3) If the byte is EB then let CLASS equal two and start again.
- 4) If the byte is DB then let INDEX equal one and start again.
- 5) If the byte is FB then let INDEX equal two and start again.
- 6) If F equals zero then....

If H equals zero then....

If G greater than three then let DIS equal JR c(G-4),V.  
If G less than four choose the Gth item in this list:

NOP/EX AF,AF/DJNZ V/JR V

If H equals one then....

If K is zero then let DIS equal LD s(J),VV

If K is one then let DIS equal ADD Y,s(J)

If H equals two then....

Let DIS equal LD plus the Gth item in this list:

(BC),A/A,(BC)/(DE),A/A,(DE)/(VV),V/V,(VV)/(VV),A/A,(VV),

If H equals three then....

If K is zero then let DIS equal INC s(J)

If K is one then let DIS equal DEC s(J)

If H equals four then let DIS equal INC r(C)

If H equals five then let DIS equal DEC r(C)

If H equals six then let DIS equal LD r(C),V

If H equals seven then choose the Gth item from this list:

RLC/RRC/RLA/RRA/DAA/CPL/SCF/CCF.

If F equals one then let DIS equal LD r(G),r(H).

If F equals two then let DIS equal x(G) r(H).

If F equals three then....

If H equals 0 then let DIS equal RET c(G)

If H equals one then....

If K is zero then let DIS equal POP c(J)

If K is one then choose the Jth item from this list:

RET/EXX/JP (Y)/LD SP,Y.

If H equals two then let DIS equal JP c(G),VV

If H equals three then choose the Gth item from this list:

JP VV/-/OUT (V),A/IN A,(V)/EX (SF),Y/EX DE,HL/HL/HL.

If H equals four then let DIS equal CALL c(G),VV

If H equals five then....

If K is zero then let DIS equal PUSH s(J).

If K is one then let DIS equal CALL VV.

If H equals six then let DIS equal RES n(G),r(H).

If H equals seven then let DIS equal RST plus the Gth item in

this list: 00/05/10/18/20/28/30/35.

If CLASS equals one then the following applies:

If F equals zero then choose the Gth item from this list: RLC/RRC/RL/RR/SLA/SRA/-/SRL and then add r(H).

If F equals one then let DIS equal BIT n(G),r(H).

If F equals two then let DIS equal RES n(G),r(H).

If F equals three then let DIS equal SET n(G),r(H).

If CLASS equals two then the following applies:

F cannot possibly equal zero.

If F equals one then....

If H equals zero then let DIS equal IN r(G),c(G).

If H equals one then let DIS equal OUT (C),r(G).

If H equals two then....

If K equals zero then let DIS equal SBC HL,s(J).

If K equals one then let DIS equal ADC HL,s(J).

If H equals three then....

If K equals zero then let DIS equal LD (VV),s(J).

If K equals one then let DIS equal LD s(J),(VV).

If H equals four then let DIS equal NEG.

If H equals five then....

If K equals zero then let DIS equal RETN.

If K equals one then let DIS equal RETI.

If H equals six then choose the Gth item from this list:

IM 0/-/IM 1/IM 2/-/-/-/-/.

If H equals seven then choose the Gth item from this list:

LD 1,A/LD R,A/LD A,I/LD A,R/RDD/RDD/-/-/.

If F equals two then choose the Hth item from this list: LD/CP/IN/OUT/-/-/-/-/ and then add the Gth item from this list: 1/D/IR/IR/-/-/-/-/.

F cannot possibly be three.

To compute the final output:

If INDEX equals zero replace every Y by HL.

If INDEX equals one replace every Y by IX

If INDEX equals two replace every Y by IY

If INDEX equals zero replace every X by (HL)

If INDEX equals one replace every X by (IX+d) where d is defined by the next byte but one after the byte DD.

If INDEX equals two replace every X by (IY+d) where d is defined by the next byte but one after the byte FD.

(This does not apply if the X is preceded by I)

Replace every V by the next byte in sequence (of those being disassembled).

DIS now contains the correctly disassembled instruction. This should now be printed to the screen.

It is possible to write a machine language program which disassembles things by using this algorithm. In fact it is possible to write such a program in just 1K. Surprising as this may sound I should add that although it is possible, the program itself is rather complicated, and involves a completely new programming technique.

What I will do is to not actually write the program for you, but to give you hints and suggestions as to how it may be done. The program revolves around eight different subroutines, which are linked together by one MASTER subroutine which calls them all up in any required order. This is achieved as follows.

Somewhere in the program there should be a table called SUBTAB which contains eight different addresses - these are the addresses of the eight subroutines which control the program. The register-pair HL' (note the dash) will be pointing to a sequence of data which tells the MASTER subroutine which order it must call the others in. The data in this sequence is terminated by an item in which bit 7 is one. The data consists simply of numbers zero to seven. Zero calls subroutine zero, one calls subroutine one, and so on. Thus this number zero to seven determines exactly which subroutine the MASTER routine is to call.

So any item of data in this sequence looks, in binary, like this: 0--- -nnn for most items, or 1--- -nnn for the last item. (The part written nnn means the appropriate number zero to seven as described.) Now some of these eight subroutines will need to be supplied with DATA, which by coincidence will also need to be a number between zero and seven - if this number in binary is ddd then it makes sense to save space by storing this number amongst some of the unused bits of the subroutine-call, thus making it look, in binary, like this: 0-dd dnnn or 1-dd dnnn. We have now made use of every bit except bit 6. This isn't needed, so for sake of argument lets always make it zero. Any item of data in the sequence can then be 0odd dnnn, but the last byte must be 1odd dnnn.

I hope that didn't confuse you. To make things clear, suppose HL' points to an address at which is stored the sequence of data 00 01 22 83. This means that first of all subroutine zero is to be called, then subroutine one, then subroutine two (which will use the data binary 100 somewhere), then finally subroutine three. I say "finally" because bit 7 is set which means we are finished.

The master subroutine which will achieve this is as follows:

D9	MASTER	EXX	
7E		LD A,(HL)	Find byte of data, and increment
23		INC HL	pointer.
D9		EXX	
5F		LD E,A	Store this byte, in case bits 5, 4, and 3 contain data to be used in the appropriate subroutine.
B607		AND 07	Isolate bits 2, 1, and 0.
17		RLA	Multiply by two.
4F		LD C,A	Store this number in the BC register pair.
0600		LD B,00	
21	return	LD HL,RETURN	Specify the return address from each of the eight subroutines.
E5		PUSH HL	Point HL to the start of the table which stores the eight subroutine call addresses.
21	mastrads	LD HL,MASTRADS	Point HL to the required address.
09		ADD HL,BC	Store this address in the BC register pair.
4E		LD C,(HL)	
23		INC HL	
46		LD B,(HL)	
C5		PUSH BC	Call this subroutine.
C9		RET	
7B	RETURN	LD A,E	If Bit 7 was not zero then continue with the next byte of data.
17		RLA	
30E8		JR NC,MASTER	

You can learn a lot from studying this MASTER-SUBROUTINE. Can you see how the appropriate subroutine (one of eight) is called? First of all the label RETURN is pushed onto the stack. This means that if each of the eight routines ends with a RET instruction then control will jump to the label RETURN - just as if the subroutine had been accessed normally. To call the subroutine itself, the address of which was in the register-pair BC, we used PUSH BC followed by RET. Think carefully about how this works. The required address is pushed onto the stack, above the address RETURN. Then a RET instruction is executed. RET has the effect of popping the first number from the stack (the subroutine address) and jumping to that address. The first address left on the stack is now the address RETURN, which enables control to return correctly. All of this is necessary because there is no such instruction as CALL (BC) - in BASIC the statement GOSUB VARIABLE is allowed, but not in machine code. Another way we could have achieved the same as PUSH BC/RET is by using the sequence LD H,B/ LD L,C/JF (HL). Can you see why this does the same thing?

You may be wondering how the appropriate address came to be in HL' in the first place. There are two means by which this will be determined. Note that all of the alternative registers have specific jobs. These are:

BC'	The address of the byte to be disassembled.
D'	The variable INDEX.
E'	The variable CLASS.
HL'	Points to subroutine data.

The byte to be disassembled is located and stored in the D register by the means EXX/LD A,(BC)/INC BC/EXX/LD D,A. From this the quantities I called F, G, and H may later be discovered. Somewhere in the program there should be a table called TABLE containing twelve different addresses. HL' is simply read from this table. The twelve addresses correspond to the cases CLASS equals zero and F equals 0, 1, 2, or 3; CLASS equals one and F equals 0, 1, 2, or 3; and CLASS equals two and F equals 0, 1, 2, or 3.

The other way in which HL' may be determined is if subroutine zero is called. Subroutine zero is called by the data-byte 00. This will be immediately followed by eight different addresses corresponding to the cases H equals zero, up to H equals seven. Subroutine zero has the task of locating the appropriate address from this list and storing it in the register-pair HL'.

One subroutine you will need, (but not one of the eight central ones,) is a subroutine to add a single character to the end of the string DIS. Using the convention that the string begins at address DIS and is terminated by the byte FF, the string may be emptied by the sequence LD HL,DIS/LD (HL),FF. To add a character (held in the A register) the subroutine is

C5	ADD DIS	PUSH BC	Store the registers BC and HL so that they won't be altered by the subroutine.
E5		PUSH HL	
0601		LD B,01	This is so that CPIR won't stop because of BC.
21818		LD HL,DIS	Find the start of the string.
F5		PUSH AF	Temporarily stack A.
3EFF		LD A,FF	
EDB1		CPIR	Find the end of the string.
77		LD (HL),A	Insert a new end-of-string marker.
2B		DEC HL	
F1		POP AF	Retrieve A.
77		LD (HL),A	Add this character.
E1		POP HL	Retrieve the remaining registers.
C1		POP BC	
C9		RET	End of subroutine.

The eight subroutines you will need for this disassembly program are as follows:

#### SUBROUTINE 0 - SPLIT

This is the subroutine called by the byte 00. It is always the first subroutine called, if it is used at all. The byte 00 should be followed eight new addresses within the disassembler program. Located at these addresses are eight different sequences of data, which correspond to the cases H equals zero, H equals one, and so on up to H equals seven. One of these sequences is selected (according to H) and the data used to decide which of the eight subroutines should then be used.

#### SUBROUTINE 1 - LITERAL

The byte 01 (or 81 if it is the last subroutine-call in sequence) is followed by a series of characters, such as N O and P, which represent part or all of the disassembled instruction. The last character should have one of the unused bits (6 or 7) set, to indicate the fact that it is the last character. The subroutine should use one bit of data, with the meaning that if it is called by the byte 09 (or 89) then the literal data following should have a space inserted after the last character. This literal data is to be added to the end of the data storage area called DIS.

#### SUBROUTINE 2 - LIST-G

Means select the Gth item from the following list. The subroutine needs data to specify how many items there are in the following list. If there are four items the data 011 (3) is required, if there are eight items, the data 111 (7) is required, and so on, the data always being one less than the number of items in the list. For example the byte 3A (in binary 010111010) - meaning call subroutine 2 and provide it with the data 111 means select the Gth item from the following list of eight. The list could, for instance, be R, L, C, inverse A, R, R, C, inverse A, R, L, inverse A, R, R, inverse A, D, A, inverse A, C, F, inverse L, S, C, inverse F, C, C, inverse F. I've used 'inverse' to indicate the last character in an individual item. You don't have to do this - you can use any means you choose as long as it works. Thus if G (that is bits 5, 4, and 3 of the instruction being disassembled) were 5, the literal DAA would be added to the end of DIS. The next byte to be interpreted as data will be the byte after the inverse F.

#### SUBROUTINE 3 - LIST-H

Means select the Hth item in the following list. Its explanation is exactly the same as that of subroutine 2.

#### SUBROUTINE 4 - SELECT-G

Again, three bits of data are required. Interpret as follows. If the data is 000 select r(G), if the data is 001 select s(G), if the data is 010 select q(G), if the data is 011 select n(G), if the data is 100 select c(G), and if the data is 110 select x(G). The item selected is to be added to the end of DIS.

#### SUBROUTINE 5 - SELECT-H

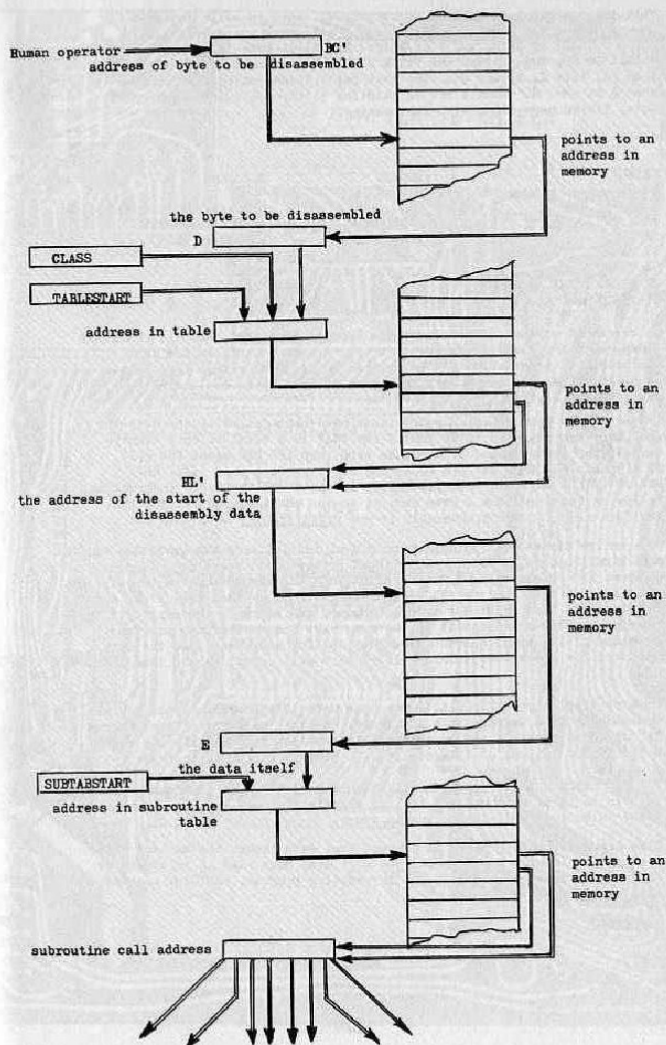
An subroutine 4, except that H is used instead of G.

#### SUBROUTINE 6 - SKIP

Resets bit 5 of E (the data-byte), and if the previous value of bit 5 was one skips over n bytes of data. The number n is determined by the immediately following byte. If bit 5 was zero this immediately following byte (which is only there to specify n) is ignored, and the next byte after is then interpreted as the next item of data.

#### SUBROUTINE 7 - K-SKIP

Replace bit 3 of E by bit 4, replace bit 4 by bit 5, and reset bit 5. Effectively this is the same as LET C equal J. Then if the previous value of bit 3 was one, n bytes are skipped over, as in subroutine six. This subroutine can be interpreted as IF K equals zero THEN..., otherwise IF K equals one then,...



With these eight subroutines, which you will have to write yourself, you can disassemble every instruction. I will give you an example. Suppose CLASS is zero, and F is three. The first byte it has to interpret should be 00. This alters the value of HL' according to the quantity H, that is, bits 2, 1, and 0 of the byte being disassembled. Suppose now that H is one. HL' should now be pointing to the following sequence of data, listed here along with its meaning.

data	binary	meaning
07 05	0000 0111	SKIP 5
09 35 34 B5	0000 1001	LITERAL POP (space)
94	1001 0100	SELECT-G-q (EXIT)
9A	1001 1010	LIST-G-4 (EXIT)
57 2A B9		RET
2A 3D BD		EXX
2F 35 00 16 3E 91		JP (Y)
31 29 00 38 35 1A BE		LD SP,Y

To represent strings of data here you can see I've used just the character codes, with the final character inverted to show that it is the last character. In other words EXX is written as 2A 3D BD rather than just 2A 3D 3D. It is of course very important to know where one string ends and the next begins.

If you follow through which subroutines have been called by the data and what they are supposed to do you'll see that in a total of only twenty-seven bytes we have said IF K equals zero then LET DIS equal POP q(J), IF K equals one then LET DIS equal the Jth item from this list: RET, EXX/JP (Y)/LD SP,Y. If this procedure is continued for every instruction, following the algorithm I gave earlier in the chapter, you'll find that the data required for disassembly is now significantly LESS than 1K.

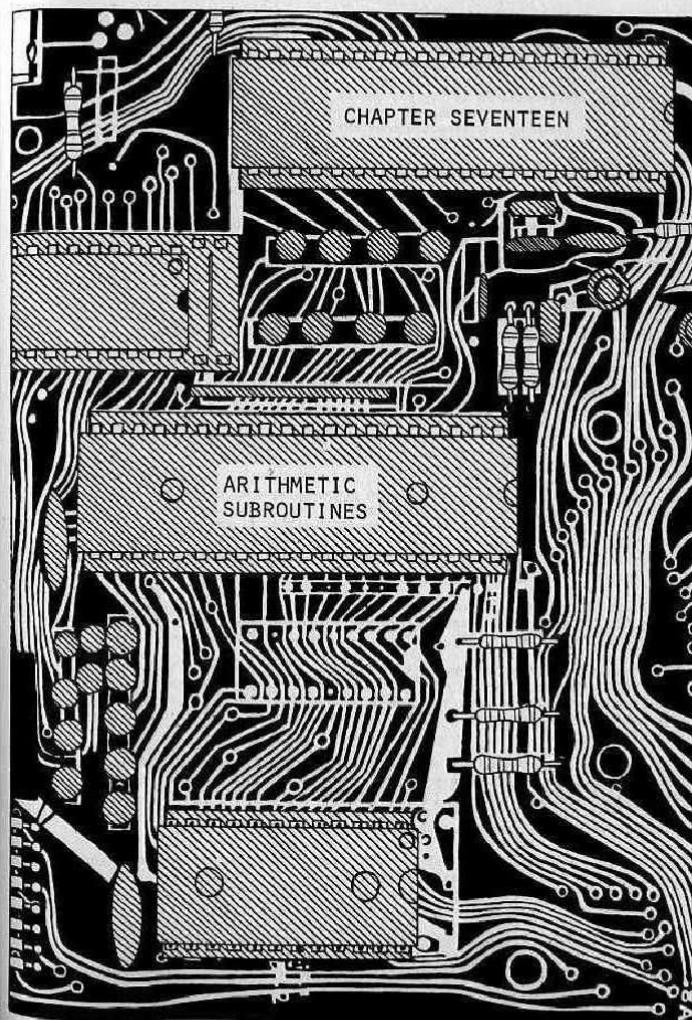
The entire disassembly program consists of initialising the variables CLASS and INDEX, assigning EC' (usually input by the human operator), finding the address HL' from tables, and then going into the master-routine. On exiting this it must then replace all V's, X's and Y's as defined earlier in this chapter, and then PRINT the result computed and go on to the next byte to be disassembled and treat it in the same way. The rest of the program consists of the eight subroutines, the table of addresses, and the data required for disassembly. The whole of this will occupy rather less than 1K.

However simple, or difficult, I may have made this program sound, you will undoubtedly find writing it a challenge. The vast majority of the program is data, and each address in every table must point to exactly the right byte. If you get any of it wrong it will be very difficult to trace.

You can improve the program too. I haven't used bit 6 of the data - you may be able to think of a use for it, for example it could indicate that a comma needs to be inserted, the choice is yours.

Like draughts, this program is so vast that even though the machine code listing itself will fit into 1K, you will need more than 1K in order for the machine code to be put there. Any editing program, BASIC or machine code, will take you above the 1K.

Good luck.



## ARITHMETIC SUBROUTINES

This chapter is divided into two sections - one for the OLD, and one for the NEW ROM. We'll tackle the OLD ROM first because it's easier.

Numbers are represented in two bytes, and as such is it possible to store them in register pairs BC, DE, and HL. First of all we shall take a look at the five major arithmetic routines.

1). Addition. The address to call is 0D3E, or more intelligibly, CALL ADD. The subroutine adds together the number stored in DE and the number stored in HL. The result is then placed in HL. This may be demonstrated by the following program:

```
113900  ADDDEMO  LD DE,0039
211100      LD HL,0011
CD3E0D      CALL ADD
C9          RET
```

Here DE is loaded with the number fifty-seven, and HL with seventeen. On return to BASIC the result stored in HL should be fifty-seven plus seventeen, so the command PRINT USR(addydemo) should generate the number seventy-four.

2). Subtraction. Just the same - DE is subtracted from HL and the result stored in HL. The address is 0D39. Thus to prove it:

```
113900  SUBDEMO LD DE,0039
211100      LD HL,0011
CD390D      CALL SUB
C9          RET
```

3). Multiplication. Up until now we have ignored multiplication completely, since there is no simple instruction which will multiply two numbers together. However, thanks to Uncle C, the ROM will do it for us. Simply CALL MULT, which is stored at address 0D44, and as if by magic DE will be multiplied by HL, the result as usual being stored in HL. Watch out for what happens to BC and DE though! They're not unaltered.

4). Division. As you'd by now expect, the instruction CALL DIV will divide HL by DE (ignoring any remainder of course, since we are dealing in integers). The address of DIV is 0D90.

5). Powers. Is raising one number to the power of another going to be any more difficult? No of course not. With elegant simplicity the instruction CALL POWER (at 0D0C) will do just that, raising HL to the power of DE, and putting the answer away in HL, using repeated multiplication to compute the answer.

One very important function is the RANDOM NUMBER GENERATOR. This is held at location 0EED. To generate a random number between one and six, (say to simulate the roll of a die,) simply load HL with six and CALL RND. This is of course the same thing as RND(6). The number in the brackets should be placed in HL, and the final answer will end up in HL.

See if you can work out what this program does. What we're interested in is the number that it returns to BASIC.

```
211400  START  LD HL,0014
CEED0B      CALL RND
110A00      LD DE,000A
CD440D      CALL MULT
116400      LD DE,0064
19          AND HL,DE
C9          RET
```

156

Let's see if you got it right. HL is loaded with 14 and RND is called, so HL is replaced by a new value, RND(20). (Note that 14 (hex) is 20 (dec).) 0A is stored in DE, and the two are then multiplied together. We then have 10xRND(20). Finally 64 (hex) is added, giving 10xRND(20)+100.

We could use this routine in a games program. Suppose we needed to jump to a random destination. We could use the by now famous Tim Hartnell method of GOTO 10xRND(20)+100. Alternatively, if the above machine code were in a REM statement, say at address 16427, we could instead simply say GOTO USR(16427). This would do exactly the same job, except just a little bit faster.

We'll leave the OLD ROM now, and turn to the rather more complex field of arithmetic on the NEW ROM.

## NEW ROM ARITHMETIC

The first and most important point to note is that NEW ROM numbers are stored as five bytes, not two, and so they can't fit into a register-pair as they stand. Nor are the numbers in simple form, for while it is true that zero is, as you'd expect, 00 00 00 00 00, it is not true that one is 00 00 00 00 01! In fact one is represented by 81 00 00 00 00. Here is a list of the Sinclair representation of the first few integers.

Decimal	Sinclair Form
0	00 00 00 00 00
1	81 00 00 00 00
2	82 00 00 00 00
3	83 00 00 00 00
4	84 00 00 00 00
5	85 20 00 00 00
6	83 40 00 00 00
7	83 60 00 00 00
8	84 00 00 00 00
9	84 10 00 00 00
10	84 20 00 00 00

... and so on. There is a kind of pattern, but it's not instantly recognisable. Take a look at the negative numbers:

Decimal	Sinclair Form
-1	81 80 00 00 00
-2	82 80 00 00 00
-3	83 00 00 00 00
-4	83 80 00 00 00
-5	83 A0 00 00 00
-6	83 C0 00 00 00
-7	83 E0 00 00 00
-8	84 00 00 00 00
-9	84 90 00 00 00
-10	84 A0 00 00 00

As you can see, you can instantly change a number from positive to negative just by adding 80 to the second byte. This doesn't apply to zero by the way - zero is represented uniquely to help speed the ROM up a little.

Knowing how the Sinclair Form is built up will slightly help your understanding of the ROM, so I will give here a brief explanation of how to turn decimal numbers into Sinclair numbers. It only takes a few simple steps.

157

STEP ONE: If the number is zero, then its Sinclair representation is 00 00 00 00.

STEP TWO: Ignoring the sign of the number, write it in binary (but without any leading zeroes). For example:

7	111
-10	1010
-4.25	100.01
0.325	0.011

Notice that the binary form has a BINARY point, not a DECIMAL point! 100.01 means one 4 plus no 2's plus no 1's (here we reach the binary point) plus no halves plus one quarter. The next column would have been an eighth.

STEP THREE is to work out a quantity called the EXPONENT. This is done as follows: If the part of the number to the left of the binary point is not zero then the exponent is the number of digits to the left of the point. If the part of the number to the left of the point is zero and the first digit after the point is one then the exponent is zero. If the part of the number to the left of the point is zero and the first digit after the point is zero, then count the number of zeroes between the point and the first 1 - the exponent is minus this number. The first byte of the Sinclair representation is 80 plus this exponent.

Decimal	Binary	Exponent	First byte of Sinclair Form
7	111	3	83
-10	1010	4	84
-4.25	100.01	3	83
0.325	0.011	-1	7F

STEP FOUR: Now we can ignore the binary point altogether - that is what the exponent is for - to tell the computer where the point is supposed to go. So ignoring the point, write the binary form starting with the first 1 and then add sufficient zeroes to the right to make the whole thing thirty-two binary digits (bits) in length.

7	1110 0000 0000 0000 0000 0000 0000
-10	1010 0000 0000 0000 0000 0000 0000
-4.25	1000 1000 0000 0000 0000 0000 0000
0.325	1100 0000 0000 0000 0000 0000 0000

STEP FIVE: It is here that we remember the sign of the original number. If the original number was negative then do nothing. If the original number was positive then replace the first one by a zero. Thus:

7	0110 0000 0000 0000 0000 0000 0000
-10	1010 0000 0000 0000 0000 0000 0000
-4.25	1000 1000 0000 0000 0000 0000 0000
0.325	0100 0000 0000 0000 0000 0000 0000

STEP SIX - Now just change these numbers straight into hex, like so, making sure you remember to put the exponent byte at the start:

7	83 60 00 00 00
-10	84 A0 00 00 00
-4.25	83 88 00 00 00
0.325	7F 40 00 00 00

This is the form in which the ROM will be working. The largest exponent you may have is FF, so the largest positive number that can be stored is FF 7F FF FF FF. This turns out to be 1.7014118E38. (If you can't understand the "E" notation the E means "with the decimal point shifted (in the above case) 38 places to the right". In other words the number 170,141,180,000,000,000,000,000,000,000,000,000,000,000,000, which is a pretty vast quantity. It can still only store ten decimal places accurately though. The smallest positive number you can have (apart from zero) is 01 00 00 00 00, which happens to represent 2.9387359E-39. To you and me that's 0.000,000,000,000,000,000,000,000,000,000,000,000,938,735,9 which I'd say was pretty microscopic.

You can check all of this with the following BASIC program.

```

10 LET A=0
20 LET B=PEEK 16400+256*PEEK 16401
30 FOR I=1 TO 5
40 INPUT A$
50 POKE B+I,16*CODE A$+CODE A$(2)-476
60 NEXT I
70 PRINT A

```

The program sets up a variable A, and then overwrites its previous contents by POKEing into the variables area, one byte at a time. (That's a letter I in line 50, not a number 1). If you run it and input "82"/"40"/"00"/"00"/"00" (where / means newline) you'll find the number three printed. And so on.

An interesting little quirk is that if you input "00"/"80"/"00"/"00"/"00" (in theory this is minus-zero) the machine actually prints -C.6E-56 ! The letter C in mid-number, and an exponent of -56! Don't panic! This doesn't really happen in the ROM. We made it happen by POKEing something that doesn't make sense. The ROM does behave slightly more sensibly than human beings.

#### HOW TO USE FLOATING POINT NUMBERS PROPERLY

Having seen that a five byte number is too big to store in the registers the next question is undoubtedly "Well where does it store them then?" Answer - it stores them in an area of RAM called the CALCULATOR STACK, which works very much like the ordinary stack except for two points. 1) It can store both floating point numbers and strings, and 2) it is the right way up, not upside down like the machine stack.

To push a number stored in the BC register onto the calculator stack all you need to do is call up a subroutine in the ROM. CALL STACKBC, as I've called it, will change BC into five byte form as described above and then push this number onto the top of the calculator stack. You can do the same for a number stored in A (ie a number between 0 and 255) by calling STACKA. The addresses to call are: 1519 (STACKA) and 151C (STACKBC)

CALL STACKA	CD1915
CALL STACKBC	CD1C15

Incidentally the first two instructions in the STACKA routine are LD C,A and LD B,00. It then leaps straight into STACKBC!

Conversely, to retrieve a number from the calculator stack we can CALL UNSTACK (address 0EA7), which removes a number from the calculator stack and stores it in the BC register.

Arithmetic is quite straightforward. The addresses are:

ADD	1754	addition
SUB	1743	subtraction
MULT	1705	multiplication
DIV	1681	division

They work like this: The five-byte number stored at an address specified by HL (this means the number is stored in locations (HL), (HL)+1, (HL)+2, (HL)+3, and (HL)+4) is added to, multiplied by, divided by, or has a second number subtracted from it. The second number is stored at an address specified by DE. After the calculation the result is stored in the five bytes beginning at address HL.

To multiply together the two numbers at the top of the calculator stack one method would be as follows:

2A1040	LD HL, (STACKEND)
11F0FF	LD DE, FF0F
19	ADD HL, DE
E5	PUSH HL
221040	LD (STACKEND), HL
19	ADD HL, DE
D1	POP DE
CDC517	CALL MULT

Can you follow exactly what is going on? HL is loaded with the contents of the system variable STACKEND - which gives the address of the first byte after the end of the calculator stack. DE is loaded with minus five, thus HL is decreased by five. This new value is loaded back into STACKEND because we start off with two items on the stack and want to end up with only one. This is the address of one of the numbers to be multiplied. If you follow the listing through carefully you'll see that DE ends up with this value. First though HL is decreased by five again, to find the start of the other number to be multiplied.

To check that it really does work, run this program.

3E06	START	LD A, 06
CD1915		CALL STACKA
3E07		LD A, 07
CD1915		CALL STACKA
2A1040		LD HL, (STACKEND)
11F0FF		LD DE, FF0F
19		ADD HL, DE
E5		PUSH HL
221040		LD (STACKEND), HL
19		ADD HL, DE
D1		POP DE
CDC517		CALL MULT
CD1708		CALL UNSTACK
C9		RET

Run it by typing PRINT USR start. What do you get?

But surely there must be easier ways to multiply six by seven. After all, the above program does look very complicated, and not something you'd easily remember. Well it's here that we really do start making full use of the ROM. The following program does exactly the same job, and I shall shortly explain why:

3E06		LD A, 06
CD1915		CALL STACKA
3E07		LD A, 07
CD1915		CALL STACKA
EF		RST 28
04		DEFB 04
34		DEFB 34
CD1708		CALL UNSTACK
C9		RET

In the NEW ROM, RST 28 means "perform floating point arithmetic." The data that follows tells it precisely what calculations it's supposed to do. The byte 04 means multiply - all of the shuffling around of the calculator stack is done automatically. The byte 34 is used after a PST 28 instruction to indicate that there is no more data to come, and the next machine code instruction should follow.

The RST 28 data codes are ADD: 0F, SUB: 03, MULT: 04, and DIV: 05. Don't forget you'll need a byte 34 as well though, to end the data.

You may be wondering what happens if the number on the top of the calculator stack is not an integer between 0 and 65535 (the maximum value any two byte register can hold). Well my first answer would be "try it for yourself and find out." Write a program that adds 8001 to 8001. Write a program that divides eight by three, then a program that divides seven by three. Write a program that subtracts five from zero, and another that subtracts a thousand from zero. But for those of you who are impatient I'll tell you anyway.

If the number at the top of the calculator stack is greater than 65535 then attempting to "unstack" it into BC will result in the program returning to BASIC - returning to command mode in fact - stopping with error code B (which means out of range).

If the number is a decimal then it will be rounded up or down (not just INTed) to the nearest whole number. If the decimal part is less than 0.5 it will be rounded down, and if the decimal part is greater than or equal to 0.5 it will be rounded up.

If the number is negative then error B will result, causing an immediate return to BASIC and stopping the program, if there is one.

RST 28 allows you to do much, much more than just simple arithmetic. All of the functions of the ZX81 are available to you. The data code for any particular function is just the character code of that function minus AB. For instance, the character code of SIN is C7. C7 minus AB is 1C. (If you don't believe me we'll do it in decimal - 199 minus 171 is 28.) This means we can find the SIN of the number at the top of the calculator stack using the sequence:

EF	RST 28
1C	DEFB 1C (SIN)
34	DEFB 34 (Exit).

To multiply two numbers (at the top of the calculator stack) together and then find the square root of the result we can use the sequence

EF	RST 28
04	DEFB 04 (MULT)
25	DEFB 25 (SQRT)
34	DEFB 34 (EXIT)

If you're not absolutely convinced yet, run this program, which multiplies five by twenty, and then takes the square root.

3E05	LD A, 05
CD1915	CALL STACKA
3E14	LD A, 14
CD1915	CALL STACKA

EF	RST 28
04	DEFB 04 (MULT)
25	DEFB 25 (SQRT)
34	DEFB 34 (EXIT)
CDAT0E	CALL UNSTACK
C9	RET

You'll notice that this is the first time we've used more than one code in the RST 28 data. In fact you can use as many as you like, provided you end the list with 34.

To save you working it out for yourselves here is a list of the available functions that we are ready to use, together with their appropriate RST 28 codes:

FUNCTION	CODE	FUNCTION	CODE
CODE	19	EXP	23
VAL	1A	INT	24
LEN	1B	SCR	25
SIN	1C	SGN	26
COS	1D	ABS	27
TAN	1E	PEEK	28
ASN	1F	USR	29
ACS	20	STR	2A
ATN	21	CHR	2B
LN	22	NOT	2C

Some of the entries in that list may surprise you. For instance we have the use of USR. This is very confusing - being allowed to use USR in the middle of a USR routine - but it's not really. Here's how it works. You've worked your way through a lot of RST 28 data, done a lot of calculation, and now you come across the code 29. What happens next is that the number at the top of the stack should be an integer between 0 and 65535 - or else you'll get an error B. This address is treated as a subroutine and CALLED. This subroutine will run exactly as you'd expect it to. When it's over (ie when a RET instruction is reached) the machine will go back to interpreting the RST 28 data from the next byte. USR will of course leave a new value at the top of the stack - the value held by BC at the end of the subroutine.

PEEK works in the same way, finding an address, PEEKING there, then pushing the result to the calculator stack.

All of the functions when used in this way will remove the number currently at the top of the calculator stack and replace it by a new one. For instance if the number at the top of the stack is 3.5 and the function INT is called, the 3.5 will be removed and replaced by a new value, 3.

The string functions CODE, VAL, and LEN, also CHR and STR need a small amount of explaining. You see, as well as storing numbers, the calculator stack can also store strings, so if you start off with the number 2000 on the top of this stack, and you then call STR (By using code 2A in a RST 28 instruction) then the item at the top of the calculator stack will now be the string "2000". You can demonstrate this with the following:

01D007	LD BC,07D0
CD1C15	CALL STACKRC
EF	RST 28
2A	DEFB 2A (STR)
19	DEFB 19 (CODE)
34	DEFB 34 (EXIT)
CDAT0E	CALL UNSTACK
C9	RET

This should produce the result of CODE STR 2000. Does it?

162

## USING THE CALCULATOR'S MEMORY

If you take a quick glance at the manual you'll see that one of the system variables, MEME07, is thirty bytes long. This is the calculator's memory area. A quick calculation involving dividing by five, if you're up to it, shows that this leaves enough room to store six different five byte numbers. The six different areas of memory may each be used by RST 28 to store, or retrieve, numbers (but numbers only) from the top of the calculator stack. There are twelve different codes to achieve this - these are

C0	stores number in memory location 0
C1	stores number in memory location 1
C2	stores number in memory location 2
C3	stores number in memory location 3
C4	stores number in memory location 4
C5	stores number in memory location 5
E0	recalls number from memory location 0
E1	recalls number from memory location 1
E2	recalls number from memory location 2
E3	recalls number from memory location 3
E4	recalls number from memory location 4
E5	recalls number from memory location 5

Storing a number copies it from the top of the stack, and recalling a number simply places it at the end of the stack - it doesn't overwrite the previous top item.

Let's see how we can use this. Suppose we want to find SIN X + COS X. We must use the following technique. Assume that X is at the top of the stack.

EF	RST 28
C0	DEFB C0 (STORE)
1C	DEFB 1C (SIN)
ED	DEFB ED (RECALL)
1D	DEFB 1D (COS)
0F	DEFB 0F (ADD)
34	DEFB 34 (EXIT)

Note that the SIN routine changes X into SIN X. When we again recall X there are now two items on the stack: SIN X and X. The COS routine changes X into COS X, so that the two items on the stack, are now SIN X, and COS X. The ADD routine will replace both of these by one single number - the answer we want - SIN X plus COS X.

We have now performed a fairly complex trigonometric function in just eight bytes!

Let's see how we can remove a floating point number from the stack without restricting ourselves to integers less than 65536. The way the ROM does it is like this:

2A1C40	LD HL,(STACKEND)
2B	DEC HL
46	LD B,(HL)
2B	DEC HL
4E	LD C,(HL)
2B	DEC HL
56	LD D,(HL)

163

```

26      DEC HL
58      LD N,(HL)
28      DD: HL
78      LD A,(HL)
271C40  LD (STACK),HL

```

As you can probably see for yourself, a five byte number is removed from the stack and stored in the registers A, E, D, C, and B. (In that order.) You can CALL this routine from address 13M4.

If the first item in the variable store is X then having popped SIN X plus CCS X from the stack you can then store the result back in X as follows

```

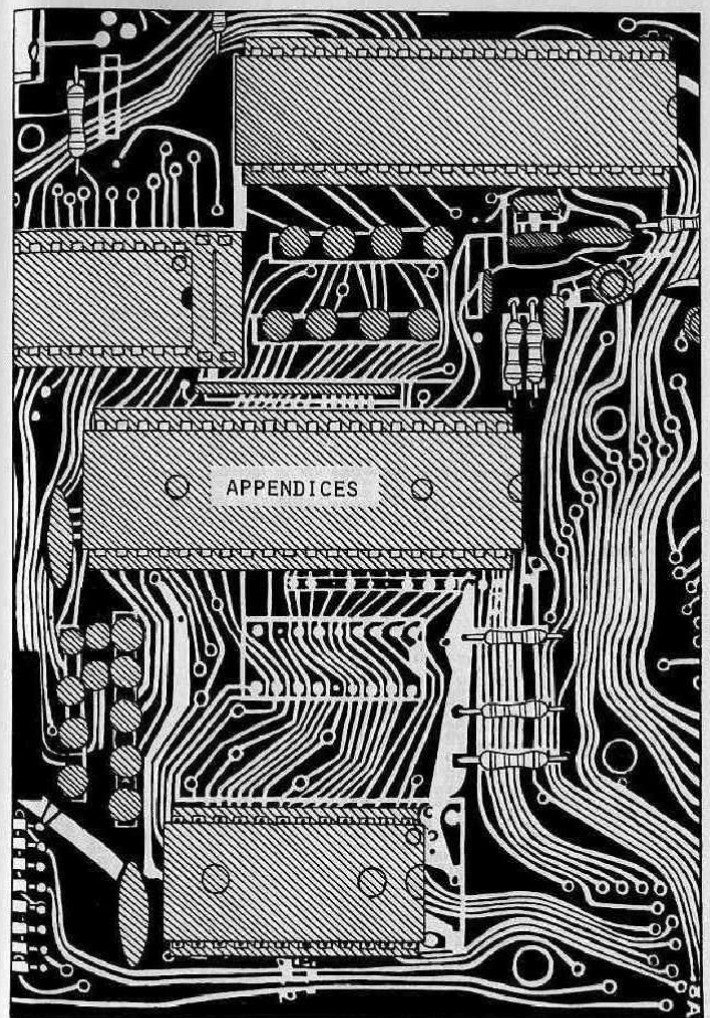
2A1040  LD HL,(VARS)
23      INC HL
77      LD (HL),A
23      INC HL
73      LD (HL),E
23      INC HL
72      LD (HL),D
23      INC HL
71      LD (HL),C
23      INC HL
70      LD (HL),B
C9      RET

```

You can see that it takes more bytes to store the answer than it does to find it in the first place!

Let's see what else we can do with RST 28. We can use the logical functions AND and OR (that in BASIC AND and BASIC OR). Both of these are available from RST 28, having byte codes 06 and 07 respectively. Also you can SWAP the two numbers at the top of the stack. Code 01 will do this.

The following sequence will raise one number to the power of another. Can you see why? After RST 28: 01 22 04 23 34.



166

HEXLD3

```

10 PRINT " LIST "
20 GOSUB 500
30 RUN USR 15539
100 PRINT " WRITE "
110 PRINT " "
120 INPUT A$
130 PRINT A$
140 RAND USR 15589
150 GOTO 120
160 PRINT " INSERT "
200 GOSUB 500
220 INPUT A$
230 PRINT " "
240 RAND USR 15597
250 GOTO 220
300 PRINT " DELETE "
310 GOSUB 500
320 LET A=15535
330 GOSUB 500
340 RUN USR 15732
400 DTH CH USR 15635)
410 RAND USR 1551
420 GRAVE "HEXLD8"
430 RAND USR 15569
500 CLEAR
520 STOP
550 LET A=15535
560 PRINT " ADDRESS " ;
570 INPUT A$
580 PRINT A$
590 POKE A+1,15*CODE A$+CODE A$
(1)-478
590 POKE A,15*CODE A$(3)+CODE A$
(1)-478
600 CLEAR
610 RETURN

```

## APPENDIX TWO

### OLD ROM SYSTEM VARIABLES:

Decimal	Hex	Name
16384	4000	ERR.NR
16385	4001	FLAGS
16386	4002	PPC
16388	4004	E.ADDR
16390	4006	E.PPC
16392	4008	VAR5
16394	400A	E.LINE
16396	400C	D.FILE
16398	400E	DF.EA
16400	4010	DF.END
16402	4012	DF.SZ
16403	4013	S.TOP
16405	4015	X.PTR
16407	4017	OLDPPC
16409	4019	FLAGX
16410	401A	T.ADDR
16412	401C	SEED
16414	401E	FRAMES
16416	4020	V.ADDR
16418	4022	ACC
16420	4024	S.POSN
16422	4026	CH.ADD

### NEW ROM MEMORY ORGANISATION

4000	system variables
4028	program
(D.FILE)	screen
(VAR5)	variables
(E.LINE)	edit line
(STKBOT)	calculator stack
(STKEND)	spare
SP	machine stack
(ERR.SP)	GOSUB stack
(RAMTOP)	reserved area

### OLD ROM MEMORY ORGANISATION

4000	system variables
4028	program
(VAR5)	variables
(E.LINE)	edit line
(D.FILE)	screen
(DF.END)	spare
SP	machine stack

### NEW ROM SYSTEM VARIABLES:

Decimal	Hex	Name
16384	4000	ERR.NR
16385	4001	FLAGS
16386	4002	ERR.SP
16388	4004	RAMTOP
16390	4006	MODE
16392	4007	PPC
16393	4009	VERSN
16394	400A	E.PPC
16396	400C	D.FILE
16398	400E	DF.CC
16400	4010	VAR5
16402	4012	DEST
16404	4014	E.LINE
16406	4016	CH.ADD
16408	4018	X.PTR
16410	401A	STKBOT
16412	401C	STKEND
16414	401E	BREFG
16415	401F	MEM
16417	4021	SPARE1
16418	4022	DF.SZ
16419	4023	S.TOP
16421	4025	LAST.K
16423	4027	DR.ST
16424	4028	MARGIN
16425	4029	NXTLIN
16427	402B	OLDPPC
16429	402D	FLAGX
16430	402E	STRLIN
16432	4030	T.ADDR
16434	4032	SEED
16436	4034	FRAMES
16438	4036	COORDS
16440	4038	PR.CC
16441	4039	S.POSN
16443	403B	CDFLAG
16444	403C	PHEUFF
16477	405D	MEMBOT
16507	407B	SPARE2

SYSTEM VAR.	OLD ROM ADDR	NEW ROM ADDR	NO. OF BYTES	PURPOSE
ACC	4022	-	2	Value of last expression
BREFG	-	401E	1	Used by floating point calculator
CDFLAG	-	403B	1	Flags relating to FAST/SLOW mode
CH.ADD	4026	4016	2	Address of the next character to interpret
COORDS	-	4036	2	Coordinates of last point PLOTTed
D.FILE	400C	400C	2	Address of start of display file
DE.ST	-	4027	1	Debounce status of keyboard
DEST	-	4012	2	Address of variable being assigned
DF.CC	-	400E	2	Address of print position within display file
DF.EA	400E	-	2	Address of start of lower part of screen
DF.END	4010	-	2	Address of end of display file
DF.SZ	4012	4022	2	Number of lines in lower part of screen
E.ADDR	4004	-	2	Address of cursor in edit line
E.LINE	400A	4014	2	Address of start of edit line
E.PPC	4006	400A	2	Line number of line with cursor
ERR.NR	4000	4000	1	Current report code minus one
ERR.SP	-	4002	2	Address of top of GOSUB stack
FLAGS	4001	4001	1	Various flags
FLAGX	4019	402D	1	Various flags
FRAMES	401E	4034	2	Updated once for every TV frame displayed
LAST.K	-	4025	2	Keyboard scan taken after the last TV frame
MARGIN	-	4028	1	Number of blank lines above or below picture
MEM	-	401F	2	Address of start of calculators memory area
MEMBOT	-	405D	1E	Area which may be used for calculator memory
MODE	-	4006	1	Current cursor mode
NXTLIN	-	4029	2	Address of next program line to be executed
OLDPPC	4017	402B	2	Line number to which CONT/CONTINUE jumps
PPC	4002	4007	2	Line number of line being executed
PR.CC	-	4038	1	Address of LPRINT position (High part assumed 40)
PHEUFF	-	403C	21h	Buffer to store LPRINT output
RAMTOP	-	4004	2	Address of reserved area (not wiped out by NEW)
S.POSN	4024	4039	2	Coordinates of print position
S.TOP	4013	4023	2	Line number of line at top of screen
SEED	401C	4032	2	Seed for random number generator
SPARE1	-	4021	1	One spare byte
SPARE2	-	407B	2	Two spare bytes
STKBOT	-	401A	2	Address of calculator stack
STKEND	-	401C	2	Address of end of calculator stack
STRLIN	-	402E	2	Information concerning assigning of strings
T.ADDR	401A	4030	2	Address of next item in syntax table
V.ADDR	4020	-	2	Address of variable name to be assigned
VAR5	4008	4010	2	Address of start of variables area
VERSN	-	4009	1	First system variable to be SAVED
X.PTR	4015	4018	2	Address of character preceeding syntax error marker

## APPENDIX THREE

ORDINARY	0	1	2	3
0	XOP	LD BC,mn	LD {BC},A	INC BC
1	DNZ e	LD DK,mn	LD {DE},A	INC DE
2	JR NZ,e	LD HL,mn	LD {PQ},HL	INC HL
3	JR NC,e	LD SP,mn	LD {PQ},A	INC SP
4	LD B,B	LD B,C	LD B,D	LD B,E
5	LD D,B	LD D,C	LD D,D	LD D,E
6	LD H,B	LD H,C	LD H,D	LD H,E
7	LD {HL},B	LD {HL},C	LD {HL},D	LD {HL},E
8	ADD A,B	ADD A,C	ADD A,D	ADD A,E
9	SUB B	SUB C	SUB D	SUB E
A	AND B	AND C	AND D	AND E
E	OR B	OR C	OR D	OR E
C	RET NZ	POP BC	JP NZ,PQ	JP PQ
D	RET NC	POP DE	JP NC,PQ	OUT {n},A
E	RET PO	POP HL	JP PO,PQ	EX {SP},HL
F	RET P	POP AF	JP P,PQ	DI

	4	5	6	7
0	INC B	DEC B	LD B,n	RLCA
1	INC D	DEC D	LD D,n	RIA
2	INC H	DEC H	LD H,n	DAA
3	INC {HL}	DEC {HL}	LD {HL},n	SCOP
4	LD B,H	LD B,L	LD B,{HL}	LD B,A
5	LD D,H	LD D,L	LD D,{HL}	LD D,A
6	LD H,H	LD H,L	LD H,{HL}	LD H,A
7	LD {HL},H	LD {HL},L	HALT	LD {HL},A
8	ADD A,H	ADD A,L	ADD A,{HL}	ADD A,A
9	SUB H	SUB L	SUB {HL}	SUB A
A	AND H	AND L	AND {HL}	AND A
B	OR H	OR L	OR {HL}	OR A
C	CALL NZ,PQ	PUSH BC	ADD A,n	RST 00
D	CALL NC,PQ	PUSH DE	SUB n	RST 10
E	CALL PO,PQ	PUSH HL	SUB n	RST 20
F	CALL P,PQ	PUSH AF	OR n	RST 30

AFTER CB	0	1	2	3	4	5	6	7
0	RLC B	RLC C	RLC D	RLC E	RLC H	RLC L	RLC {HL}	RLC A
1	RL B	RL C	RL D	RL E	RL H	RL L	RL {HL}	RL A
2	SLA B	SLA C	SLA D	SLA E	SLA H	SLA L	SLA {HL}	SLA A
3	-	-	-	-	-	-	-	-
4	BIT 0,B	BIT 0,C	BIT 0,D	BIT 0,E	BIT 0,H	BIT 0,L	BIT 0,{HL}	BIT 0,A
5	BIT 2,B	BIT 2,C	BIT 2,D	BIT 2,E	BIT 2,H	BIT 2,L	BIT 2,{HL}	BIT 2,A
6	BIT 4,B	BIT 4,C	BIT 4,D	BIT 4,E	BIT 4,H	BIT 4,L	BIT 4,{HL}	BIT 4,A
7	BIT 6,B	BIT 6,C	BIT 6,D	BIT 6,E	BIT 6,H	BIT 6,L	BIT 6,{HL}	BIT 6,A
8	RES 0,B	RES 0,C	RES 0,D	RES 0,E	RES 0,H	RES 0,L	RES 0,{HL}	RES 0,A
9	RES 2,B	RES 2,C	RES 2,D	RES 2,E	RES 2,H	RES 2,L	RES 2,{HL}	RES 2,A
A	RES 4,B	RES 4,C	RES 4,D	RES 4,E	RES 4,H	RES 4,L	RES 4,{HL}	RES 4,A
B	RES 6,B	RES 6,C	RES 6,D	RES 6,E	RES 6,H	RES 6,L	RES 6,{HL}	RES 6,A
C	SET 0,B	SET 0,C	SET 0,D	SET 0,E	SET 0,H	SET 0,L	SET 0,{HL}	SET 0,A
D	SET 2,B	SET 2,C	SET 2,D	SET 2,E	SET 2,H	SET 2,L	SET 2,{HL}	SET 2,A
E	SET 4,B	SET 4,C	SET 4,D	SET 4,E	SET 4,H	SET 4,L	SET 4,{HL}	SET 4,A
F	SET 6,B	SET 6,C	SET 6,D	SET 6,E	SET 6,H	SET 6,L	SET 6,{HL}	SET 6,A

ORDINARY		4	5	6	7	8	9	A	B
0		EX AF,AF'	ADD HL,BC	LD A,(BC)					DAC BC
1		JR E	ADD HL,DE	LD A,(DE)					DEC DE
2		JR Z,c	ADD HL,HL	LD HL,(pq)					DEC HL
3		JR C,e	ADD HL,SP	LD A,(pq)					DEC SP
4		LD C,H	LD C,C	LD C,D					LD C,E
5		LD E,B	LD E,C	LD E,D					LD E,E
6		LD L,B	LD L,C	LD L,D					LD L,E
7		LD A,B	LD A,C	LD A,D					LD A,E
8		ADC A,B	ADC A,C	ADC A,D					ADC A,E
9		SBC A,B	SBC A,C	SBC A,D					SBC A,E
A		XOR B	XOR C	XOR D					XOR E
B		CP B	CP C	CP D					CP E
C		RET Z	RET	JP Z,pq					●
D		RET C	EXX	JP C,pq					IN A,(n)
E		RET PE	JP (HL)	JP PE,pq					EX DE,HL
F		RET M	LD SP,HL	JP M,pq					EI

	C	D	E	F
0	INC C	DEC C	LD C,n	RRCA
1	INC E	DEC E	LD E,n	RRA
2	INC L	DEC L	LD L,n	CEFL
3	INC A	DEC A	LD A,n	CCF
4	LD C,H	LD C,L	LD C,(HL)	LD C,A
5	LD E,B	LD E,L	LD E,(HL)	LD E,A
6	LD L,B	LD L,L	LD L,(HL)	LD L,A
7	LD A,B	LD A,L	LD A,(HL)	LD A,A
8	ADC A,H	ADC A,L	ADC A,(HL)	ADC A,A
9	SBC A,H	SBC A,L	SBC A,(HL)	SBC A,A
A	XOR H	XOR L	XOR (HL)	XOR A
B	CP H	CP L	CP (HL)	CP A
C	CALL Z,pq	CALL pq	ADC A,n	RET 0B
D	CALL G,pq	●	SBC A,n	RST 16
E	CALL PE,pq	●	XOR n	RET 26
F	CALL M,pq	●	CP n	RST 36

AFTER CB		8		9		A		B		C		D		E		F	
0		RRC B	RRC C	RRC D	RRC E	RRC H	RRC L	RRC (HL)	RRC A								
1		RR B	RR C	RR D	RR E	RR H	RR L	RR (HL)	RR A								
2		SRA B	SRA C	SRA D	SRA E	SRA H	SRA L	SRA (HL)	SRA A								
3		SRL B	SRL C	SRL D	SRL E	SRL H	SRL L	SRL (HL)	SRL A								
4		BIT 1,B	BIT 1,C	BIT 1,D	BIT 1,E	BIT 1,H	BIT 1,L	BIT 1,(HL)	BIT 1,A								
5		BIT 3,B	BIT 3,C	BIT 3,D	BIT 3,E	BIT 3,H	BIT 3,L	BIT 3,(HL)	BIT 3,A								
6		BIT 5,B	BIT 5,C	BIT 5,D	BIT 5,E	BIT 5,H	BIT 5,L	BIT 5,(HL)	BIT 5,A								
7		BIT 7,B	BIT 7,C	BIT 7,D	BIT 7,E	BIT 7,H	BIT 7,L	BIT 7,(HL)	BIT 7,A								
8		RIS 1,B	RIS 1,C	RIS 1,D	RIS 1,E	RIS 1,H	RIS 1,L	RIS 1,(HL)	RIS 1,A								
9		RIS 3,B	RIS 3,C	RIS 3,D	RIS 3,E	RIS 3,H	RIS 3,L	RIS 3,(HL)	RIS 3,A								
A		RIS 5,B	RIS 5,C	RIS 5,D	RIS 5,E	RIS 5,H	RIS 5,L	RIS 5,(HL)	RIS 5,A								
B		RIS 7,B	RIS 7,C	RIS 7,D	RIS 7,E	RIS 7,H	RIS 7,L	RIS 7,(HL)	RIS 7,A								
C		SET 1,B	SET 1,C	SET 1,D	SET 1,E	SET 1,H	SET 1,L	SET 1,(HL)	SET 1,A								
D		SET 3,B	SET 3,C	SET 3,D	SET 3,E	SET 3,H	SET 3,L	SET 3,(HL)	SET 3,A								
E		SET 5,B	SET 5,C	SET 5,D	SET 5,E	SET 5,H	SET 5,L	SET 5,(HL)	SET 5,A								
F		SET 7,B	SET 7,C	SET 7,D	SET 7,E	SET 7,H	SET 7,L	SET 7,(HL)	SET 7,A								

## AFTER DD

	0	1	2	3	4	5
0	-	-	-	-	-	-
1	-	-	-	-	-	-
2	-	LD IX,mn	LD (pq),IX	INC IX	-	-
3	-	-	-	-	INC (IX+d)	DEC (IX+d)
4	-	-	-	-	-	-
5	-	-	-	-	-	-
6	-	-	-	-	-	-
7	LD (IX+d),B	LD (IX+d),C	LD (IX+d),D	LD (IX+d),E	LD (IX+d),H	LD (IX+d),L
8	-	-	-	-	-	-
9	-	-	-	-	-	-
A	-	-	-	-	-	-
B	-	-	-	-	-	-
C	-	-	-	-	-	-
D	-	-	-	-	-	-
E	-	POP IX	-	EX (SP),IX	-	PUSH IX
F	-	-	-	-	-	-

## AFTER DD

	6	7	8	9	A	B	C	D	E	F
0	-	-	-	ADD IX,BC	-	-	-	-	-	-
1	-	-	-	ADD IX,DE	-	-	-	-	-	-
2	-	-	-	ADD IX,IX	LD IX,(pq)	DEC IX	-	-	-	-
3	LD (IX+d),n	-	-	ADD IX,SP	-	-	-	-	-	-
4	LD B,(IX+d)	-	-	-	-	-	LD C,(IX+d)	-	-	-
5	LD D,(IX+d)	-	-	-	-	-	LD E,(IX+d)	-	-	-
6	LD H,(IX+d)	-	-	-	-	-	LD L,(IX+d)	-	-	-
7	-	LD (IX+d),A	-	-	-	-	LD A,(IX+d)	-	-	-
8	ADD A,(IX+d)	-	-	-	-	-	ADC A,(IX+d)	-	-	-
9	SUB (IX+d)	-	-	-	-	-	SBC (IX+d)	-	-	-
A	AND (IX+d)	-	-	-	-	-	XOR (IX+d)	-	-	-
B	OR (IX+d)	-	-	-	-	-	CP (IX+d)	-	-	-
C	-	-	-	-	-	-	-	-	-	-
D	-	-	-	-	-	-	-	-	-	-
E	-	-	-	JP (IX)	-	EX DE,IX	-	-	-	-
F	-	-	-	LD SP,IX	-	-	-	-	-	-

## AFTER DD

	8	9	A	B	C	D	E	F
0	-	-	-	-	-	-	-	-
1	-	-	-	-	-	-	-	-
2	-	-	-	-	-	-	-	-
3	-	-	-	-	-	-	-	-
4	IN C,(C)	OUT (C),C	ADC HL,BC	LD BC,(pq)	-	RETI	-	LD R,A
5	IN B,(C)	OUT (C),B	ADC HL,DE	LD DE,(pq)	-	-	IM 2	LD A,R
6	IN L,(C)	OUT (C),L	ADC HL,HL	-	-	-	-	RHD
7	IN A,(C)	OUT (C),A	ADC HL,SP	LD SP,(pq)	-	-	-	-
8	-	-	-	-	-	-	-	-
9	-	-	-	-	-	-	-	-
A	LDD	CPD	IND	OUTD	-	-	-	-
B	LDDR	CPDR	INDR	OTDR	-	-	-	-
C	-	-	-	-	-	-	-	-
D	-	-	-	-	-	-	-	-
E	-	-	-	-	-	-	-	-
F	-	-	-	-	-	-	-	-

## AFTER FD

	0	1	2	3	4	5
0	-	-	-	-	-	-
1	-	-	-	-	-	-
2	-	LD IY,mn	LD (pq),IY	INC IY	-	-
3	-	-	-	-	INC (IY+d)	DEC (IY+d)
4	-	-	-	-	-	-
5	-	-	-	-	-	-
6	-	-	-	-	-	-
7	LD (IY+d),B	LD (IY+d),C	LD (IY+d),D	LD (IY+d),E	LD (IY+d),H	LD (IY+d),L
8	-	-	-	-	-	-
9	-	-	-	-	-	-
A	-	-	-	-	-	-
B	-	-	-	-	-	-
C	-	-	-	-	-	-
D	-	-	-	-	-	-
E	-	POP IY	-	EX (SP),IY	-	PUSH IY

## AFTER FD

	6	7	8	9	A	B	C	D	E	F
0	-	-	-	ADD IY,BC	-	-	-	-	-	-
1	-	-	-	ADD IY,DE	-	-	-	-	-	-
2	-	-	-	ADD IY,IY	LD IY,(pq)	DEC IY	-	-	-	-
3	LD (IY+d),n	-	-	ADD IY,SP	-	-	-	-	-	-
4	LD B,(IY+d)	-	-	-	-	-	-	LD C,(IY+d)	-	-
5	LD D,(IY+d)	-	-	-	-	-	-	LD E,(IY+d)	-	-
6	LD H,(IY+d)	-	-	-	-	-	-	LD L,(IY+d)	-	-
7	-	LD (IY+d),A	-	-	-	-	-	LD A,(IY+d)	-	-
8	ADD A,(IY+d)	-	-	-	-	-	-	ADC A,(IY+d)	-	-
9	SUB (IY+d)	-	-	-	-	-	-	SBC (IY+d)	-	-
A	AND (IY+d)	-	-	-	-	-	-	XOR (IY+d)	-	-
B	OR (IY+d)	-	-	-	-	-	-	CP (IY+d)	-	-
C	-	-	-	-	-	-	-	-	-	-
D	-	-	-	-	-	-	-	-	-	-
E	-	-	-	JP (IY)	-	EX DE,IY	-	-	-	-
F	-	-	-	LD SP,IY	-	-	-	-	-	-

	0	1	2	3	4	5	6	7
0	-	-	-	-	-	-	-	-
1	-	-	-	-	-	-	-	-
2	-	-	-	-	-	-	-	-
3	-	-	-	-	-	-	-	-
4	IN B,(C)	OUT (C),B	SBC HL,BC	LD (pq),BC	NEG	RETW	IN 0	LD I,A
5	IN D,(C)	OUT (C),D	SBC HL,DE	LD (pq),DE	-	-	IN 1	LD A,I
6	IN H,(C)	OUT (C),H	SBC HL,HL	-	-	-	-	RHD
7	-	-	SBC HL,SP	-	-	-	-	-
8	-	-	-	-	-	-	-	-
9	-	-	-	-	-	-	-	-
A	LDI	CPI	INI	OUTI	-	-	-	-
B	LDIR	CPIR	TNIR	OTIR	-	-	-	-
C	-	-	-	-	-	-	-	-
D	-	-	-	-	-	-	-	-
E	-	-	-	-	-	-	-	-
F	-	-	-	-	-	-	-	-

AFTER DDCBdd

AFTER PDCBdd

	6	E	6	E
0	RLC (IX+d)	RRC (IX+d)	RLC (IX+d)	RRC (IX+d)
1	RL (IX+d)	RR (IX+d)	RL (IX+d)	RR (IX+d)
2	SLA (IX+d)	SRA (IX+d)	SLA (IX+d)	SRA (IX+d)
3	-	SRL (IX+d)	-	SRL (IX+d)
4	BIT 0, (IX+d)	BIT 1, (IX+d)	BIT 0, (IX+d)	BIT 1, (IX+d)
5	BIT 2, (IX+d)	BIT 3, (IX+d)	BIT 2, (IX+d)	BIT 3, (IX+d)
6	BIT 4, (IX+d)	BIT 5, (IX+d)	BIT 4, (IX+d)	BIT 5, (IX+d)
7	BIT 6, (IX+d)	BIT 7, (IX+d)	BIT 6, (IX+d)	BIT 7, (IX+d)
8	RES 0, (IX+d)	RES 1, (IX+d)	RES 0, (IX+d)	RES 1, (IX+d)
9	RES 2, (IX+d)	RES 3, (IX+d)	RES 2, (IX+d)	RES 3, (IX+d)
A	RES 4, (IX+d)	RES 5, (IX+d)	RES 4, (IX+d)	RES 5, (IX+d)
B	RES 6, (IX+d)	RES 7, (IX+d)	RES 6, (IX+d)	RES 7, (IX+d)
C	SET 0, (IX+d)	SET 1, (IX+d)	SET 0, (IX+d)	SET 1, (IX+d)
D	SET 2, (IX+d)	SET 3, (IX+d)	SET 2, (IX+d)	SET 3, (IX+d)
E	SET 4, (IX+d)	SET 5, (IX+d)	SET 4, (IX+d)	SET 5, (IX+d)
F	SET 6, (IX+d)	SET 7, (IX+d)	SET 6, (IX+d)	SET 7, (IX+d)

## APPENDIX FOUR

INSTRUCTIONS	FLAGS	INSTRUCTIONS	FLAGS
Opcode	Hexcode	Opcode	Hexcode
ADC A,r	table 1	HALT	76
ADC HL,s	table 2	IM 0	ED46
ADD A,r	table 1	IM 1	ED56
ADD HL,s	table 2	IM 2	ED5E
ADD IX,s	table 2	INC r	table 1
AND r	table 1	INC s	table 2
BIT b,r	table 1	IN A,(n)	DBnn
CALL p <sub>q</sub>	CDqppp	IN r,(C)	table 1
CALL C,p <sub>q</sub>	table 3	IMI	ED42
CCF	3F	IND	ED4A
(the H flag becomes the previous value of the C flag)		(Z becomes 1 if B becomes zero)	
CP r	table 1	IMIR	EDB2
CPI	EDA1	INDR	EDBA
CPD	EDA9	JP p <sub>q</sub>	CDqppp
CPDR	EDB1	JP C,p <sub>q</sub>	table 3
CPDR	EDB9	JP (HL)	ED
(Z becomes 1 if BC becomes zero, F/V becomes 1 if A = (HL-1))		JP (IX)	DD89
CPL	2F	JP (IY)	FD89
DAA	27	JR e	18ee
DEC r	table 1	JR C,e	table 3
DEC s	table 2	LD (BC),A	O2
DI	F3	LD A,(BC)	0A
DWZ e	10ee	LD (DE),A	12
EI	FB	LD A,(DE)	1A
EX AF,AP	08	LD I,A	ED47
EX DE,HL	ED	LD H,A	ED4F
EX (SP),HL	E3	LD A,I	ED57
EX (SP),IX	DD83	LD A,R	ED5F
EX (SP),IY	FD83	(P/V is set to interrupt storage flag)	
EXX	D9	LD SP,HL	F9
		LD SP,IX	DDF9
		LD SP,IY	FDf9

INSTRUCTIONS	FLAGS	INSTRUCTIONS	FLAGS
Opcode	Hexcode	Opcode	Hexcode
LD r,r	table 1	RES b,r	table 1
LD s,nn	table 2	RET	C9
LD A,(p <sub>q</sub> )	3Aqppp	RET c	table 3
LD s,(p <sub>q</sub> )	table 2	RETN	ED45
LD (p <sub>q</sub> ),A	32qppp	RETI	ED4D
LD (p <sub>q</sub> ),s	table 2		
LDI	ED40	RLCA	07
LDD	ED48	RRCA	0F
(P/V becomes 0 if BC becomes 0)		RLA	17
LDIR	ED90	RRA	1F
LDHR	EDB8	RLC r	table 1
NEG	ED44	RRC r	table 1
NOP	00	RL r	table 1
OR r	table 1	RR r	table 1
OUT (n),A	D3nn	RRD	ED67
OUT (C),r	table 1	RLD	ED6F
OUTI	ED43		
OUTD	EDAB	RST 00	C7
(Z becomes 1 if B becomes zero)		RST 08	CF
OFIR	EDB3	RST 10	D7
OFDR	EDBB	RST 18	DF
POP AF	F1	RST 20	E7
(Flags are determined by the byte at the top of the stack)		RST 28	EF
POP a	table 2	RST 30	F7
PUSH AF	F5	RST 38	FF
PUSH s	table 2	SBC A,r	table 1
RES b,r	table 1	SBC HL,s	table 2
REN	C9	SCF	37
RET c	table 3	SET b,r	table 1
RETN	ED45	SLA r	table 1
RETI	ED4D	SRA r	table 1
RLA	17	SRL r	table 1
RL r	table 1	SUB r	table 1
RLCA	07	XOR r	table 1

TABLE ONE												
r	B	C	D	E	F	G	H	I	(HL)	A	(IX+d)	(IY+d)
ADD A,r	B0	B1	B2	B3	B4	B5	B6	B7	DD86dd	DD86dd	DD86dd	DD86dd
ADD A,r	B8	B9	B0A	B0B	B0C	B0D	B0E	B0F	DD86dd	DD86dd	DD86dd	DD86dd
AND r	A0	A1	A2	A3	A4	A5	A6	A7	DDA6dd	DDA6dd	DDA6dd	DDA6dd
BIT 0,r	CB00	CB01	CB02	CB03	CB04	CB05	CB06	CB07	DDCBdd46	DDCBdd46	DDCBdd46	DDCBdd46
BIT 1,r	CB08	CB09	CB0A	CB0B	CB0C	CB0D	CB0E	CB0F	DDCBdd46	DDCBdd46	DDCBdd46	DDCBdd46
BIT 2,r	CB10	CB11	CB12	CB13	CB14	CB15	CB16	CB17	DDCBdd46	DDCBdd46	DDCBdd46	DDCBdd46
BIT 3,r	CB18	CB19	CB1A	CB1B	CB1C	CB1D	CB1E	CB1F	DDCBdd46	DDCBdd46	DDCBdd46	DDCBdd46
BIT 4,r	CB20	CB21	CB22	CB23	CB24	CB25	CB26	CB27	DDCBdd46	DDCBdd46	DDCBdd46	DDCBdd46
BIT 5,r	CB28	CB29	CB2A	CB2B	CB2C	CB2D	CB2E	CB2F	DDCBdd46	DDCBdd46	DDCBdd46	DDCBdd46
BIT 6,r	CB30	CB31	CB32	CB33	CB34	CB35	CB36	CB37	DDCBdd46	DDCBdd46	DDCBdd46	DDCBdd46
BIT 7,r	CB38	CB39	CB3A	CB3B	CB3C	CB3D	CB3E	CB3F	DDCBdd46	DDCBdd46	DDCBdd46	DDCBdd46
CF r	B8	B9	BA	BB	BC	BD	BE	BF	DD86dd	DD86dd	DD86dd	DD86dd
DFC r	05	0D	15	1D	25	2D	35	3D	DD35dd	DD35dd	DD35dd	DD35dd
IN r,(C)	FD40	FD48	FD50	FD58	FD60	FD68	-	ED78	-	-	-	-
INC r	04	0C	14	1C	24	2C	34	3C	DD34dd	DD34dd	DD34dd	DD34dd
LD R,r	40	41	42	43	44	45	46	47	DD46dd	DD46dd	DD46dd	DD46dd
LD C,r	48	49	4A	4B	4C	4D	4E	4F	DD46dd	DD46dd	DD46dd	DD46dd
LD D,r	50	51	52	53	54	55	56	57	DD56dd	DD56dd	DD56dd	DD56dd
LD E,r	58	59	5A	5B	5C	5D	5E	5F	DD56dd	DD56dd	DD56dd	DD56dd
LD F,r	60	61	62	63	64	65	66	67	DD66dd	DD66dd	DD66dd	DD66dd
LD G,r	68	69	6A	6B	6C	6D	6E	6F	DD66dd	DD66dd	DD66dd	DD66dd
LD (HL),r	70	71	72	73	74	75	76	77	DD76dd	DD76dd	DD76dd	DD76dd
LD A,r	78	79	7A	7B	7C	7D	7E	7F	DD76dd	DD76dd	DD76dd	DD76dd
LD (IX+d),r	DD70	DD71	DD72	DD73	DD74	DD75	-	DD77	-	-	DD76	DD76
LD (IY+d),r	DD70	DD71	DD72	DD73	DD74	DD75	-	DD77	-	-	DD76	DD76
OR r	B0	B1	B2	B3	B4	B5	B6	B7	DD86dd	DD86dd	DD86dd	DD86dd
OUT (C),r	ED41	ED49	ED51	ED59	ED61	ED69	-	ED79	-	-	-	-
RL r	CB80	CB81	CB82	CB83	CB84	CB85	CB86	CB87	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86
RES 0,r	CB88	CB89	CB8A	CB8B	CB8C	CB8D	CB8E	CB8F	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86
RES 1,r	CB90	CB91	CB92	CB93	CB94	CB95	CB96	CB97	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86
RES 2,r	CB98	CB99	CB9A	CB9B	CB9C	CB9D	CB9E	CB9F	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86
RES 3,r	CB98	CB99	CB9A	CB9B	CB9C	CB9D	CB9E	CB9F	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86
RES 4,r	CB90	CB91	CB92	CB93	CB94	CB95	CB96	CB97	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86
RES 5,r	CB98	CB99	CB9A	CB9B	CB9C	CB9D	CB9E	CB9F	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86
RES 6,r	CB90	CB91	CB92	CB93	CB94	CB95	CB96	CB97	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86
RES 7,r	CB98	CB99	CB9A	CB9B	CB9C	CB9D	CB9E	CB9F	DDCBdd86	DDCBdd86	DDCBdd86	DDCBdd86

r	B	C	D	E	F	G	H	I	(HL)	A	(IX+d)	(IY+d)	n
RIC r	CB00	CB01	CB02	CB03	CB04	CB05	CB06	CB07	DDCBdd06	DDCBdd06	DDCBdd06	DDCBdd06	-
RRC r	CB08	CB09	CB0A	CB0B	CB0C	CB0D	CB0E	CB0F	DDCBdd06	DDCBdd06	DDCBdd06	DDCBdd06	-
RL r	CB10	CB11	CB12	CB13	CB14	CB15	CB16	CB17	DDCBdd16	DDCBdd16	DDCBdd16	DDCBdd16	-
RR r	CB18	CB19	CB1A	CB1B	CB1C	CB1D	CB1E	CB1F	DDCBdd16	DDCBdd16	DDCBdd16	DDCBdd16	-
SET 0,r	CB00	CB01	CB02	CB03	CB04	CB05	CB06	CB07	DDCBdd06	DDCBdd06	DDCBdd06	DDCBdd06	-
SET 1,r	CB08	CB09	CB0A	CB0B	CB0C	CB0D	CB0E	CB0F	DDCBdd06	DDCBdd06	DDCBdd06	DDCBdd06	-
SET 2,r	CB10	CB11	CB12	CB13	CB14	CB15	CB16	CB17	DDCBdd16	DDCBdd16	DDCBdd16	DDCBdd16	-
SET 3,r	CB18	CB19	CB1A	CB1B	CB1C	CB1D	CB1E	CB1F	DDCBdd16	DDCBdd16	DDCBdd16	DDCBdd16	-
SET 4,r	CB20	CB21	CB22	CB23	CB24	CB25	CB26	CB27	DDCBdd26	DDCBdd26	DDCBdd26	DDCBdd26	-
SET 5,r	CB28	CB29	CB2A	CB2B	CB2C	CB2D	CB2E	CB2F	DDCBdd26	DDCBdd26	DDCBdd26	DDCBdd26	-
SET 6,r	CB30	CB31	CB32	CB33	CB34	CB35	CB36	CB37	DDCBdd36	DDCBdd36	DDCBdd36	DDCBdd36	-
SET 7,r	CB38	CB39	CB3A	CB3B	CB3C	CB3D	CB3E	CB3F	DDCBdd36	DDCBdd36	DDCBdd36	DDCBdd36	-
SUB A,r	90	91	92	93	94	95	96	97	DD96dd	DD96dd	DD96dd	DD96dd	D6nn
SEG A,r	98	99	9A	9B	9C	9D	9E	9F	DD96dd	DD96dd	DD96dd	DD96dd	D6nn
SIA r	CB20	CB21	CB22	CB23	CB24	CB25	CB26	CB27	DDCBdd26	DDCBdd26	DDCBdd26	DDCBdd26	-
SRA r	CB28	CB29	CB2A	CB2B	CB2C	CB2D	CB2E	CB2F	DDCBdd26	DDCBdd26	DDCBdd26	DDCBdd26	-
SRL r	CB38	CB39	CB3A	CB3B	CB3C	CB3D	CB3E	CB3F	DDCBdd36	DDCBdd36	DDCBdd36	DDCBdd36	-
XOR r	A8	A9	AA	AB	AC	AD	AE	AF	DDA8dd	DDA8dd	DDA8dd	DDA8dd	D6nn

TABLE TWO						
s	BC	DE	HL	SP	IX	IY
ADC HL,s	ED4A	ED5A	ED6A	ED7A	-	-
ADD HL,s	09	19	29	39	-	-
ADD IX,s	DD09	DD19	-	DD39	DD29	-
ADD IY,s	FD09	FD19	-	FD39	-	FD29
DEC s	0B	1B	2B	3B	DD2B	FD2B
INC s	03	13	23	33	DD23	FD23
LD s,mm	01nnmm	11nnmm	21nnmm	31nnmm	DD21nnmm	FD21nnmm
LD s,(pq)	ED4Bqpp	ED5Bqpp	2Aqpp	ED7Bqpp	DD2Aqpp	FD2Aqpp
LD (pq),s	ED43qpp	ED53qpp	22qpp	ED73qpp	DD22qpp	FD22qpp
POP s	C1	D1	E1	-	DD61	FD61
PUSH s	C5	D5	E5	-	DD65	FD65
SBC HL,s	ED42	ED52	ED62	ED72	-	-

TABLE THREE							
c	NZ	Z	NC	C	PO	PE	P
CALL c,pq	C4qpp	C4qpp	D4qpp	D4qpp	E4qpp	E4qpp	F4qpp
JP c,pq	C2qpp	C4qpp	D2qpp	D4qpp	E2qpp	E4qpp	F2qpp
JR c,e	20ee	28ee	30ee	38ee	-	-	-
RET c	C0	C8	D0	D8	E0	E8	F0

# APPENDIX FIVE

	0	1	2	3	4	5	6	7
0	space	"	!	~	#	@	^	~
1	{	}	-	+	*	/	=	>
2	4	5	6	7	8	9	A	B
3	K	L	M	N	O	P	Q	R
4	? RND	? PI	? INKEY	? ?	? ?	? ?	? ?	? ?
5	? ?	? ?	? ?	? ?	? ?	? ?	? ?	? ?
6	? ?	? ?	? ?	? ?	? ?	? ?	? ?	? ?
7	up up	down down	left left	right right	HOME GRAPHCS	EDIT EDIT	NEWLINE NEWLINE	RUBOUT RUBOUT
8	█	█	█	█	█	█	█	█
9	█	█	█	█	█	█	█	█
A	█	█	█	█	█	█	█	█
B	█	█	█	█	█	█	█	█
C	? ""	? AT	? TAB	? ?	? CODE	? VAL	? LEN	? SIN
D	? SQR	? SGN	? ABS	? PEEK	? USR	? THEN STR\$	? PO CHR\$	? NOT
E	AND STEP	OR LPRINT	** LLIST	= STOP	< SLOW	> FAST	LIST NEW	RETURN SCROLL
F	? LIST	? LET	? PAUSE	? NEXT	? POKE	? PRINT	? PLOT	? RUN

First row - OLD ROM characters  
Second row - NEW ROM characters

	8	9	A	B	C	D	E	F
0	█	█	█	█	█	█	█	█
1	█	█	█	█	█	█	█	█
2	C	D	E	F	G	H	I	J
3	S	T	U	V	W	X	Y	Z
4	?	?	?	?	?	?	?	?
5	?	?	?	?	?	?	?	?
6	?	?	?	?	?	?	?	?
7	? K/L	? FUNCTION	? ?	? ?	? ?	? ?	number	cursor
8	█	█	█	█	█	█	█	█
9	█	█	█	█	█	█	█	█
A	█	█	█	█	█	█	█	█
B	█	█	█	█	█	█	█	█
C	? COS	? TAN	? ASN	? ACS	? ATN	? LN	? EXP	? INT
D	? **	? OR	? AND	? NOT =<	? >=	? +<>	? * THEN	? TO
E	CLS CONT	DIM DIM	SAVE REM	FOR FOR	GO TO GOTO	POKE GOSUB	INPUT INPUT	RANDOMISE LOAD
F	STOP SAVE	CONTINUE RAND	IF IF	GO SUB CLS	LOAD UNPLOT	CLEAR CLEAR	REM RETURN	? COPY

(NEW ROM users only!)

This program looks particularly effective when run in the SLOW mode. I'm not telling you what it does - feed it in and find out....

BASIC: 1 REM one hundred and sixty one characters  
2 RAND USR 16514

MACHINE CODE: (To be written to address 4082 - decimal 16514):

21B940	LD HL,40B9	01FF0001	DEFB 01 FF 00 01
7E	LD A,(HL)	0100FFFF	DEFB 01 00 FF FF
23	INC HL	FE050C4E	DEFB FE 05 0C 4E
1F	RRA	7C54004E	DEFB 7C 54 00 4E
F5	PUSH AF	7C55B4AE	DEFB 7C 55 B4 AE
D7	RST 10	B2B2B1B1	DEFB B2 B2 B1 B1
F1	POP AF	B1B1B1B1	DEFB B1 B1 B1 B1
30FB	JR NC,FB	B1B1B0B4	DEFB B1 B1 B0 B4
0680	LD B,60	B5B5B3B3	DEFB B5 B5 B3 B3
3D	DEC A	B3B3B5B3	DEFB B3 B3 B5 B3
20FD	JR NZ,FD	B3B5B3B3	DEFB B3 B5 B3 B3
10FB	DJNZ FB	B5B3B3B3	DEFB B5 B3 B3 B3
01240A	LD BC,0A24	B3B0B0B0	DEFB B3 B0 B0 B0
C5	PUSH BC	B0B1B1B1	DEFB B0 B1 B1 B1
B5	PUSH HL	B0B1B0B1	DEFB B0 B1 B0 B1
CDB60B	CALL DBB6	B1AEB3B3	DEFB B1 AE B3 B3
C1	POP BC	B5AFB0B0	DEFB B5 AF B0 B0
0A	LD A,(BC)	B1AEB1B0	DEFB B1 AE B1 B0
6F	LD L,A	B1B3B3B3	DEFB B1 B3 B3 B3
2640	LD H,40	B3B0B0B1	DEFB B3 B0 B0 B1
5E	LD E,(HL)	B1B3B3B3	DEFB B1 B3 B3 B3
2C	INC L	B1B1B0B0	DEFB B1 B1 B0 B0
56	LD D,(HL)	AEB2B1B2	DEFB AE B2 B1 B2
E1	POP HL	B1B2B1B2	DEFB B1 B2 B1 B2
C8	RET Z	B2B2B4B5	DEFB B2 B2 B4 B5
19	ADD HL,DE	B5B5B4B5	DEFB B5 B5 B4 B5
C5	PUSH BC	B5B4B5B5	DEFB B5 B4 B5 B5
4D	LD C,L	B4B5B5B4	DEFB B4 B5 B5 B4
44	LD E,H	B5B5AEB7	DEFB B5 B5 AE B7
E1	POP HL	FF	DEFB FF
23	INC HL		
1829	JR B9		

# MASTERING MACHINE CODE ON YOUR **ZX 81** TONI BAKER

The ZX-81 computer from Sinclair Research, Ltd., is an exciting new breakthrough in personal computing. About the size of this book, it uses your television set to display programs and any cassette recorder to save programs. Though it can be used for games, for home recordkeeping, and for business functions, it is not "for" any of these uses. Because it is the least expensive, most complete, and most powerful computer of its size on the market, it is an ideal "first computer" to introduce adults and children to the world of computing.

This comprehensive, yet easy-to-understand handbook leads the programmer gently from the BASIC language into ZX-81 machine code, permitting much faster execution of programs and more efficient use of memory. Discover the internal secrets of the ZX-81 machine, and extend your programming capabilities!

**Other books from Reston on the ZX-81:**

**The ZX-81 Pocket Book** by Trevor Toms

**49 Explosive Games for The ZX-81** by Tim Hartnell

**Making the Most of Your ZX-81** by Tim Hartnell

Information about ZX-81 may be obtained from the National ZX Users Group, 599 Adamsdale Rd., N. Attleboro, Mass. 02760.

**RESTON PUBLISHING COMPANY, INC.**  
A Prentice-Hall Company  
Reston, Virginia

0-8359-4261-9